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EVALUATION OF SDRC DAMPING ANALYSIS.(U)
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EVALUATION OF SDRC DAMPING ANALYSIS

M. D. Noll U. S. COAST GUARD

with Damping Analysis
by
Structural Dynamics Research Corporation



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FINAL REPORT

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EVALUATION OF SURC DAMPING ANALYSIS

LT M. D. NOLL

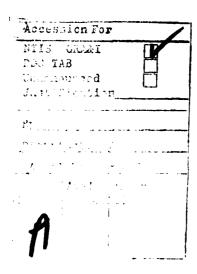
U. S. COAST GUARD RESEARCH AND DEVELOPMENT

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Introduction

During the past two decades, vessel designs have made significant advances which include increased speeds, reduced hydrodynamic resistance, increased pay loads, and increased longitudinal strength. Great Lake ore carriers have also made significant advances but with a special restriction not felt by ocean-going vessels. The Great Lake ore carrier has a maximum beam (B) and hull depth (D) restriction due to physical limitations of the locks at Sault Ste. Marie, Michigan. However, these Great Lake vessels have increased in length to 1000 feet with an appropriate lengthening of the locks by the U.S. Army Corps of Engineers.

Of interest to the U.S. Coast Guard, the American Bureau of Shipping (ABS) and the shipping industry is the longitudinal strength required of these long, shallow ore ships exceeding 750' in length. As shown in Table 1, the L/D ratio has increased from 18.7 to 22.23 giving rise to more flexible ships. These vessels experience a phenomenon known as "springing", a 2-node vertical oscillation of the hull structure, caused by the wave encounter frequency matching and being in phase with the natural frequency of the hull girder. The addition of springing to the still water and wave induced bending moments may cause large cross-sectional dynamic stress fluctuations. These increased stresses and associated longitudinal bending moments must be accounted for in the search for a safe and effective longitudinal strength standard.

One illusive parameter in the study of springing has been the damping factor (ζ). System damping is a combination of the hydrodynamic damping, structural damping, cargo damping and the out-of-phase seaway damping. In order to determine the damping factor for Great Lake ore carriers in general, stress recordings from strain gauges mounted on three ore carriers have been analyzed in the effort to determine the damping factor. The three vessels used were the M/V STEWART J. CORT, M/V ROCER BLOUCH, and S/S EDWARD L. RYERSON. Table 1 lists the comparative characteristics for these vessels. The stress records from these vessels have been recorded and analyzed with the results available in References 1.2. and 3.

TABLE 1 - Vessel Characteristics

	CORT	BLOUCH	RYERSON
LOA (ft) B (ft) L/B D (ft) L/D B/D G.T. (tons) N.T. (tons) H.P.	998.0	833	730
	105.164	105	75
	9.49	7.9	9.73
	44.9	39.2	39.0
	22.23	21.3	18.7
	2.34	2.68	1.92
	32930	22041	12170
	29918	14114	7637
	14000	14000	9000
Yr. Built	1971	1971	1960
Owner	Beth. Steel	U.S. Steel	Inland Steel

Background

In June 1977, Teledyne Engineering Services (formerly Teledyne Materials Research) of Waltham, Massachusetts was contracted by the U. S. Coast Guard to transfer specified intervals of analog tape stress records from these three vessels onto FM magnetic tape. These intervals were chosen to represent high, medium and low springing stresses experienced by the vessels during both the loaded and ballasted condition. The intervals were chosen by the Coast Guard from the computer tables listed in Reference 1,2, and 3. Tables 2-4 (Columns 1, 2, 3 and 14) provide the listing of the intervals and maximum peak-to-through (P-T) stresses which Teledyne was contracted to copy over onto magnetic tape. Tape Number and interval number correspond to computer tables in these references. (For example: Table 2, Tape No. "18", Interval No. "20" corresponds to same Tape Number and Interval Number in Reference 1, Appendix B, page 48).

Upon receipt of the FM magnetic tapes and the quick-looks from Teledyne, Structural Dynamics Research Corporation (SDRC) of Cincinnati, Ohio was contracted to determine the range of damping values for these specific intervals. SDRC took possession of the tapes and the quick-looks for their damping analysis.

SDRC Determination

For each specific interval, SDRC supplied a table of estimated roots and an associated damping power spectra. The tables of modal parameters and the data plots are connected by a FREGRESP-BODE number located at the top of the table and at the bottom of the plot (i.e. for pages A-1 and A-2, this number is IX + 2Y+). The BODE number before the Y refers to the "ID" column in the table of calculated damping values on pages A-3 and A-4. This allows the correct correlation with appropriate table and plot. Appendix F provides a complete listing of all damping power spectras submitted by SDRC.

Figure 6 (a,b,c) shows a plot of amplitude versus frequency for the CORT, BLOUCH, and RYERSON respectively, which illustrates how the max amplitude under this procedure can be used to choose the appropriate damping factor. Notice that when all data is plotted as amplitude versus frequency, two peaks appear. This may be misleading since the peak of interest occurs at the known natural frequency for each vessel.

As mentioned before, the damping values calculated by SDRC represents the total system damping which includes hydrodynamic, structural and cargo damping. The representative system damping factor and frequency for the specific interval was chosen by picking the damping factor and frequency that corresponded to the max amplitude of the associated power spectrum. For example: the damping factor of 0.01247 chosen from page A-1 corresponds to a frequency of .3455 Hz. which corresponds to the max amplitude of 0.4804E-03 shown in the table of estimated roots (pg. A-3) and plotted on page A-2 (As mentioned in the cover letter from SDRC (Appendix B), the amplitude is in error by a constant factor).

In order to portray the complete picture at a glance, Tables 2, 3 and 4 were expanded to include other pertinent data such as ship course and speed, wind direction and speed, wave direction and height, max P-T stress, and etc. This data, extracted from References 1,2, and 3, is listed in Table 2, 3, and 4 to correspond to the CORT, BLOUCH, and RYERSON, respectively. Parentheses used in the Tables indicate that the data was extracted from the last recorded entry in that column from the original tables in References 1, 2, and 3.

Table #2 M/V STEWART J. CORT

							:						1	Stresses (PSI)	es (PSI)				
	Tape.	Tape Int.	Trip Date	Ship Course	Speed (MPH.)	Prop.	Sea State	Wind Direc-	Wind	Wave Direc-	Mave Ht.	Per. (sec)	Wave	Max P-T	RMS	Max	v	¥ 2.	Comments
Column	1	2	3	4	2	9	7	80	-k 70 TS	10	£11	12	(ft) 13	14	15	16	17	18	19
High Springing -Load	ន្តមន	888	12-13-73 11-06-72 10-23-72	009 _ 187	1 24	084.1	ווגר	002-R 067-R	29-R 16-R	- 038 5	סטוו	10	- 24	14666 12236	4560 - 4316	17657 	.0180 .0125 .0246	88.4	
High Springing -Ballast	SI 51	02 02E 24	11-08-73 11-08-73 11-20-74	192 192 302	14 14 14.4	102	અવ્યવ	000-R 000-R 005-T	50-R 50-R 34-T	000 000 070 S	55 8 8	2 -	48 48 -	20306 16464 20036	4607 5319 7299	10037	.0125 .0181 .0146	8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8	ппп
Medium Springing -Load	883	828	11-23-74 11-23-74 11-17-74	- 196 205	_ 14.4 14.1	1 1 1	144	- 196-T 210-T	- 22-T 30-T	010 S 000	1 40 40			9150 10167 9554	3558 4266 5197	, , ,	.00804	.28	III
Medium Springing -Ballast	15 17	030 27	11-08-73 11-08-73 12-04-73	- 566	15.2	101	1.100	_ _ 090-R	_ 12-R	- 135 S	114	2	- 15	10896 9197 9817	4072 3647 3727	6122 3462 4862	.0167	.35	>
Low Springing -Load	17 6 8	22.23	12-05-73 7-11-74 8-11-74	120 177 114	13 14.8 13.3	100	949	055-R 090-T 130-T	46-R 20-T 28-T	055 P 030 P 015 S	0 ω 4	וומא	35	3985 3935 4335	1771 1583 1730	2684	.0137 .0173 .00719	.32 .28 .28	VI VII VIII
Low Springing -Ballast	9 10 19	10 7 22	8-21-74 8-27-74 11-21-74	292	14.6 14.2	1 1 1	n ا 4	218-T 090-T	14-T 26-T	060 P	2.7	1 1 1	1 1 1	5179 4382 4595	2094 2244 1786	1 1 1	.0122 .0203 .0151	.30	× ×
																1		1	

s: I - 29 mi. S. of Caribou Island
III - Manitou Island; 16 mi; 093
III - N. Manitou Island; 24 mi; 093
IV - Pt. Betsie; 22 mi; 290
V - 16 mi. E. of Taconite
VI - 8 mi. SE of Pic. Island, Lake Superior
VII - Burns Harbor; 32 mi.; 180
VIII - Crisp Pt.; 10 mi.; 171
IX - Crisp Pt.; 9 mi.; 220
X - Eagle Harbor; 25 mi.; 310 Comments:

Table #3 M/V ROGER BLOUGH

													+	Stresses	S (PSI)-				
	Tape ♣	Int.	Trip Date	Sh ip Course	Speed (MPH)	Prop.	Sea State	Wind Direc-	Wind	Wave Direc-	Mave Ht.	Per. (sec)	Mave Length	Max P-T	RMS	M A	, n	¥Ž.	Comments
Column	-	2	3	4	2	9	7	8	-knots	10			(f)	14	15	16	17	18	19
High Springing -Load	ដដ	50 51	9-30-74 9-30-74	(078)	(15.8)		1 1	(350-T)	24-T	9 080 -	(1 1	9074 10830	3722 3704	5369 5879	.0171	.383	
High Springing -Ballast	13R 13R 088	% 2 %	8-31-74 10-17-74 8-31-74	(291) (330) 291	(15) (15) 15			(280-T) (340-T) 280-T	(38-1) (40-1) 38-1	(011 P) (010 P) 011 P	e@@		. , ,	20026 16274 14226	5651 6372 4948	8537 7831 7344	.0174 .0232 .033	.39	1111
	\downarrow																		
Medium Springing -Load	ដដ	52 53 47	9-30-74 9-30-74 9-30-74	(078) (078) (078)	(15.8) (15.8) (15.8)	, , ,		(350-T) (350-T) (350-T)	(24-T) ((24-T) ((24-T) ((090 P) (090 P) (090 P)	<u>4</u> .4.4		1 1 1	7581 5961 7090	3422 2002 3067	4796 3531 3640	.0303 .0248 .0128	.382	
Medium Springing -Ballast	ឯដង	288	9-29-74 9-29-74 9-29-74	(291) (291) (291)	(15) (15) (15)			(360-T) (360-T) (360-T)	(32-1) ((32-1) ((32-1) ((075 S) (075 S) (075 S)	(5) (5) (5)		1 1 1	10721 10603 10111	4568 3558 4223	6580 6352 6252	.0143 .0227 .0120	14.	>>>
	1																		
Low Springing -Load	ដដ	84 £ £	9-30-74 9-30-74 9-30-74	(078) (070) (078)	(15.8) (15.8) (15.8)		111	(350-T) (316-T) (350-T)	(24-T) ((18-T) ((24-T) ((090 P) (090 P) (090 P)	(43.4		111	4459 4186 3777	1738 1665 1565	1893 2093 2229	.0202	.383	- 2-
Low Springing -Ballast	08R 08R 13R	28 38 57	8-30-74 8-21-74 10-17-74	013 291 (291)	17 15 (15.8)	1 1 1	111	013-T 299-T (010-T)	18-T 20-T (25-T) (010 P (080 S)	9 (8)	111	1 1 1	4273 4042 4111	1544 1581 1823	1480 3017	.0117	- 43	VIII VIII
																		_	

Comments:

1 - (Eagle Harbor; 55 mi.; 270)
11 - (Whitefish Point; 8 mi.; 215)
111 - (Whitefish Point; 8 mi.; 315)
11 - (Whitefish Point; 8 mi.; 315)
12 - (Whitefish Point; 10 mi.; 310)
13 - (Whitefish Point; 10 mi.; 310)
14 - (Two Harbors; 15 mi.; 070)
15 - (Manitou Island; 35 mi.; 112; BP#3)
17 - (Manitou Island; 12 mi.; 090; BP#5)

Table #4 S/S EDWARD L. RYERSON

													1	Stresses (PSI)-	:s (PSI).				
	Tape *	Int.	Trip Date	Sh ip Course	Speed (MPH)	Prop.	Sea State	Wind Direc-	Wind	Wave Direc-	Mave Ht.	Per. (sec)	Mave Length	Max P-T	RMS	Max	r,	≥ 1	Comments
Column		2	3	4	2	9	7	8	- 1	10			(ft) 13	14	15	16	17	18	19
High Springing -Load	5-1	1,1	11-22-67 11-16-67		17	105 102	6	058-R 054-R	30-R 28-R	058 054	nω	1 1	300			11800 9110	.00483	.57	111
High Springing -Ballast	5-1 1-5-1 1-5-1	12/26 13/27 15/28 16/24	11-26-67 11-26-67 11-26-67 11-27-67	1111	12 12.2 11 12	75 75 75 75	~ ~ ~ ~	030-R 030-R 014-R 005-R	30-R 34-R 30-R	030 030 025 005	10 12 12 8		200 200 200 200 200	1111	1 1 1 1	13420 12621 13960 11800	.00433 .00514 .00578	75: 75: 75:	III VI VI
	\downarrow															T		T	
Medium Springing -Load	5-2	19/1 24/6 39/40	11-27-67 11-28-67 11-04-67	4 1 1	17.1	106 105 105	5 7 2	133-R 032-R 003-R	26-R 35-R 20-R	133 032 003	404	111	75 55 25	111		7550 7730 7090	.00539 .00745 .00395	8.8.7.	VIII
Medium Springing -Ballast	4-4-4-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1	10/18 11/19 15/30 17/32	11-12-67 11-12-67 11-13-67 11-14-67		16.7 15 17.2	98 106 106	സവസയ	037-R 047-R 015-R 014-R	26-R 28-R 28-R 25-R	015 047 015 014	9004		100 75 40 50	1111		6000 5900 6540 7940	.00405 .00362 .00387	8.8.2.2	XIX XIII XIII
		}																T	
Low Springing -Load	6-1 6-1	8/15 1 9/16 1 10/17 1	12-09-67 12-09-67 12-09-67		17.1 17.1 17.1	105 105 105	4 የ የ	097-R 097-R 090-R	20-R 20-R 20-R	097 097 080	422		885		111	4470 4390 4300	.00625	55. 44.	XIX XX IXX
Low Springing -Ballast	1-1	21/35 24/40	9-24-67 9-25-67		17.1	106 106	44	033-R 075-R	20-R 24-R	033 075	N4	1 .	505			4170	.00359	88.85	XVII
													1			1		7	

Comments:

I - Superior Shoals; 6 mi.
II - S. of Passage Island; 8 mi.
III - SE of Caribou Island; 21 mi.
IV - WSW of Caribou Island; 15 mi.
V - NWE of Manitou Island; 54 mi.
VI - SE of Passage Island; 9 mi.
VII - SE of Passage Island; 9 mi.
VIII - Straits of Mackinac
IX - N of Gull Island; 7.5 mi.

X - NE of Waukegan; 15 mi.
XI - NE of Milwaulkee; 15 mi.
XII - SE of Whitefish Point; 5 mi.
XIII - ENE of Manitou Island; 36 mi.
XIV - E of Port Washington; 30 mi.
XV - SE of Wind Point; 24 mi.
XVI - NE of Glencoe, Illinois; II mi.
XVII - NE of Gull Island; 7 mi.
XVIII - SE of Caribou Island; 20 mi.

Method of Analysis

The system of analysis utilized by SDRC is known as MODAMS (MODal Analysis and Modeling System). The technique used to determine the desired modal parameter estimations was the multi-degree-of-freedom (MDOF) curve fit to the frequency response data over a specific frequency range. (see Appendix E for a brief description of a single d.o.f. system used by ABS)

The algorithm used by SDRC is explained in Appendix B of this report. This description gives the theoretical background for the curvefit algorithm used to extract modal parameters from the response spectra. This algorithm will work on spectra with no phase information but results in an analytical function of frequency whose calculated phase angle is essentially meaningless. Even though mode shape coefficients would also be meaningless, the mode shape evident in each graph is damping dependent and therefore allows the determination of the damping factor despite the lack of the phase information.

The basic concept behind the extraction of the damping values centers on the assumption that the operating data consists of a system's response to a fairly random forcing function (fairly flat frequency of input). The measured response can be strain, displacement, velocity, or acceleration. The first two are used directly and the latter two are converted to displacement data first. Since strain relates to displacement directly, the MDOF technique calculates A_{Ik}^c (page 7, Appendix B) from a displacement/force function. Since SDRC assumed the force applied was a constant function of frequency, using F(w) = 1.0 lbf for division in X/F did not affect the overall shape of the response curves.

Using this method allowed SDRC to establish the tables and associated graphs for each interval specified by the U. S. Coast Guard. The damping factor and frequency range chosen for each interval corresponds to the max amplitude for the frequency range investigated, specifically 0.01 to 1.0 Hz.

Analysis of SDRC Results

The range of values supplied by SDRC still raises the question of the accuracy of their results. Determining the accuracy may be difficult but determining whether or not they are in the "ballpark" would be highly beneficial.

The damping value (ζ) calculated by SDRC is the fraction of critical damping where: $r = \underline{c}$

and: c = damping coefficient, tons-sec/in

cc = critical damping coefficient, lb-sec/in

= 2mw_n = 2√mk

 $w_n = \text{natural frequency} = \sqrt{k/m}$

k = stiffness factor, tons/in

m = mass, tons-sec²/in

Then ζ represents a certain ratio of c to c_c to arrive at the damping coefficient c where $c_c * \zeta = c$.

In order to determine a "feel" for the approximate magnitude of the damping values for the three vessels, a mechanical method was used to determine the different springing parameters. This method utilizes the filtered records from existing stress records. It allows the determination of the approximate damping values from mechanical measurements taken directly from stress records.

Suppose that a free transient has the following form:

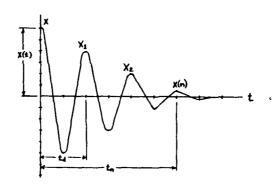


Figure 1 - Example of a Free Transient

Where:

X(t) = Amplitude at time t, psi

 X_0 = Initial amplitude, psi, at t=0

 X_1 = Amplitude after initial oscillation, psi

 $X_n = Amplitude$ after n oscillations

n = Number of oscillations

 t_n = Time for n oscillations to occur, sec

t_d = Damped period, sec w_d = Damped Frequency

w_n = Natural Frequency

The free transient response for this system shown in Figure 1 is:

$$X_0(t) = X_0 * e^{-\zeta \omega_n t} *(\sin(\sqrt{1-\zeta^2} \omega_n t + \phi))$$

With the initial conditions being:

$$X(0) = X_0$$

$$\dot{X}(0) = 0$$

These initial conditions are used in the mechanical analysis because the actual forces causing a peak condition is of no concern to this analysis. The area of interest is the decay period of the record. Once the peak springing stress is reached on a specific interval, the analysis is measuring the rate of decay as the oscillations decrease in amplitude.

From the springing record, X_0 , X_n , and n may be measured. From these values the damping can be determined as follows:

$$\frac{x_0}{x_n} = \frac{x_0(0)}{x_n(t_n)} = \frac{x_0(0)}{x_0(n * t_d)} = \frac{\zeta}{\sqrt{1-\zeta^2}} * 2\pi n$$

and rearranging:

$$\frac{\zeta}{\sqrt{1-\zeta^2}} = \frac{1}{2\pi n} + \ln \frac{X_0}{X_n}$$

When $\zeta \ll 1.0$, then $\sqrt{1-\zeta^2} = 1.0$. Therefore:

$$\zeta = \frac{1}{2 \pi n} + \ln \frac{X_0}{X_n} \tag{1}$$

Equation 1 is the formula used to calculate the damping values found in Table 5. Appendix C contains the stress records from which the appropriate measurements were made in order to calculate damping via the mechanical method. From the same records the damped frequency ($w_{\rm d}$), the natural frequency ($w_{\rm m}$), the damped period ($t_{\rm d}$), and the logarithmic decrement (δ) may be calculated via the following formulas:

$$w_d = \frac{n}{t_n}$$
 Hz. = $\frac{2 \pi n}{t_n}$ radians sec. (2)

$$w_n = \frac{1}{\sqrt{1-\zeta^2}} * w_d Hz.$$
 (3)

Note: as per conditions for Equation 1, wd wm

$$t_{d} = \frac{t_{n}}{n} \quad \text{sec.} \tag{4}$$

The term $\ln X_0/X_n$ from Equation 1 is often referred to as the logarithmic decrement and is defined as the natural logarithm of any two successive amplitudes. Since Table 5 lists the peaks amplitudes, X_0 , and the amplitude after n oscillations, X_n , the equation for the logarithmic decrement is modified to be:

$$\delta = \frac{1}{n} \quad \text{in} \quad \frac{X_0}{X_n} \tag{5}$$

These parameters are calculated from the measurements taken from Appendix C and the results are incorporated into Table 5. The areas of measurement are enclosed by double rectangles and are numbered to correspond to the numerical order in Table 5.

Logarithmic decrement may also be determined if the damping value is already known. The equation for & can be written in the simplified form:

$$\delta = \frac{2\pi\zeta}{\sqrt{1-\zeta^2}} = 2\pi\zeta \tag{6}$$

Equation 6 is an alternate method for determining 6 when ζ is known and the stress records are not available for mechanical measurements as performed for Table 5.

Comparison of Results

In order to provide a means of comparison between the SDRC results and the mechanical results, a program was written in BASIC to calculate the δ , t_d , the bending moment (BM) from the data presented in Tables 2,3, and 4. A flow chart, the program data and the results are shown in Appendix D.

Table 5 - Damping Parameters Calculated from Mechanical Measurements

						1	2	3	4	5	
		X ₀ psi	X _n ps i	n cy	t _n (sec)	ζ	w _d Hz.	w _n Hz.	t _d sec/cy	δ	Ref. *
CORT	1	6206	2500	7	20.2	.0207	. 35	. 35	2.89	.129	C1:R9:14
	2	2327	517	5	13.4	.048	.37	. 37	2.68	. 30	C1 "
	3	4913	2586	6	17	.017	. 35	. 35	2.83	. 107	C2 "
	4	6465	1552	5	14.6	.0434	.34	.34	2.9	. 285	C2 "
	5	7758	1034	8	24	.040	. 33	. 33	3.0	. 25 1	С3 "
	6	7500	3879	4	12.2	. 026	.33	.33	3.05	. 163	С3 "
	7	7241	1243	9	26.6	.0311	. 34	. 34	2.96	. 191	С3 "
	8	6350	2533	5	17.6	. 0293	. 28	.28	3.52	. 184	C4 "
	9	11200	1867	18	52.7	.0158	. 34	. 34	2.93	. 099	C5 : Q-L
	10	1917	800	6	17.6	.0232	. 34	. 34	2.93	. 146	C6 : Q −L
BLOUCH	11	6600	1000	12	30.0	.025	.4	.4	2.5	.025	C7:R2
	12	9250	2434	7	15	.0304	. 47	.47	2.14	. 191	C7 "
	13	5780	2720	6	16	.02	. 38	.38	2.67	. 126	C7 "
RYERSON	14	(.28)		7	12.5	. 0289	.56	.56	1.79	. 182	C8:R3
	15	(.47)		5	9.0	.0240	.56	.56	1.80	. 151	C8 "

*Reference Code C - Appendix C of this report
C1 - pg. 1 of Appendix C of this report

R9 - Reference 9 (page 19) 14 - pg. 14 of Reference Q-L - Quick-look

**Numbers in parenthesis is % with x_0 being unit 1 and x_n being a fraction of x_0 .

The locator code in the computer output refers to Tables 2,3, and 4. For example: the first locator code in the computer output (page D-4) is "CHSL*18*20". This refers to Table 2 meaning "CORT-High Springing Load, Tape #18, Interval #20". In this way a direct connection may be made between Tables 2,3, and 4 and the computer output. The equations used for the calculations of the variables in the program are located on page D-2.

Using the output from the computer, Tables 1 - 5, and the SDRC results, a comparison was performed to see how close all inputs agree. Figure 2 is a plot of δ versus ζ . The "Key" differentiates between the SDRC results and the mechanical results. Since ζ is small (i.e. << 1.0), it was expected that the data points would lie on a straight line since δ is directly proportional to ζ as per Equation 6. The numbered points on Figure 2 correspond to the sequential numbering from Table 5. Generally the mechanical results plotted linearly with the SDRC results but gave higher values of ζ . This could possibly be explained by the lack of more information on the actual sea state existing at the time of stress measurements. Table 6 below gives the relative comparisons between the two results.

Table 6 - Comparison of SDRC Results with Mechanical Results

l	SDRC		Mechanica	1	<u> </u>
	Range of ζ	Avg.	Range of &	Avg.	SDRC avg * 100 Mech. avg.
CORT	.00611~.0246	.014	.017048	.029	48 %
BLOUGH	.01030248	.01916	.0200304	.0251	76 %
RYERSON	.0033700745	.00480	.0240289	.0265	18 %

As can be seen from Table 6, the differences in the calculated damping factors are quite pronounced, especially for the CORT and the RYERSON. At first inspection, this would tend to invalidate the SDRC results. However, despite the observed differences in Table 6 and Figure 2, an examination of frequency versus damping yields an interesting results.

Figure 3 is plot of w versus ζ using the results from SDRC. The data points for each vessel are enclosed within a dashed line. From Table 1 it may be seen that the CORT has a higher L/D ratio (22.2) than the other two vessels and this would tend to make the CORT more "flexible" than the BLOUCH or the RYERSON. This in turn would cause the CORT to have a lower springing frequency than the BLOUCH or the RYERSON. Since the RYERSON has the lower L/D ratio of 18.7, it would tend to be a stiffer ship and show a higher springing frequency. These observations are shown in Figure 3. The approximate springing frequency for the CORT is 0.32 Hz. despite the loading condition and despite the stress levels seen. By reviewing the original stress levels, the Low Springing Ballast case for the CORT is approximately

one-third the levels in the High Springing Load case. (See Table 2) This is an important observation illustrating that exciters that would be used for establishing the fundamental mode of hull vibration (springing) would not have to generate peak stress levels. The box girder of the vessel would still spring at approximately 0.32 Hz. The damping would be measured more accurately since the out-of-phase seaway damping would essentially be eliminated.

Figure 4 is a plot of damping versus frequency as calculated in Table 5. The numbered points correspond to the sequential numbering in Table 5. The enclosed dashed lines represent the SDRC results in Figure 3. As shown, several points are outside the representative areas but the corresponding points do correspond to the same frequency as depicted in Figure 3. Comparison between Figure 3 and Figure 4 illustrates this notable point: using only analog stress records (digitized by Teledyne) during periods of vessel springing, SDRC developed a list of damping factors and associated frequencies at springing which matched "fairly" well with a mechanical analysis from apparently disassociated springing records (Appendix C) and agrees with the known natural frequency of each vessel.

The unknowns in both analyses are (1) the components of the total damping, (2) the method and distribution of seaway loading on the vessel, (3) the out-of-phase/in-phase characteristics of the seaway with the hull response, (4) understanding of the full complexity of the hull structure, and (5) more accurate and complete description of the sea conditions (i.e. wave height, wave length, wave direction, wind parameters, and actual loading conditions). With this as part of the total consideration, the results from SDRC are very encouraging despite the differences calculated in Table 6.

As one final attempt for correlation between the two methods, the program in Appendix D also calculated the bending moment, BM, using both the P-T stresses of each vessel from Appendix A, but also using the max stress, X_0 , from Table 5. The calculated BM was plotted versus the damping factor. The plot is shown as Figure 5.

The values of BM calculated by Appendix D are shown in Column 6 of page D-4 of Appendix D. The values for BM from Table 5 are shown in Table 7. The BM was calculated by:

$$BM = \frac{SM * \sigma}{12 * 2000}$$
 FT-Tons

where:

BM = total bending moment, ft-tons

SM = section modulus, in.3

 σ = stress, psi 12 = 12 in./ft.

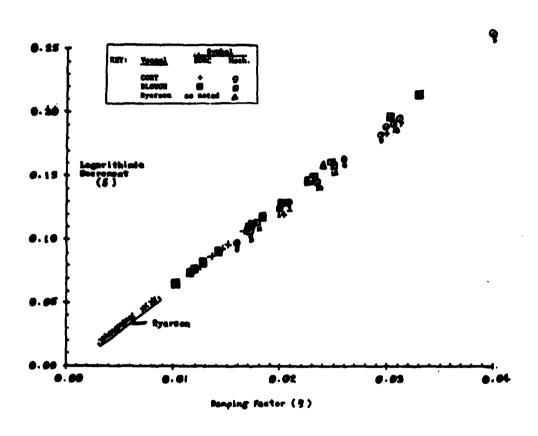
Table 7 - Calculated Bending Manents from Initial Stress of Table 5

	X	6	BM	
1.	6206	PSI	23833	FT-TONS
2.	2327	11	8986	11
3.	4913	11	18868	11
4.	6465	IT	24828	11
5.	7758	11	29794	11
6.	7500	***	28800	11
7.	7241	11	27808	11
8.	6350	11	24386	**
9.	11200	PT	43012	11
10.	1917	11	7361	***
11.	6600	**	16500	11
12.	9250	11	23125	11
13.	5780	17	14450	**

The SM used for each vessel is shown on page D-2. Since the RYERSON worked by relative values of X_0 and X_n , no BM was calculated. The calculated values for each vessel as per the SDRC results were boxed in. The BM's calculated in Table 7 were overlayed with the numbered points corresponding to the sequential numbering in Table 5 and in Table 7. There appears to be "general" agreement but there appears to be no conclusions that can be derived from this plot. The plotted points would be in better agreement if the damping factors were in better agreement. Therefore, the points for the BLOUCH show good agreement since the SDRC results are 76% of the mechanical results. (see Table 6) One final comment on Table 6: just because the results show better correlation of the SDRC results with the mechanical results for the M/V BLOUCH does not mean that a better analysis was performed on the BLOUCH or that better records were achieved or that springing was better identified. The only conclusion that can be drawn as result of Table 6 is that the comparative springing records in Appendix C may have more closely resembled the BLOUCH records used by SDRC. The sea conditions may have been closer to being the same. There is nothing to say that if different springing records had been chosen for comparison, the CORT or RYERSON results may have proven to give the best comparison with the SDRC results.

Conclusion

Considering the information that SDRC had and did not have, the results of their analysis is very encouraging. The damping values provided are a combination of structural damping, hydrodynamic damping, cargo damping, and out-of phase seaway damping. The data provided by SDRC may be used for further analysis. In order to arrive at the true structural damping within a vessel, an exciter capable of producing springing may be needed in order to eliminate so many of the unknowns which have complicated this analysis. The sign and operation of such a device presents its own difficulties in the form of unknowns, assumptions, and feasibility.



Pigure 2 -Damping vs. Logarithimic Decrement - Comparison of SDRC and Mechanical Results

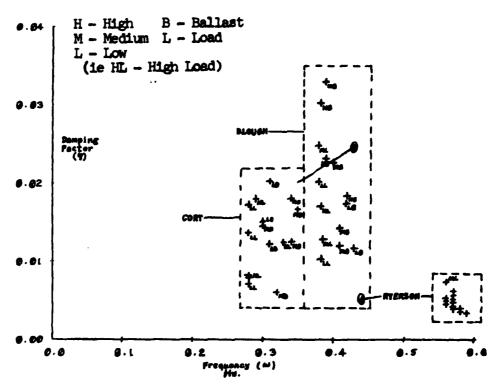


Figure 3 - Frequency vs. Damping Factor - SDRC data utilized in Calculations

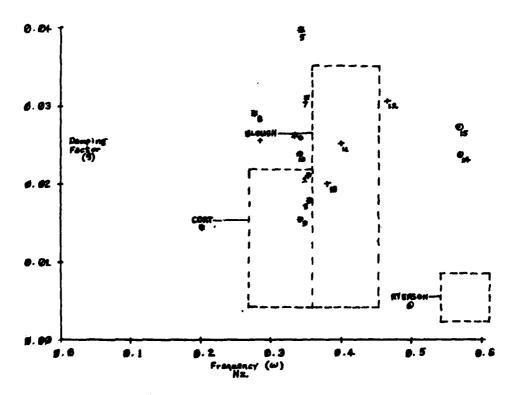


Figure 4 - Frequency vs. Damping Factor - Mechanical Data Used and Compared Figure 3

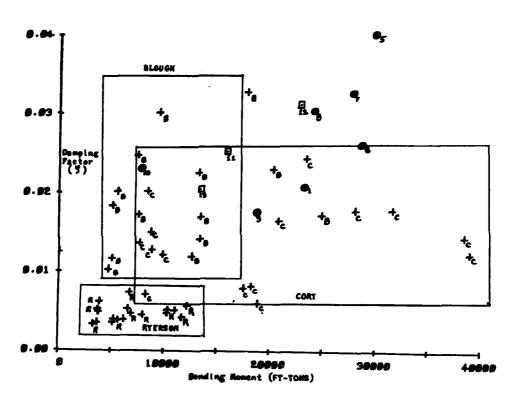


Figure 5 - Bending Moment vs. Damping Factor - Comparison of SDRC and Mechanical Results

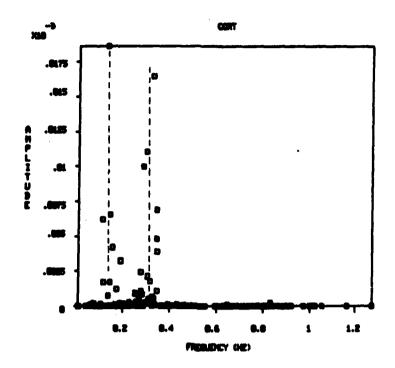


Figure 6(a) - Frequency vs. Amplitude - CORT All Data Points Submitted by SDRC

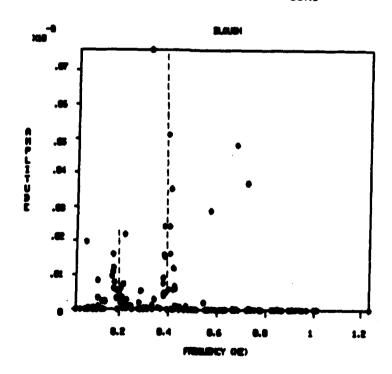


Figure 6(b) - Frequency vs. Amplitude - BLOUGH

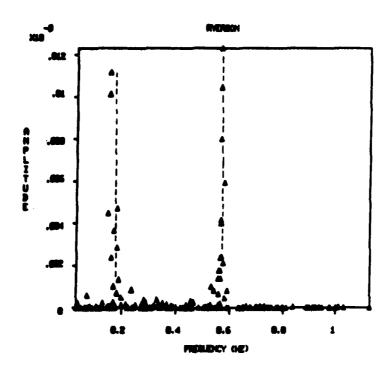


Figure 6(c) - Frequency vs. Amplitude - RYERSON

References

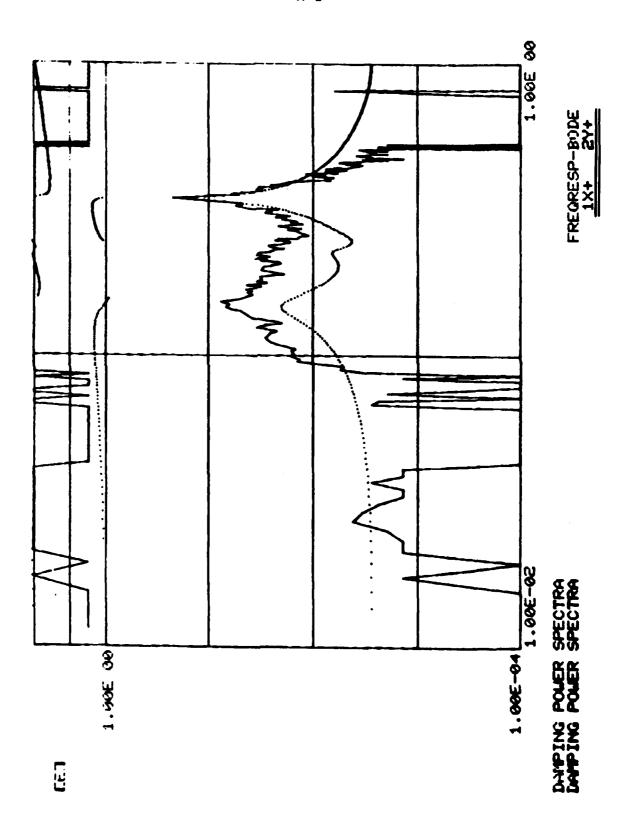
- 1. "Instrumentation of M/V STEWART J. CORT 1971-1974", Final Report # CG-D-162-75, Teledyne Materials Research, AUG 75, NTIS AD A022 164.
- 2. "Instrumentation of M/V ROCER BLOUCH-Second Season (1974-1975)", June 6, 1975, Teledyne Materials Research, NTIS.#
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- 4. "Dynamic Response of Large Great Lakes Bulk Carriers to Wave Excited Loads, S. G. Stiansen, SNAME, NOV 10-12, 1977.
- 5. "Theory of Vibration with Applications", William T. Thompson, 1972.
- 6. "Damping Factors in the Higher Modes of Ship Vibration", Toyoji Kumai, Reports of Research Institute for Applied Mechanics, Vol. VI, No. 21, 1958.
- 7. "Instrumentation of M/V ROGER BLOUCH 1973-1974 Season", June 30, 1974, Technical Report E-1739 (a), Teledyne Materials Research, TR-1738 (c).
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- 9. "Analysis of Springing Stresses on SS CHARLES M. BEECHLY and M/V STEWART J. CORT" Final Report # CG-D-163-75, July 1975, NSRDC, NTIS AD-A-018589.
- 10. CenRad Brochure, 'Modal Analysis... for improved structural design', obtained from Structural Dynamic Research Corp., Cincinnati, Chio.

APPENDIX A

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Sample Results from SDRC

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ν (7	9	•	380	.0202	4	20	2395-2425
7	200	49	7	.387	.0128	47	55	2440-2475
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APPENDIX B

Theoretical Background for Curve Fit Algorithm



Structural Dynamics Research Corporation 5729 Dragon Why Cincinnati, Chio 45227 513-272-1109 - TWX 810-461-2615

August 15, 1977

Lt. M. Noll Commandant (G-DSA/TP44) U.S. Coast Guard Washington, D.C.

Subject: Results of Springing Damping Analysis, SDRC Proposal No. 6704-01; Your RFQ No.

G-FCP-13/C22/77.

Dear Mark:

Attached you will find:

- 1. Table of calculated damping values.
- 2. Tabulation of modal parameters from each curve-fit
- 3. Plots with superposition of data and curve fit
- 4. Theoretical background for curve-fit algorithm

There are a few comments I would like to make concerning the interpretation of results:

- 1. The curve-fit algorithm used on this data to extract modal parameters is briefly described in the attachment (4). The form of the data we curve-fit was PSD, of course, not transfer functions. However, the data was assumed to be a transfer function where the force applied was a constant function of frequency, F(w) = 1.0 lbf so that division by this to get X/F (actually strain/force, which is not an important difference here) will not affect the shape of the curves.
- The algorithm we use to curve fit transfer functions will work on spectra with no phase information. The result is simply an analytical expression as a function of frequency whose amplitude is in error by a constant factor, and of course the calculated phase angle is meaningless. Thus mode shape coefficients calculated from a power spectrum would be meaningless. The damping on the other hand does not suffer from the lack of phase angle. As the superimposed plots show the overall shape of the curves, which are damping dependent, are correct, but the plot must be shifted up or down the vertical axis to obtain the correct amplitude. The constant by which the curve is in error depends upon the frequency of the most dominant peaks, so not all the plots show the same amplitude error.
- 3. The Hilbert transform is used to calcualte a phase angle from a power spectrum as a function of frequency. The inclusion of the phase angle data with the amplitude data in the curve fit allows exact amplitude correlation between transfer functions calcualted from the curve fit parameters and the original data (see Figures 1 and 2). However, as the enclosed plots show, the visual correlation can be done very well by comparing the shapes of the two curves.

Lt. M. Noll August 15, 1977 Page Two

4. The reason the Hilbert transform was not utilized in this project is that hardware problems with the computer were inhibiting a function required in the phase angle computation. For expediency, I elected to proceed with the data reduction rather than await the correction problem. The algorithm for curve-fitting was checked out on other data prior to reduction of the Coast Guard data to verify the hardware problem was not interfering with its operation.

If you need more information, or have any questions, please contact me.

Regards,

P. Live Smiley
R. Gene Smiley
Project Manager

RGS/dh

Enclosures

THEORETICAL BACKGROUND FOR CURVE—FIT ALGORITHM

APPENDIX A - THECRETICAL BACKGROUND

The theory behind modal analysis via frequency response functions can be examined by referring to the equations of motion for an N degree of freedom system with viscous damping:

$$[K][\ddot{q}] + [C][\dot{q}] + [K][q] = [f]$$
 (1)

where

[Ni] = mass matrix

[C] = viscous damping matrix

[K] = stiffness matrix

[q] = time history of the displacement of system

[f] = time history of excitation to system

[q] = time history of velocity of system

[q] = time history of acceleration of system

This equation is inconvenient to handle with standard methods of eigenvalue analysis if [C] is not proportional to [M] or [K]. However, a method has been proposed by Duncan (1)* which reduces these equations to a standard eigenvalue form. In this method combine the identity:

$$[M][\dot{q}] - [M][\dot{q}] = [0]$$

with Equation 1 to obtain:

$$\begin{bmatrix} \begin{bmatrix} 0 \end{bmatrix} \begin{bmatrix} K \end{bmatrix} \begin{bmatrix} C \end{bmatrix}$$

Represent this equation in the following manner:

$$[A][\dot{y}] + [B][y] = [z]$$
(3)

*Numbers in parentheses designate references at end of section

In order to find the solution to Equation 3 for the case of harmonic inputs, first consider the solution to the homogeneous equation found by letting [z] = [0]

$$[A][\dot{y}] + [B][y] = [0]$$
(4)

Seek a solution of the form $[y] = [Y]e^{st}$

therefore $[\dot{y}] = s [Y]e^{st}$

Hence, Equation 4, becomes,

$$s[A][y] + [B][y] = [0] or$$

 $[B] + s[A]][y] = [0]$

This set of equations only have a solution if the determinant of the coefficient matrix is zero.

$$det {[3] + s[A]} = 0$$

This leads to a set of 2N roots or eigenvalues $s_1, s_2 \dots s_{2n}$, which satisfy the above equation. For a resonant system, these eigenvalues will occur in conjugate pairs (2). Corresponding to each eigenvalue s_r , there exists an eigenvector $[\Psi^r]$ having 2N components satisfying the following equation:

$$[[B] + s_r[A]] [\Psi^r] = [0]$$
(5)

In the case where the eigenvalues of a system are complex, in which

case they occur in conjugate pairs, the eigenvectors will be complex and will also occur in conjugate pairs,

The above eigenvectors have important orthogonality conditions which can be easily shown. Consider the r^{th} and p^{th} eigenvectors $[\Psi^r]$ and $[\Psi^p]$ both of which satisfy Equation 5. First write Equation 5 for the r^{th} mode and premultiply by the transposed vector $[\Psi^p]^T$, to obtain:

$$[\Psi^{p}]^{T}[s][\Psi^{r}] - s_{r}[\Psi^{p}]^{T}[\lambda][\Psi^{r}] = [0]$$
(6)

Using the reversal law for transposed matrix products and recalling that [A] and [B] are symmetric matrices, transpose Equation 6 to obtain:

$$[\Psi^{r}]^{T}[B][\Psi^{p}]+s_{r}[\Psi^{r}]^{T}[A][\Psi^{p}]=[0]$$
(7)

Next write Equation 5 for the p^{th} mode and premultiply by $[\Psi^r]^T$

$$[\Psi^{r}]^{T}[B][\Psi^{p}]+s_{p}[\Psi^{r}]^{T}[A][\Psi^{p}]=[0]$$
(8)

If Equation 8 is subtracted from Equation 7, the result is:

$$(\mathbf{s_r} - \mathbf{s_p}) [\Psi^T]^T [\mathbf{A}] [\bar{\Psi}^P] = 0$$

If eigenvalues s_r and s_p are different, the following orthogonality property relates the two eigenvectors.

$$[\Psi^{r}]^{T}[A][\Psi^{p}] = 0 \tag{9}$$

It follows that these vectors are also orthogonal with respect to matrix [3]

$$[\boldsymbol{\Psi}^{\mathbf{r}}]^{\mathrm{T}}[\mathbf{B}][\boldsymbol{\Psi}^{\mathbf{p}}] = \mathbf{0} \tag{10}$$

Equations 9 and 10 are important orthogonality conditions which shows that the 2N vectors $[\Psi]$ form a linearly independent set, and therefore any vector in 2N space can be expressed as a linear combination of these 2N vectors. Since we are interested in frequency response information, let

$$[z(t)]=[z] e^{j\omega t}$$
 (11)

and seek a solution in the form:

$$[y(t)] = [Y]e^{j\alpha t}$$
 (12)

Substitute Equation 11 and Equation 12 into Equation 3 and divide by $e^{j\omega t}$ to obtain:

$$\mathbf{j}\omega[A][Y] + [E][Y] = [Z] \tag{13}$$

Since the eigenvectors defined by Equation 5 form a linearly independent set over 2N space, write the solution to Equation (13) as a linear combination of these 2N vectors

Substitute Equation 14 into Equation 13 and multiply by $\left[\Psi^{p}\right]^{T}$ to obtain:

$$\mathbf{j}\omega[\Psi^{p}]^{T}[\lambda]\sum_{\mathbf{r}=1}^{2N} \mathbf{v}_{\mathbf{r}}[\Psi_{\mathbf{r}}] + [\Psi^{p}]^{T}[\mathbf{b}] \sum_{\mathbf{r}=1}^{2N} \mathbf{v}_{\mathbf{r}}[\Psi^{r}] = [\Psi^{p}]^{T}[\mathbf{z}]$$

From the orthogonality conditions, we obtain:

$$\mathbf{j}\omega \mathbf{a}_{\mathbf{p}}(\mathbf{x}_{\mathbf{p}}) \div \mathbf{b}_{\mathbf{p}}(\mathbf{x}_{\mathbf{p}}) = [\boldsymbol{\Psi}^{\mathbf{p}}]^{\mathbf{T}}[\mathbf{z}]$$
where

$$\mathbf{a}_{\mathbf{p}} = [\Psi^{\mathbf{p}}]^{\mathrm{T}}[A][\Psi^{\mathbf{p}}]$$
$$\mathbf{b}_{\mathbf{p}} = [\Psi^{\mathbf{p}}]^{\mathrm{T}}[3][\Psi^{\mathbf{p}}]$$

Hence, we can solve Equation 15 for $% \mathbf{x}_{\mathbf{p}}$ to obtain:

$$\mathbf{x}_{\mathbf{p}} = \frac{[\Psi^{\mathbf{p}}]^{\mathbf{T}}[z]}{\mathbf{j}\omega \mathbf{a}_{\mathbf{p}} + \mathbf{b}_{\mathbf{p}}}$$
(16)

Substituting Equation 16 into Equation 14, we obtain:

$$[Y] = \underbrace{\sum_{r=1}^{2N} \frac{[\Psi^r]^T[z][\Psi^r]}{j\omega a_r + b_r}}_{(17)}$$

However, from Equation 7, we obtain

$$b_r + s_r s_r = 0$$

$$s_r = \frac{-b_r}{s_r}$$

Therefore, Equation (17) can be written

$$[Y] = \sum_{r=1}^{2N} \frac{[\Psi^r]^T[z][\Psi^r]}{a_r(j\omega - s_r)}$$
(18)

Frequently the complex eigenvalues s_r are written in the following form:

$$s_r = - \beta_r \omega_r \pm j \omega_r \sqrt{1 - \beta_r^2}$$

where

3 = damping ratio

ω_x = undamped natural frequency

In terms of [Q] and [F], Equation 18 becomes:

$$\begin{bmatrix} \mathbf{j} \, \omega \, \mathbf{Q} \\ \mathbf{Q} \end{bmatrix} = \sum_{\mathbf{r}=1}^{2N} \frac{\left[\boldsymbol{\Psi}^{\mathbf{r}} \right]^{\mathbf{T}} \begin{bmatrix} \mathbf{0} \\ \mathbf{r} \end{bmatrix} \left[\boldsymbol{\Psi}^{\mathbf{r}} \right]}{\mathbf{a}_{\mathbf{r}} (\mathbf{j} \, \omega - \, \mathbf{3}_{\mathbf{r}} \, \omega_{\mathbf{r}}^{\pm} \mathbf{j} \, \omega_{\mathbf{r}} \sqrt{1 - \, \mathbf{3}_{\mathbf{r}}^{2}})}$$

Therefore the frequency response function recorded from excitation applied at location k and response monitored at location i is:

$$H_{ik} = \frac{2N}{\sum_{r=1}^{2N} \frac{\Psi_k^r \Psi_i^r}{a_r(j\omega + \xi_r \omega_{r^{\pm}} j\omega_r \sqrt{1-\xi_r^2})}}$$
(19)

Since the eigenvalues occur in conjugate pairs, Equation 19 can be written as

$$H_{ik} = \sum_{r=1}^{N} \frac{\psi_k^r \quad \psi_i^r}{a_r(j\omega + 5_r\omega_r + j\omega_r\sqrt{1-5_r}^2)} +$$

$$\frac{\Psi_{r}^{r^{*}} \Psi_{i}^{r^{*}}}{\mathbf{a}_{r}^{*}(j\omega + \mathbf{b}_{r}^{*}\omega_{r}^{-j}\omega_{r}\sqrt{1-\mathbf{b}_{r}^{2}})}$$
(20)

Equation 19 is an extremely valuable relationship between Frequency Response Functions and modal characteristics. It relates motion at any point i due to an force at point k. Notice that equation 19 implies that the frequency response between response at i and excitation at k is the same as the function between response at k and excitation at i. Equation 19 is frequently written in the form:

$$H_{ik} = \sum_{r=1}^{2N} \frac{A_{ik}^r}{(s - s_r)} = \sum_{r=1}^{N} \frac{A_{ik}^r}{(s - s_r)} + \frac{A_{ik}^{r*}}{(s - s_r^*)}$$
(21)

where

$$A_{ik}^{r}$$
 = Residue at pole $s_{r}(i.e. \frac{\Psi_{i}^{r} \Psi_{k}^{r}}{a_{r}})$

The impulse response of the system can be obtained from Equation.

21 by performing an inverse transform to obtain:

$$E_{ik}(t) = \sum_{r=1}^{2N} A_{ik}^r e^{srt}$$
 (22)

Since the roots occur in conjugate pairs, Equation 22 can be written in the form:

$$H_{ik}(t) = 2 \sum_{r=1}^{N} \left| \hat{A}_{ik} \right| e^{-\frac{r}{2}} \cos \left[(\omega_r \sqrt{1 - \frac{r}{2}}) + \beta_{ik}^r \right]$$
 (23)

where

$$p_{ik}^r = \sqrt{A_{ik}^r}$$

Equation 23 indicates that the impulse response of the system can be represented by a summation of the number of damped cosine waves times the appropriate modal parameters.

The multi-degree-of-freedom (MDCF) curve fitting procedures in the modal analysis program calculates the value of A_{ik}^r in the above equations. Therefore, in the case where A_{ik}^r was determined from a displacement/force frequency response function, the value of a can be determined from the equation:

$$a_r = \frac{\Psi_i^r \ \Psi_k^r}{A_{ik}^r}$$

where

 A_{ik}^{r} is determined from a displacement/force function.

In the case where a velocity/force frequency response function was curve fit with the MDOF procedure, the parameter $\mathbf{a_r}$ is determined from the following:

$$a_{r} = \frac{\Psi_{i}^{r} \quad \Psi_{k}^{r}}{A_{ik}} \times i \ \omega_{r}$$

where: ω_{r} is in the units of rad/sec and

 $\mathbf{A_{ik}^r}$ is determined from a velocity/force function

Similarly, if an acceleration/force frequency response function is used, a_r is determined from the equation:

$$a_r = \frac{\Psi_i^r \Psi_k^r}{A_{ik}^r} \times (-\omega_r^2)$$

where

 $\omega_{\rm m}$ is in units of rad/sec and

 $\mathbf{A_{ik}^r}$ is determined from an acceleration/force function

If an analytical model is to be created from the test data, the parameters a_r , Ψ^r , ω_r and \mathfrak{F}_r are all that is necessary to describe the component with complex normal modes. However, in some cases an analyst would like to use a "real" mode approximation with the associated effective mass or effective stiffness in order to describe the component under test via the following equation:

$$H_{ik} = \sum_{r=1}^{N} \frac{\Psi_i^r \Psi_k^r}{m_r [\omega_r^2 - \omega^2 + j + j + \beta_r \omega_r]}$$
 (24)

In that case it is recommended that this approximate representation be determined by setting the magnitude of the mode shape coefficient equal to the magnitude of the complex mode shape value and the sign of the mode shape coefficient from one of the following procedures:

1) Inverse of the sign of the imaginary portion of the mode shape coefficient when a displacement/force frequency

response function is used to determine the mode shape coefficients.

- 2) The sign of the real portion of the mode shape coefficient when a velocity/force frequency response function is used to define the mode shape coefficients.
- 3) Sign of the imaginary portion of the mode shape coefficient when an acceleration/force frequency response function is used to determine the mode shape coefficients.

The effective mass necessary to approximate the actual frequency response with that described by Equation 24 can be determined from one of the following equations:

$$m_r = \frac{(\text{Approx. } \Psi_i^r)(\text{Approx. } \Psi_k^r)}{2\omega_r | A_{ik}^r|}$$

where A_{ik}^{r} is determined from a displacement/force function

$$n_{r} = \frac{(\text{Approx.} \Psi_{i}^{r})(\text{Approx.} \Psi_{k}^{r})}{2 \left| A_{ik}^{r} \right|}$$

where Ar is determined from a velocity/force function

$$m_{r} = \frac{\frac{(\text{Approx. } \Psi_{i}^{r})(\text{Approx. } \Psi_{k}^{r})}{2 |A_{ik}^{r}|} \times \omega_{r}$$

where A_{ik}^{r} is determined from a acceleration/force function

In order to represent a component in an overall system model .via a "real" mode approximation, the following approach can

...frequently be used. The uncoupled equations of motion for the component in terms of modal coordinates [%] are:

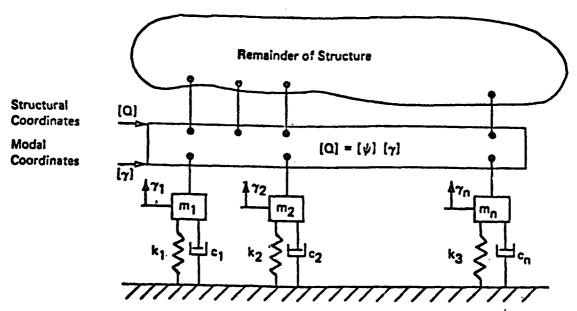
$$\left\{-\omega^{2}[m] + j\omega[c] + [k]\right\} [a] = [a]$$

where [m.] is a diagonal matrix of effective masses
[c.] is a diagonal matrix of effective dampness
[k.] is a diagonal matrix of effective stiffnesses

The motion of the physical coordinates [2] is related to the motion of the modal coordinates by:

$$[A] = [A] = [b]$$

Symbolically, this can be represented by the following diagram:



Therefore, a component can be represented analytically from test data in an overall system model by a set of springs, masses, dampers and equations of constraint which relate the motion of the physical coordinates to the motion of the model coordinates. Since the equations of constraint can be quite volumnous, the NASTRAN input and NATRIX Generation task provides the capability to generate NASTRAN Multi Poin Constraint (N.PC) equations in a relatively automatic marrier.

Model Analysis User Manual (3-JAN-77)

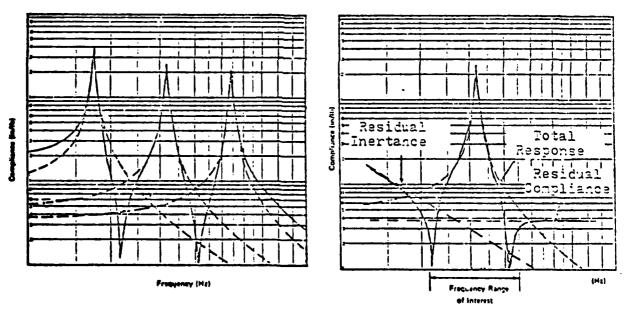
The frequency response in a specified range can be approximately described in terms of the following quantities:

- 1) "Residual Inertance" of the modes of vibration below the range of interest.
- 2) The modes of vibration which are resonant in the specified frequency range.
- 3) "Residual Compliance" of the modes of vibration above the range of interest.

Hathematically this can be expressed as:

$$H_{ik} = \frac{x_{ik}}{\omega^2} + \sum_{r=1}^{2N} \frac{\Psi_k^r \Psi_i^r}{a_r (j\omega + \delta_r \omega_r \pm j\omega_r \sqrt{1 - \delta_r^2})} + z_{ik}$$

This concept is shown graphically in the following figures:



The SDCF and MDCF curve fitting procedures available in the Estimation task are used to evaluate the contribution due to the modes which are resonant in the frequency range under investigation. In order to determine the contribution of the residual effects the Generate Residual command in the Frequency Response Synthesis task is used.

REFERENCES

- 1. W. J. Duncan, "Elementary Matrices" Macmillian Company, New York 1946
- 2. W. C. Hurty, "Dynamics of Structures" Prentice Hall Inc. 1964
- 3. A. L. Klosterman, "On the Experimental Determination and Use of Modal Representations of Dynamic Characteristics", Ph.D. Dissertation, University of Cincinnati, 1971.

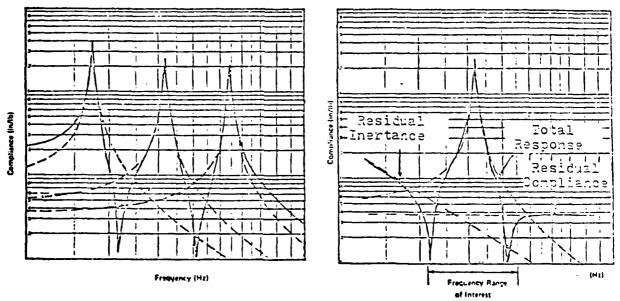
. The frequency response in a specified range can be approximately described in terms of the following quantities:

- 1) "Residual Inertance" of the modes of vibration below the range of interest.
- 2) The modes of vibration which are resonant in the specified frequency range.
- 3) "Residual Compliance" of the modes of vibration above the range of interest.

Mathematically this can be expressed as:

$$H_{ik} = \frac{X_{ik}}{\omega^2} + \sum_{r=1}^{2N} \frac{\Psi_k^r \Psi_i^r}{z_r (j\omega + \delta_r \omega_r \pm j\omega_r \sqrt{1 - \delta_r^2})} + z_{ik}$$

This concept is shown graphically in the following figures:



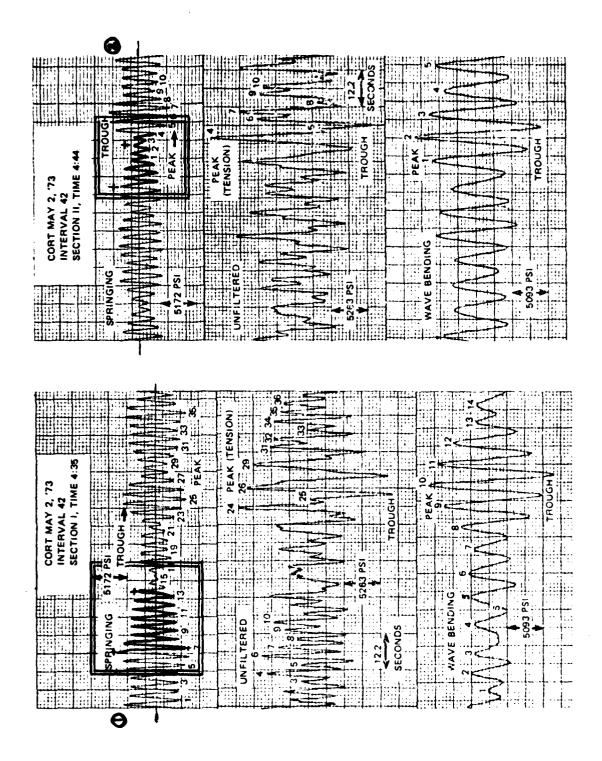
The SDOF and MDCF curve fitting procedures available in the Estimation task are used to evaluate the contribution due to the modes which are resonant in the frequency range under investigation. In order to determine the contribution of the residual effects the Generate Residual command in the Frequency Response Synthesis task is used.

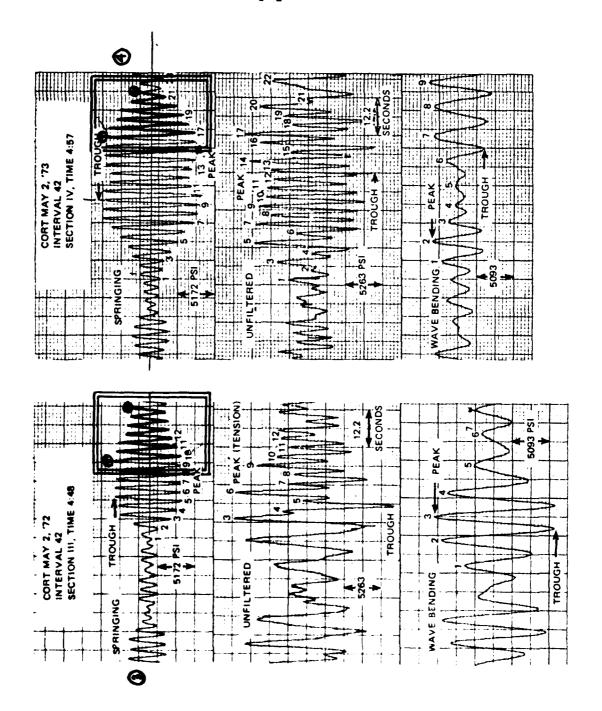
REFERENCES

- 1. W. J. Duncan, "Elementary Matrices" Macmillian Company,
 New York 1946
- 2. W. C. Hurty, "Dynamics of Structures" Prentice Hall Inc. 1964
- 3. A. L. Klosterman, "On the Experimental Determination and Use of Modal Representations of Dynamic Characteristics", Ph.D. Dissertation, University of Cincinnati, 1971.

APPENDIX C

Mechanical Analysis Data

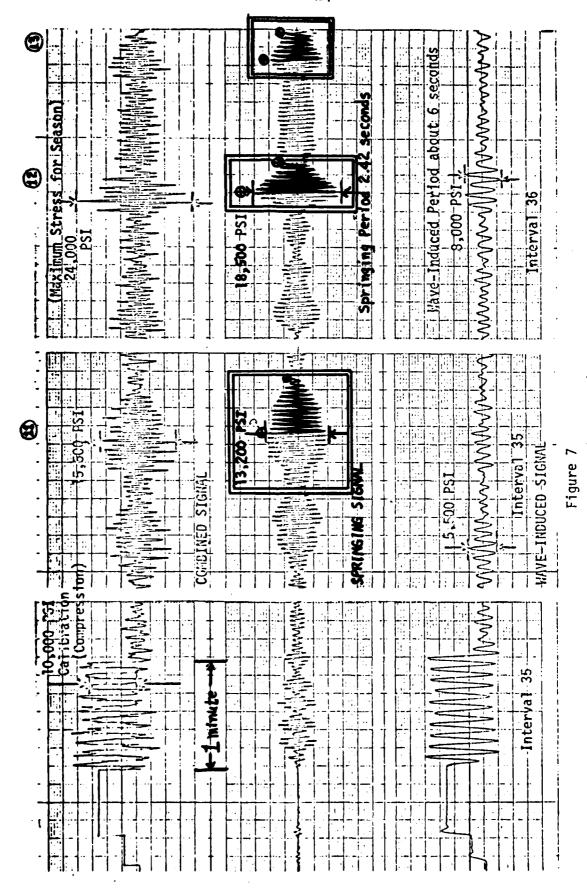




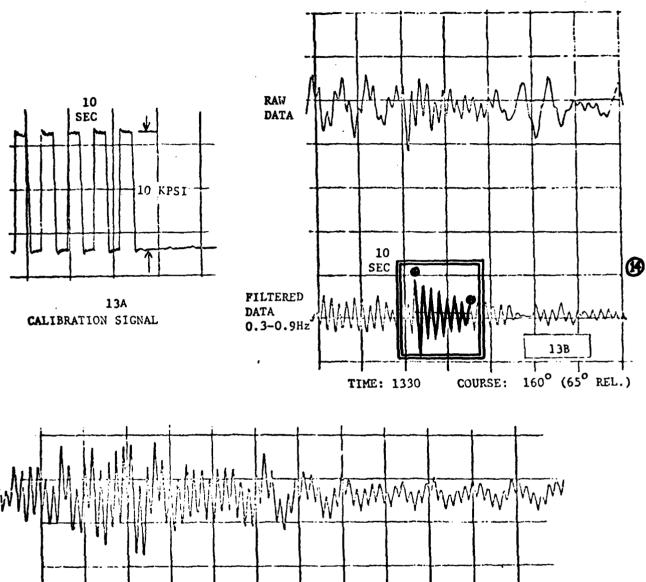
WANTOWN WILLIAM WINDOWN WAS AND WAS AN WWW. MINNING TO THE TOWN WITH

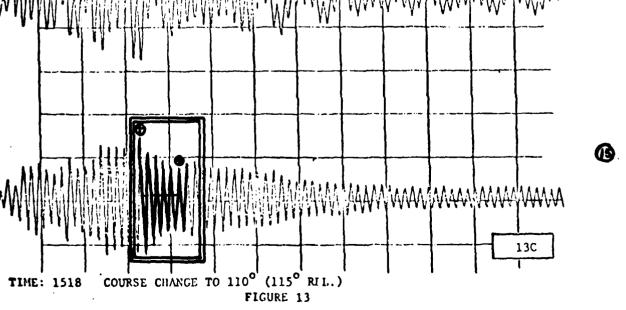
JAMINAMANA A JAMINA MANANA - MHKIMUM FOR INTERNAL 8650 psi -MAKIMUM FOR INTERVAL Aft Quarter Bending

WWW. MWW. MW. MAKIMUM FOR INTERVAL.



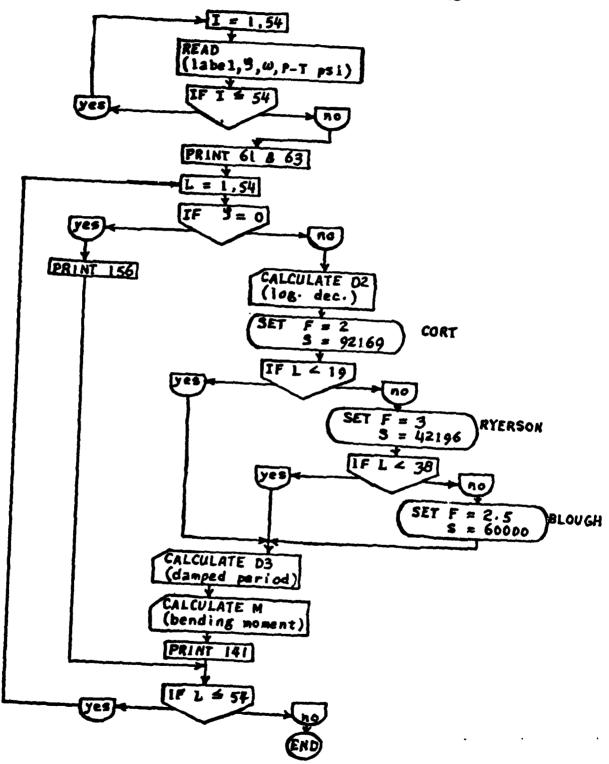
Tape 8R-74, Track 2 (Hatch 15) Filtered Record, M/V ROGER BLOUGH





APPENDIX D

Basic Program plus Results



Program Variables

D2 : Logarithmic decrement =
$$\frac{2 \pi \xi}{\sqrt{1 - \xi^2}}$$

The state of the s

D3: Damped Period =
$$t_d = \frac{\delta}{w_n * \xi}$$

M : Bending Moment = BM =
$$\frac{\sigma_{P-T}}{12 * 2000}$$

```
-D3-
10 DIM U(100,4),T$64,U$(100)64
20 INPUT L$,!!
30 FOR I=1 TO N
40 READ D$(1),D(1,2),D(1,3),D(1,4)
50 NEXT 1
60 PRINTUSING 61
61 % LOCATOR CODE
                     DAMPING
                                  FREQ
                                            LOG. DEC DAMPED PERIOD
                                                                       B.M.
62 PRINTUSING 63
69 Z
                     FACTOR
                                  (HZ)
                                                          (SEC)
                                                                       (FT-TONS)
70 FOR L=1 TO N
80 M=2
100 1F D(L,M)=0 THEN 155
110 D2=2*#FI*D(L,M)/(1-(D(L,M)+2)+.5)
120 F=2
121 5=92169
122 IF L<19 THEN 130
123 F=3
124 5=42196
125 IF LK38 THEN 130
126 F=2.5
127 5=60000
130 U3=D2/(F*U(L,M))
135 M=(S*(D(L,4)/2))/(2000*12)
140 PRINTUSING 141,0%(L),D(L,2),D(L,3),D2,D3,H
                                                                        *.###.+++
141 2 ############
                      ***
                                   特。特殊
                                             ######
                                                         ***
150 CDTD 160
155 PRINTUSING 156,D$(L)
156 2 普鲁特特特鲁特特特
160 MEXT L
170 END
180 DATA 'CHSL*18*20",.018,.29,14666
190 DATA: "CHBL*21*33",.0125,.33,0.,"CHSL*20*28",.0246,.43,12236,"CHSE*15*02",.01
25,.34,20306
200 DATA "CH58*15*2E",.0181,.34,16464,"CH5E*19*24*",.0145,.3,20036,"CM5L*26*03".
.00804,.28,9150,"CMSL*20*01",0.0,0.0,0.,"CMSL*19*05",.00828,.26,9554
210 DAFA "CMSB#15#30",.0167,.35,10895,"CMSE*15#06",0.0,0.0,0.,"CMCB#17#87",.0061
1,.32,9817,"CLSL*17*31",.0137,.88,3985,"CLSL*06*12",.0173,.28,3935,"CLSL*06*21",
.00719,.28,4335
220 DATA "CLBB*09*10",.0122,.31,5179,"CLSB*10*07",.0203,.31,4352,"CLSE*19*25",.0
151,.3,4595
원인1 DATA "NHL*5-1*1",.004원3,.57,11800,"RHL*4-2위1",.00455,.56,9110,"CH판+5-1#12",.
00433,.57,13420
222 DATA "RHE*5-1*13",.00514,.57,12621,"RHE*5-1*15",.00578,.57,13960,"R **5-1*16
 ',.00522,.57,11800,"RAL*5-2*19",.00533,.56,7550,"RAL*5-2×24",.00745,.55,7700,'RA
L*5-2*39",.00395,.57,7090
223 DATA "RME*4-1*10",.00405,.58,6000,"RME#4-1*11",.00362,.58,5900,"RME#4-1*15",
.00387,.57,6540,"RMB+4-1-17",.00475,.57.7940
224 DATA "RLL*6-1*3",.00625,.57,4470,"RLL*6-1*3",.00495,.56,4390,"RLL*6-1*10",.0
0524, 44, 4300
225 DATA "RLB*1-1*21",.00359,.58,4170,"RLB*1-1*24",.00336,.59,3730,"RLB*1-1*00",
0,0,0
226 DATA "BHL*13*51",0,0,0,0,"BHL*13*50",.0171,.393,10830,"BHB*08R*36",.0174,.42,2
0026, "BH5*13R*45*,.0232,.39,16274, "BH5*0DR*35*,.033,.39,14226
227.DATA "EML*13*52",.0903,.382,7581,"EML*13*53",.0248,.379,5971,"EML*13*47',.01
28,.387,7090,"EMB*13%3",.0143,.41,10721,"ENB*13*5",.0227,.4,10003,"BNB*13*4",.01
2,.41,10111
226 DATA "PLL*13*46",.0202..38,0159,"BLL*13*43*,0,0,0,"BLL*13*45",.0103..383.37
7, BLB*SH*28*,0,0,0,"BLB*8R*38*,.0117,.43,4642,*PLB*13E*57*,.0184,.42,4111
```

		- D4-			
	FACTOR	(HZ)	S	(SEC)	(FT-TONS)
CHSL + 18 * 20	0.018000	0.29	0.11517	3.199	2.816E+04
CHSL#21*33	0.012500	0.33	0.07953	3.181	0.000E+00
CHSL*20*28	0.024600	0.43	0.15846	3.220	2.349E+04
CHSP*15*02	0.012500	0.34	0.07953	3.181	3.899E+04
CHSB*15*2E	0.018100	0.34	0.11582	3.199	3.161E+04
CH5B*19*24	0.014600	0.30	0.09309	3.188	3.847E+04
CNSL#20#03	0.003040	0.28	0.05092	3.167	1.756E+04
CMSL*20*01					
CMSL*19*05	0.003280	0.28	0.05245	3.167	1.834E+04
CMSB*15*3D	0.016700	0.35	0.10671	3.194	2.092E+04
CMSB*15*06					
CMS8*17*27	0.006110	0.32	0.03862	3.160	1.885E+04
CLSL*17*31	0.013700	0.28	0.08727	3.185	7.651E+03
CLSL*06*12	0.017300	0.28	0.11061	3.196	7.555E+03
CLSL < 08°21	0.007190	0.23	0.04550	3.164	8.324E+03
CLSB*09*10	0.012200	0.31	0.07760	3.180	9.944E+03
CLS9*10*07	0.020300	0.31	0.13019	3.206	8.414E+03
CLS8*19*25	0.015100	0.30	0.05633	3.189	8.883E+03
KHL*5-1*1	0.013100	V.57	0.03049	2.104	1.037E+01
RHL*4-2*1	0.004550	, 0.56	0.02871	2.103	8.003E+03
RHB*5-1*12	0.004330	0.57	0.02732	2.103	1.179E+04
RHB*5-1:13	0.005140	0.57	0.03246	2.105	1.109E+04
RHB*5-1*15	0.005780	0.57	0.03652	2.106	1.227E+04
RHB*5-1*16	0.005220	0.57	0.03297	2.105	1.037E+04
RML*5-2*19	0.005390	0.56	0.03404	2.105	6.637E+03
KML*5-2*24	0.007450	0.56	0.04716	2.110	6.7955+03
RML 45-2+39	0.003950	0.57	0.02491	2.102	6.232E+03
RISB*4-1*10	0.004650	0.58	0.02555	2.102	5.274E+03
RM6#4-1#11	0.003620	0.58	0.02282	2.102	5.186E+03
RMH#4-1*15	0.003870	0.57	0.02441	2.102	5.749E+03
RMB#4-1#17	0.004750	0.57	0.02993	2.104	6.979E+03
HLL*6-1*8	0.006250	0.57	0.03951	2.107	3.929E+03
RLL*6-1*9	0.004950	0.56	0.03125	2.104	3.859E+03
RLL*6-1*10	0.005240	0.44	0.03309	2.105	3.780E+03
RLB*1-1*21	0.003590	0.58	0.02263	2.101	3.665E+03
HLB#1-1#24	0.003350	0.59	0.02118	2.101	3.322E+03
RLB#1-1#00	********		V.VL.10		
BHL*13*51					
BHL*13*50	0.017100	0.38	0.10931	2.556	1.353E+04
BH8#08R#36	0.017400	0.42	0.11126	2.557	2.503E+04
BHB*13R*45	0.023200	0.39	0.14923	2.572	2.0345404
BH3*06R*35	0.033000	0.39	0.21442	2.599	1.778E+04
BML+13×52	0.030300	0.38	0.19632	2.591	9.476E+03
BML * 13 * 53	0.024800	0.37	0.15978	2.577	7.463E+03
BML*13:47	0.012800	0.38	0.08146	2.545	8.862E+03
BMB#13*3	0.014300	0.41	0.09115	2.549	1.340E+04
BM8#13#5	0.022700	0.40	0.14594	2.571	1.325E+04
BMB*13*4	0.012000	0.41	0.07631	2.543	1.263E+04
BLL*13*46	0.020200	0.38	0.12953	2.565	5.573E+03
BLL*13*43	4.45454	V.30	V.1C333	E.303	3.3132703
BLL*13*45	0.010300	0.38	0.06539	2.539	4.721E+03
BLB*8R*28		V.36	4.0033	E.337	CVYSASIOF
BFR-84*38	0.011700	0.43	0.07438	2 FA2	5.052E+03
BLB*13R*57	0.018400	0.42	0.07438	2.543 2.560	5.052E+03
	V. V. 207 V. V	V 17E	APTILL	E.50V	5.1305403

APPENDIX E

American Bureau of Shipping letter

American Bureau of Shipping

Sustry-five Broadway New York, N. Y. 10006

Refer to YNC/bv The Ref

23 January 1979

Lt. Mark Noll
Department of Transportation
U.S.Coast Guard (G-DSA-1/TP44)
Washington, D.C. 20590

Dear Mark:

We have received the package containing a sample copy for the purpose of transfer of fund and your report "Evaluation of SDRC Damping Analysis" dated 18 October 1978. Matters regarding the feasibility study are now being handled by Dr. D. Liu, our Chief Engineer. I believe he has discussed this matter with you on the phone already.

I would like to offer some comments, as you so requested, on the SDRC work and your report as follows. I believe that the SDRC work and our efforts (hereby abbrieviation as ABS' work for easy reference) on analyzing the damping coefficient through the use of sea trial data (stress history) are based on the same principle, a happy coincidence. There are, however, major differences as noted below:

- (1) SDRC uses a multi-degree-of-freedom system and ABS uses a one d.o.f. system. It is believed that the inter-modal correlation in the power spectrum is neglibible with the provision of (2) as a safeguard.
- (2) We employ partial spectra based on a concept proposed by Vanmarcke (OTC 1971) rather than the full spectrum.
- (3) ABS' work also incorporate the equilibrium branch of a wave spectrum which is assumed to be inversely proportional to the fifth power of frequency. This is also a departure from Vanmarcke's original idea.
- (4) Since the power spectrum transformed from the stress time-history is expressed as blocks with constant ordinate within a frequency cell (bin), the fabricated spectrum should also be in the same form as in the case in our analysis. Our matching criterion, as proposed by Vanmarcke, is to have the quantity p of the fabricated spectrum to match that of the measured spectrum where

$$p = 1 - m_1^2/(m_1^2)$$

Lt. Mark Noll
Department of Transportation
U.S. Coast Guard

DATE 1/23/79 FILE REF

and

TO

m; = ith spectral moment.

In pursuing the curve fitting, the damping coefficient as well as the resonance frequency (not necessarily equal to the central value of the frequency cell) are regarded as variables. In doing so, the two spectra will have the same zero, first and second spectral moments.

We have employed 542 intervals of the "Cort" data set (1973 season) from which one value of the damping coefficient is obtained for each interval and the resulting histogram is shown in Fig. 1.

It should be noted that not all results are reliable. Some intervals have spectral ordinates so small that they are nothing but small ripples in the power spectrum (no springing). For this reason, cutoff values for the RMS value (square root of mo) have been used and the resulting mean and standard deviation of the set of results are shown as functions of this cutoff value as displayed in Fig. 2. As a result, those unreliable intervals are screened out as the cutoff RMS value increases and both the mean and standard deviation exhibit stablized trend. In this figure, the curves labeled as "C ≤ 0.039" represent further screening of elimininating the unusually high values of the damping coefficients which amounts to less than 5% of all intervals computed. It is evident that the damping coefficient is virtually independent of the stress level as the "stablized" portion of the curves indicate. It suffices to apply this conclusion without limiting it to the high stress samples since only the cases of high springing stress are of interest.

It is apparent although the number of intervals considered in the SDRC calculation is very small compared with our sample size, that the mean value of their results as well as the spread agree very well with our results (i.e., mean \approx 0.0145, standard deviation \approx 0.0045).

As indicated in your report, results obtained utilizing the logarithmic decrement method are much higher than those from spectral synthesis. We have observed the same tendency through the case of the RANDOMDEC method which yields a vibration signature in the time domain. Such time domain signatures are subsequently analyzed by way of logarithmic decrement. One possible explanation of the discrepancy between results obtained in these two methods is that in the time domain, the signal is not truly monochromatic. In this regard, perhaps

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Lt. Mark Noll
Department of Transportation
U.S. Coast Guard

DATE 1/23/79 FILE REF.

the test of a ship with zero surge would yield closer agreement between the two approaches.

Based on the discussion presented above, it appears that the spectral synthesis approach is more promising. In this regard, the approximate shape of the wave energy spectrum should also be accounted for as our analysis indicates that the omission of this aspect leads to about 20% higher values for the damping coefficient on the average.

I hope the preceding comments would provoke more subsequent discussions on this subject. If you have any suggestions or comments, please feel free to contact me.

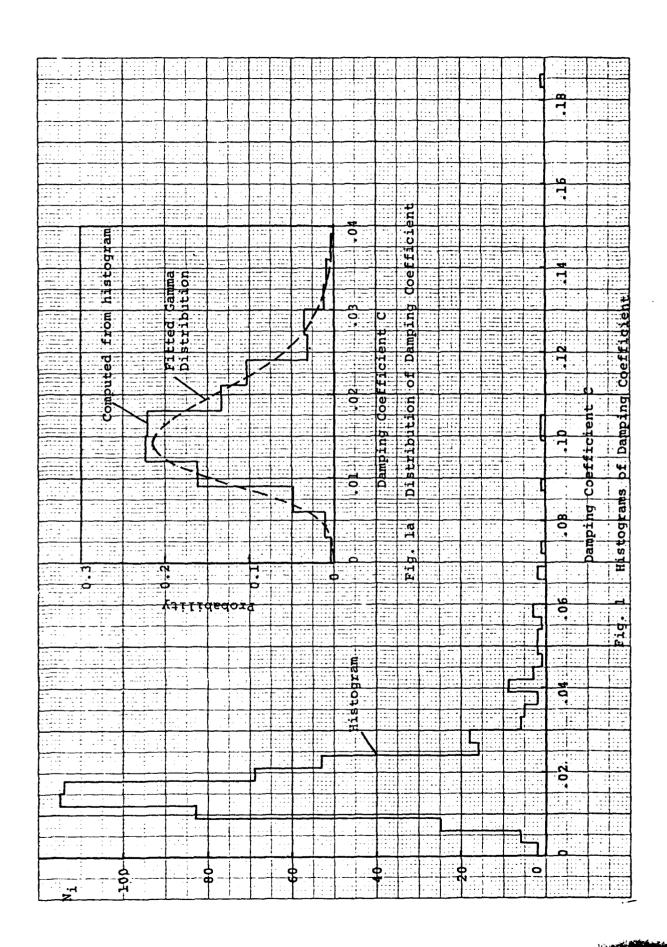
Sincerely yours,

y. n. Chen Y.N. Chen

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APPENDIX F

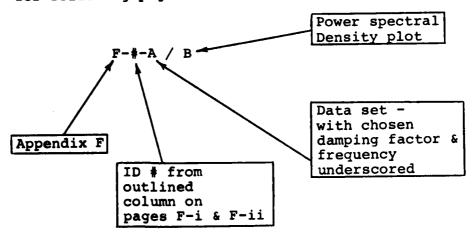
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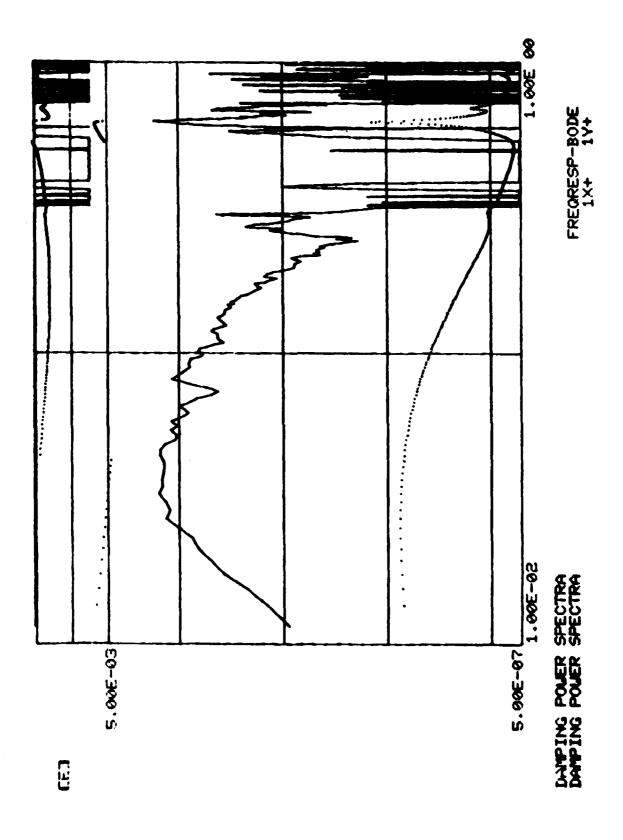
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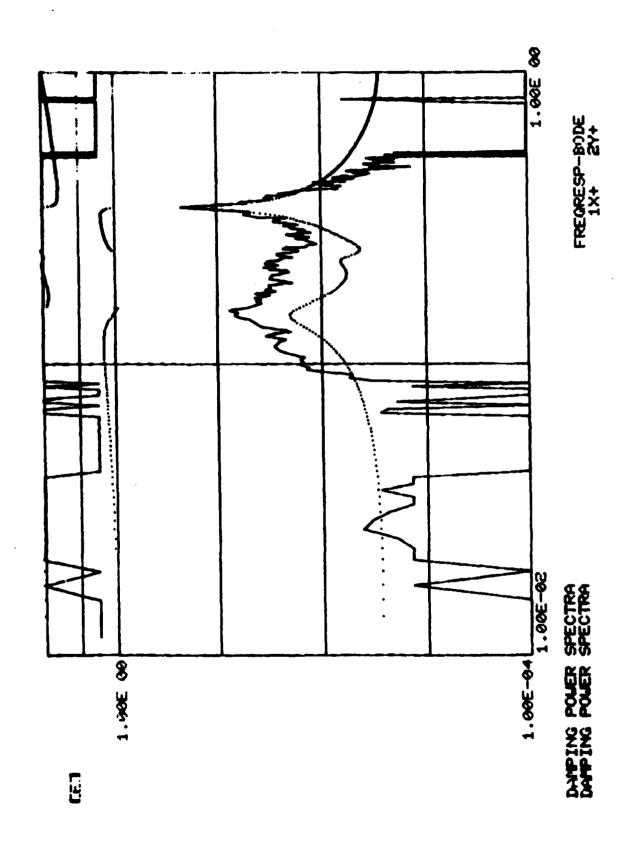
	PHASE	3.148	-1.343	1.369	0.5438	-2.041	ი. 436	-0.6885E-01	-0.21		-0.6822	0.1210E-05
	SMDI TTIINE	0.1960E-06	0.8257E-06	0.1391E-11	0.6609E-08	0.1350E-08	0.1624É-08	0.3414E-07	0.4270E-08	0.9081E-12	0.1213E-08	0.1541E-07
CORT	14+)	1.000	4000	0.6269	0.1749	0.3521E-01	0.5288E-01	0.5397E-02		0.6282E-01		
	1×+	10	2.5	•								
	TIMATED ROOTS	0.1408F-01	• 0.	0.1234	8.2948	0.3162	9.5696	0.6266	0.6972	0.8798	0.9171	1.058
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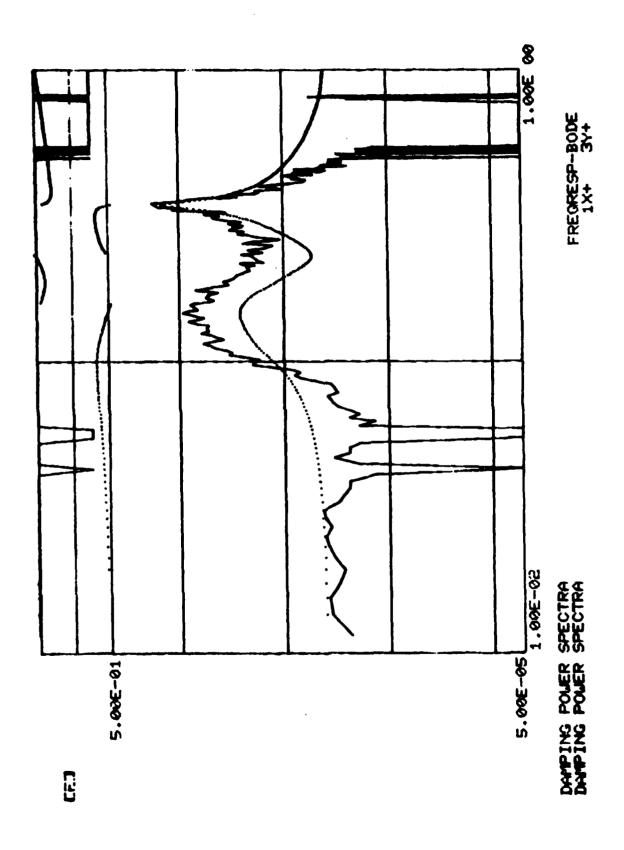
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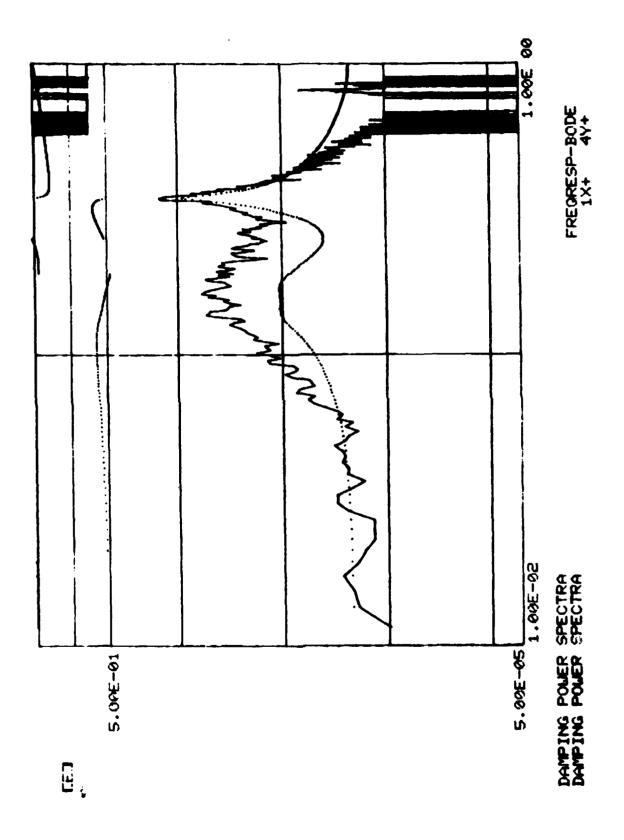
	PHASE	-0.8724E-02	5.96	-1.650	0.238S	-0.6653	-0.2004E-01	1.366	-1.783	-0.9194	יין ו יין	- A 6500E-0-
	AMPLITUDE	0.9041E-06	0.1975E-08	176	4	0.2644E-04	0.4804E-03	0.5835E-05		ਾਵਾ	0.2013E-09	0.1014F-06
1×+ 0×+)	DAMPING	1.000	1.000	0.1981	0.8880E-01	0.5714E-01	0.1247E-01	0.2279E-01	0.5420E-01	0.3782E-01	0.3452E-01	0.4167E-03
ROOTS (EO.	0.5261E-02	6.2469	Ø.1155	0.1476	. S39S≥ • 0	0.3455		0.4562	0. 5068	0.7963	6.8169
ESTIMATEL	E STOR	€-1	ល	יח	す	ņ	ī	<i>ر</i> -	00	O	10	11



	PHASE	2.894	1.824	-0.4368	2. 038	-0.8678E-01	2.614	-8.348	-3.124	0.2672	-0.2747E-01	-0.7412E-08
	AMPLITUDE	0.2670E-07	0.1722E-03	0.4183E-03	0.7068E-04	0.6887E-03	0.6661E-05	0.8692E-08	0.5548E-06	0.1463E-07	0.2388E-06	0.1230E-11
34+)	DUMPING	1.000	0.2249	0.1742	0.2842	0.1808E-01	0.2614E-01	0.5840E-01	0.1046	0.5204E-02	0.1316E-02	0.5159
1X+												
J	•	-01										
ESTIMATED ROOTS	FREGUENCY	9.4071E-01	9.1177	0.1566	0.2750	0.3449	6.3941	P. 4865	0.5321	0.7932	0.8103	1.167
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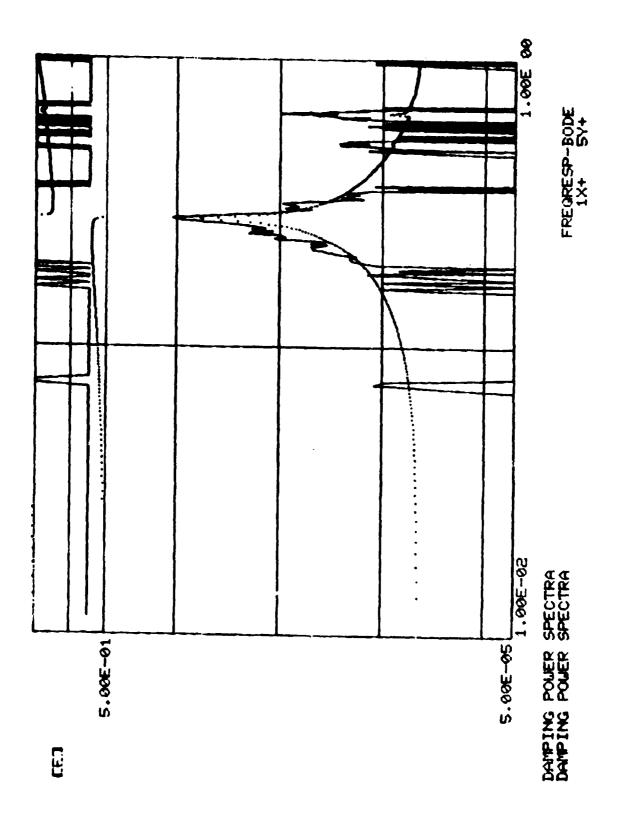


	PHASE	-0.1486F-03	0. TARE1	9.5750F-01	-2.317	0.0055F-01	0.4132	-0.8076	(AQ. (C)	-0.55.04	8269.6	0.5214E-03
	AMPLITUDE	0.37435-05	0.6993F-04	0.1235E-63	0.6330E-04	0.3899E-03	0.3281E-05	0.2943E-07	0.5355E-07	0.29235-06	0.26055-06	0.4449E-07
(十六年 十六日	DEMPING	1.000	0.1426		0.1501	0.1672E-01	0.1476	0.1186E-01	0.7756E-01	0.5461E-03	0.1278E-01	0.8866E-01
J	FREQUENCY	0.5355E-01	0.1394	0.1751	0.3263	0.3460	0.4611	0.4987	0.6162	0.8131	9.8 2 80	1.004
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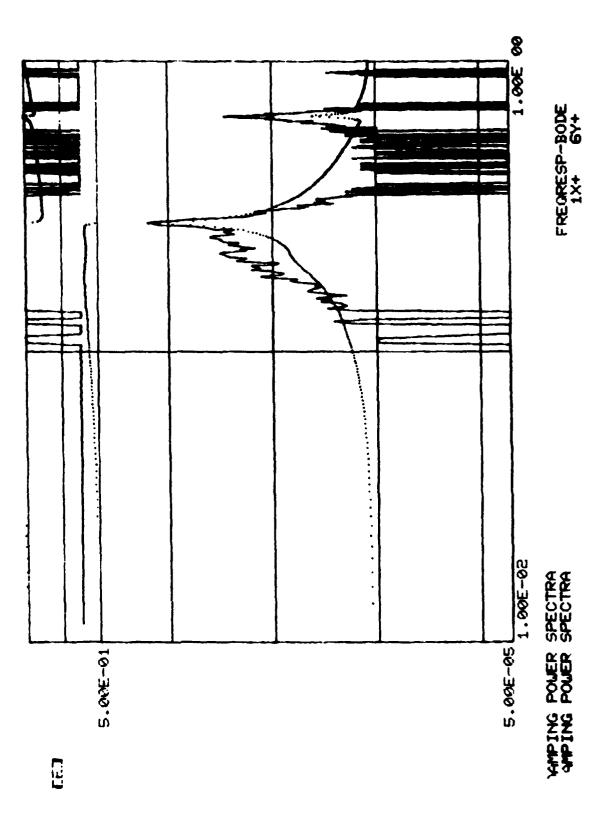


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	PHASE	-0.1979	0.3104	101010 101010	-0.6889E-01	-1.482	100		-0.39E0E-01	-0.3501E-01	n. 040	0000	0 1904F-00
	AMPLITUDE	0.7518E11	0.4335E-08	9.7928E-05	0.1077E-03	Š	0.1848F-10	0.1318F-00	00.000.00	00100000	מינטועב-מינ	0.2382F-07	0.8176F-07
+ 57+)	DHILL	1.990	0.3200E-01	0.9224E-01	8037	0.4792E-01	0.1647	0.7253E-02	0. 6007F-02	46405-	20130	0.1172E-01	
7. 7.			91										
TED ROOTS (1X+	FREQUENCY	0.1273	€.5831E-01	3.248E	0.2785	0.3271	0.4938	0.5108	0.6475	0.7005	٠.	カマンカ・シ	1.054
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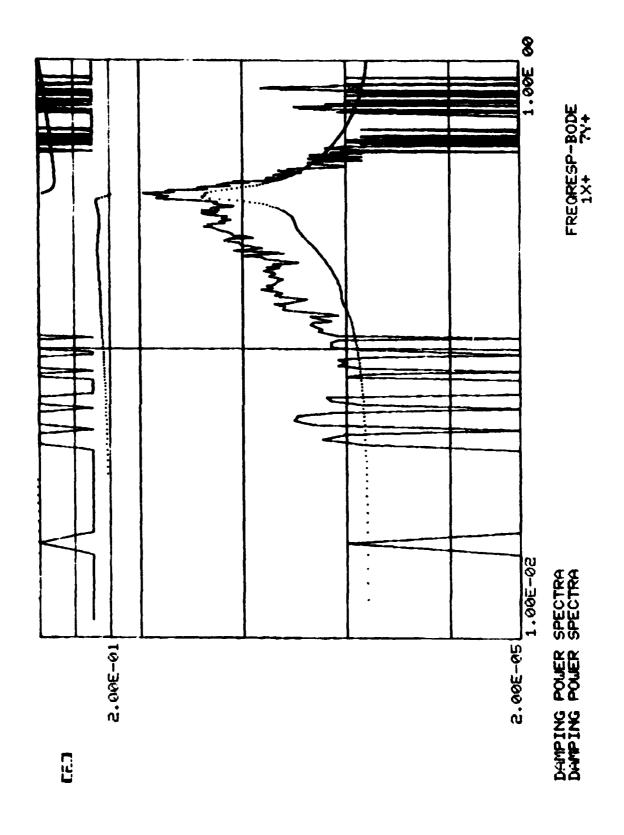


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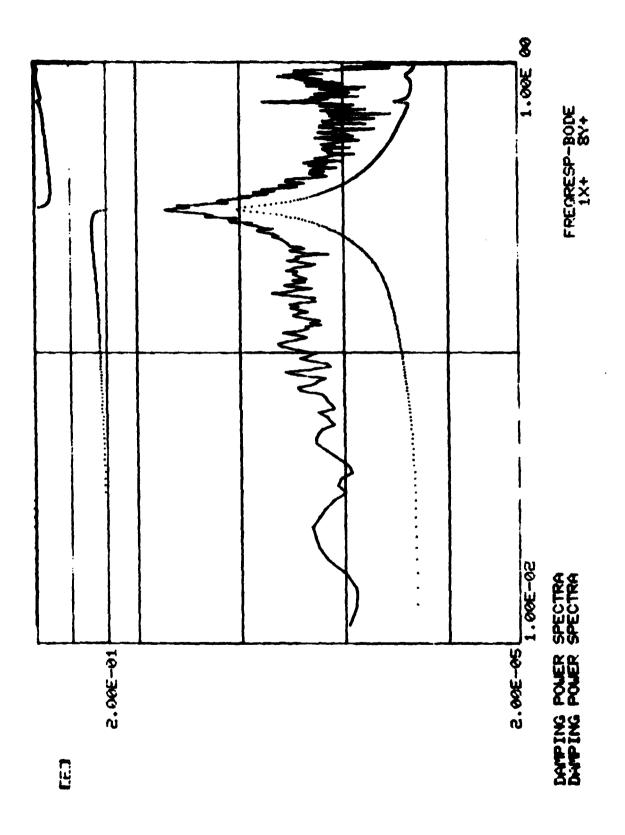


F-6-B

	PHASE	1.337	Ø.7982	0.5627	0.8424	-0.5375	-1.224	•	-2.659	-0.2077E-01	0.6746
	AMPLITUDE	0.9564E-08	0.5860E06	0.2799E-04	0.5293E-04	0.1063E-03	0.1547E-06	0.1503E-06	0.1015E-06	0.4511E-06	80-35005.0
(+*4 +	DAMPING	0.5568	0.6536E-01	Ø.1348	0.1401E-01	0.2487E-01	0.1122	0.1049E-01	0.1061	0.3155E-02	A 4047F-00
4 7 4											
MATED ROOTS	FREQUENCY	0.4523E-01	Ø.1466	9.2664	Ø.3341	0.3464	Ø.486S	Ø. 6 88Ø	A.7188	0.8037	0.8679
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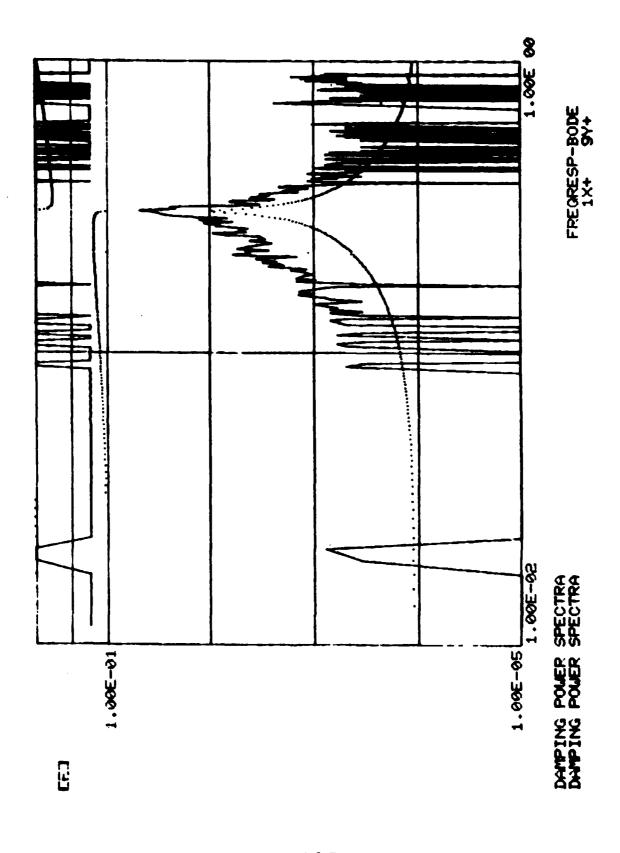


PHASE	0.140	1.490	9	-0.8674	0.1340F-00	2.215	0.00 0.00 0.00 0.00 0.00	0.1740	0.4500F-01	n.	S CO
AMPLITUDE	0.7234E-AS	0.3797E-12	0.29976-07	0.4006E-05	0.4964E-04	0.2180E-05	0.3914E-08	0.1221E-06	3819E-	0.2014E-11	370
1X+ 8Y+) DAMPING	1.000	1.600	Ø.1295	ଜ. 4098	0.2029E-01	0.1880	0.4302E-01	0.6774E-01	0.7815E-02	0.2145	0.2905E-01
+											
MATED ROOTS FREGUENCY		7	w.1278	•	• 1	•	0.4988	•	•		0.9097
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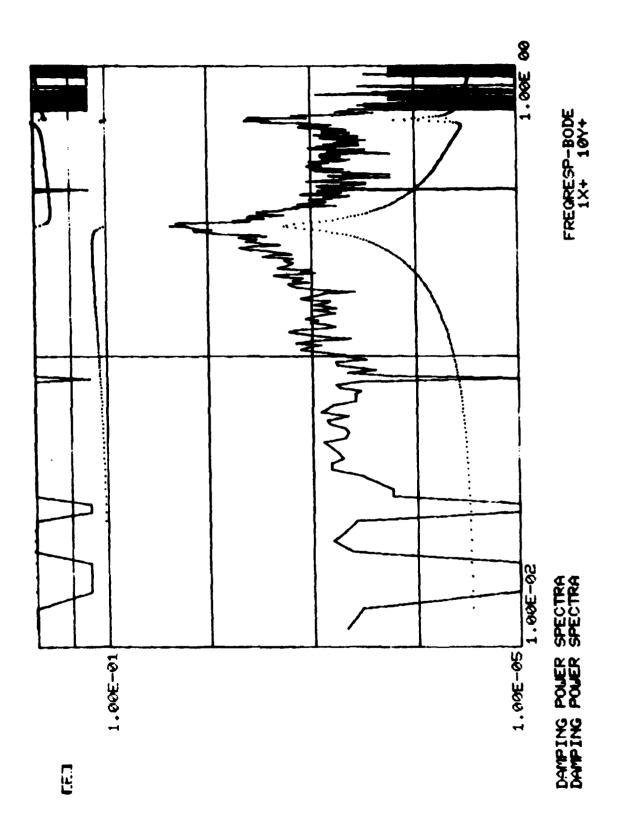
	PHASE	-0.9463F-05	962	-0.2751	1.435	-0.9509F-01	1.401	2.847	-3.005	•	•	-0.3207
	AMPLITUDE	0.69395-07	0.1584E-11	C	0.2852E-05	0.2735E-04	0.4571E-09	រោ		0.3357E-07	0.6035E-10	0.4732E-07
(+\b6 +		1.000	1.000	0.8338E-04	0.1936	0.1221E-01	0.1213	0.3723E-01	0.2817E-01	0.3544E-03	0.5341E-01	0.1095E-01
1×4		01										
ESTIMATED ROOTS	FREGUENCY	0.8865E-01	Ø.1675	0.2207	ტ.∂634	0.3060	0.3676	0.5216	0.6577	0.7227	0.8473	0.8820
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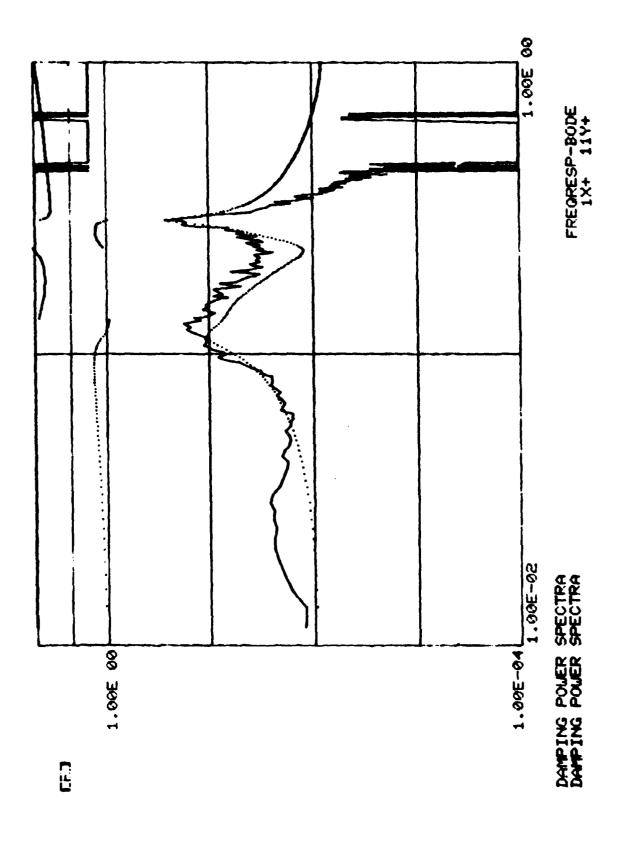
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PHASE	-0.9321E-01	-3.142	0.1204E-01	1.444	-0.1304	-1.699	0.2749	-0.2434	0.9560	Ø.1025	2.830
AMPLITUDE	0.4112E-11	0.6029E-07	0.1463E-08	0.8394E-06	0.6758E-05	80-3ES89.0	•	0.3500E-06	0.6879E-07	3514	
18Y+) DAMPING	1.000	1.000	0.2587	0.1915	0.1727E-01	0.1428E-01	0.7605E-01		1235		-3979E-
IMATED ROOTS (1X+	o.1008	0.5900E-01	 1216 	6.8736	0.2815	0.4712	0.4743		0.8600	•	•
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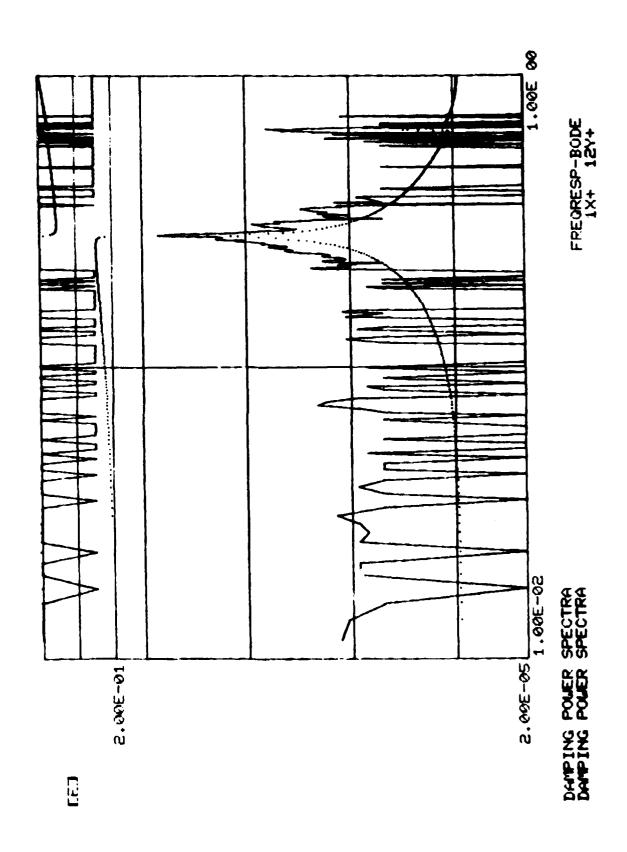
F-10-B

	PHASE	-3.132	-3.148	9.6296	-0.5320	986. 0	-0.1200	-2.012	-2.969	-0.9387E-01	1.613	-1.790
!	AMPLITUDE	0.3001E-07	0.2871E-09	0.6186E-03	0.6537E-03	0.8956E-04	0.9974E-03	0.9075E-06	0.6185E-08	0.5931E-06	0.1112E-07	0.7845E-09
11	DAMPING	1.000	1.000	0.9220E-01	0.1968	0.9873E-01	0.1800E-01	0.1221	0.5902E-01	0.1095E-01	0.3590E-02	0.2307E-01
STIMMTED ROOTS (1X+	FREGUENCY	0.6464E-01	8968.0	0.1141	0.1468	0.2544	6.2873	0.4357	<i>ଚ</i> .600ନ	0.65 26	0.7279	0.9134
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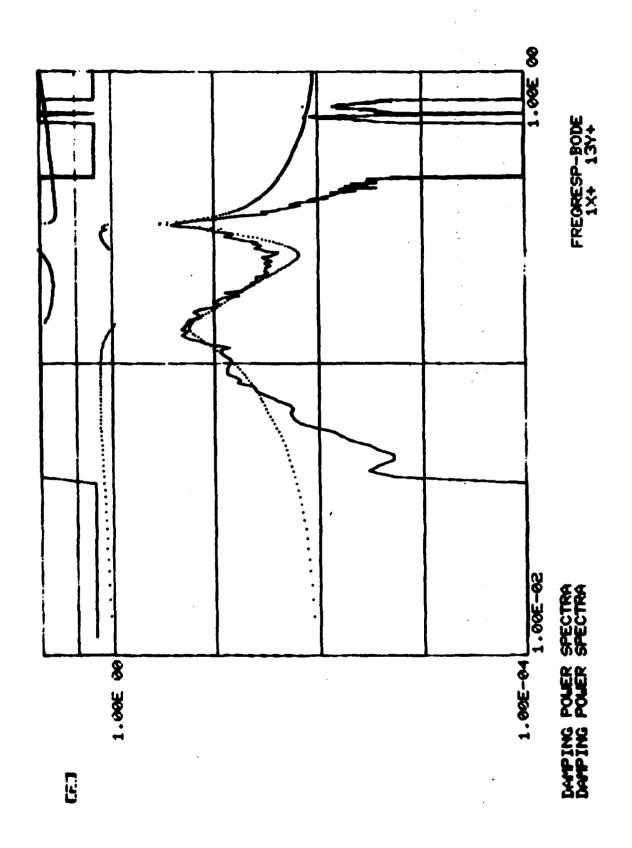
	PHASE	-2.015	-1.207	-3.127	0.2655E-02	-2.340	-2.003	1.700	-0.8669E-01	0.1702	ø.3196
	AMPLITUDE	0.2066E-08	0.3331E-07	0.3522E-06	0.2206E-04	0.1589E-06	0.1529E-09	0.3313E-07	0.3536E-06	0.3986E-08	0.6390E-12
127+)	DAMPING	0.2276	0.5603	0.1864	Ø.7188E-02	0.9297E-01	0.7148E-01	0.6499E-01	0.3664E-02	0.1781E-03	0.2437E-01
1X+											
TED ROOTS (FREGUENCY	Ø.1021	0.1346	0.2289	9.232e	0.3661	0.4430	₩.6033	0.6524	0.7259	0.8941
ESTIMATED	100	- 4	ាវ	ŋ	4	in	21	£-	w	Ø	10



COAST GUARD WASHINGTON DC OFFICE OF RESEARCH AND DEV---ETC F/6 13/13 EVALUATION OF SDRC DAMPING ANALYSIS.(U)
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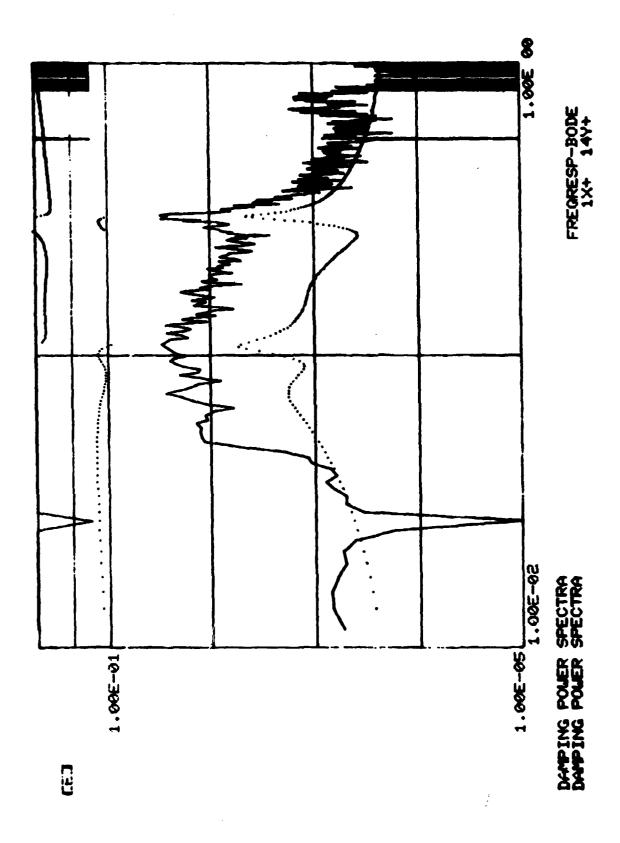
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	PHASE	-3.142	+	0.1360	-2.850	9	-0.6478E-01	-3.024	0.1468	w	-0.1711E-01	-0.7022E-03
	AMPLITUDE	6.2356E-04	0.9684E-05	0.1861E-02	0.3221E-03	0.8389E-04	0.1102E-02	K	761E-	•	0.4854E-06	.8773E
~ + ~ り ! ・ + ~ 1		1.000	•	•	•	0.6963E-02	0.1470E-01	0.430SE-01	0.6166E-02	0.6860E-03	0.3946E-02	0.2074
	FPEQUENCY	9.8317		0.132E	0.1913	0.2860	0.3013	0.4438	0.6955	9.7596	•	1.000
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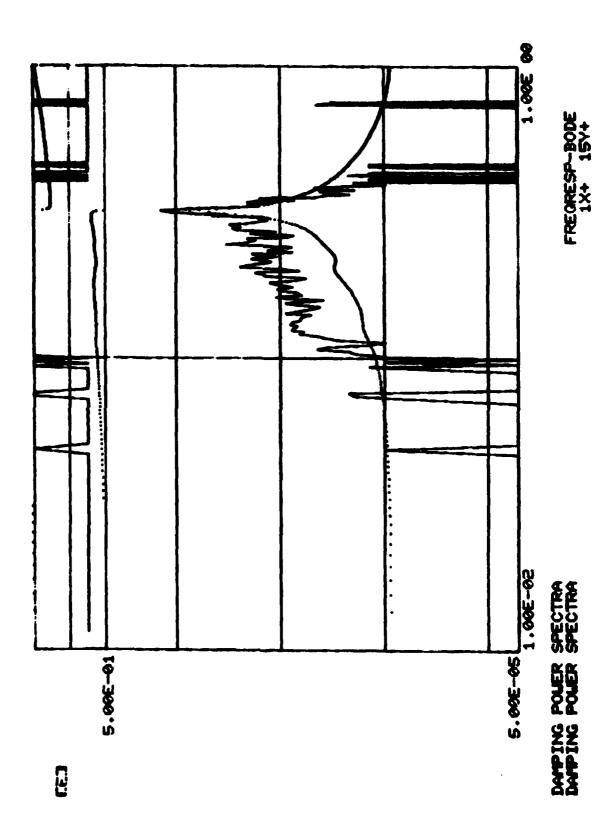
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	BINGE		3.133	1,697		0.7550	7000		6.54A	-0.778GF-01	2000	1005.0	-1.302	000	11.000	SAN DE		-0.0000E-00	2 44 4	F 7 7 7 7
	AMPLITTINE	30-10000	100 III	0.1247E-08	•	_	•	•••		0.1751E-03	A. GORIE-OF		0.7132E-08	0 3682F-00	מס וחספיי	0.1498F-06		۲	1213	
1X+ 15Y+)	DAMPING	1.000		1.000	0.9427F-91		8	0.1288		v.6112€-02	0.3494E-01	200000	0.E000E-01	0.2039E-01			2100		0.2502E-02	
TIMATED ROOTS (TABOCEN'S	9.5379	5, 15,12 C131, 2		4 0.1264	4 0000	ייייייייייייייייייייייייייייייייייייייי			6016-0	0.3405	B 6.4710		s.	77.0		1.00.1		1.666	
	TIMATED ROOTS (1X+	TIMATED ROOTS (1X+ 15V+)	TIMATED ROOTS (1X+ 15V+) OT FREQUENCY DAMPING AMPLITUDE O-5379 1.000	TIMATED ROOTS (1X+ 15Y+) OT FREQUENCY DAMPING AMPLITUDE 1.000 0.7797E-06 3	(1X+ 15Y+) Y DAMPING AMPLITUDE 1.000 0.7797E-06 1.000 0.1247E-08	TIMATED ROOTS (1X+ 15Y+) OTHER FREQUENCY DAMPING AMPLITUDE 1 0.5379 1.000 0.7797E-06 3 2 0.1247E-08 1 0.9427E-04 0.9427E-04	TIMATED ROOTS (1X+ 15Y+) OT FREQUENCY DAMPING AMPLITUDE 1.000 0.7797E-06 3 0.1517 1.000 0.1247E-08 1 0.9427E-01 0.1696E-05 0.	TIMATED ROOTS (1X+ 15V+) OT FREQUENCY DAMPING AMPLITUDE 3 O.5379 1.000 0.7797E-06 3 O.1517 1.000 0.1247E-08 1 O.2062 0.90427E-01 0.1212E-04	TIMATED ROOTS (1X+ 15V+) OFFICIENCY OFFICIENCY 1.000 0.7797E-06 3.0.1517 1.000 0.1247E-08 1.000 0.1247E-08 0.9048E-01 0.2062 0.9048E-01 0.2062	TIMATED ROOTS (1X+ 15Y+) O-5379	TIMATED ROOTS (1X+ 15Y+) O 5379 O 5379 O 5379 O 69427E-06 O 7797E-08 O 1264 O 99427E-01 O 2662 O 9048E-01 O 2592 O 1288 O 2455E-04 O 6112E-02 O 1751E-03	TIMATED ROOTS (1X+ 15Y+) O 5379 O 5379 O 5379 O 69427E-06 O 7797E-08 O 1264 O 9427E-01 O 1696E-05 O 1288 O 1288 O 2592 O 1288 O 2495E-04 O 3494E-01 O 5081E-03 O 3494E-01 O 5081E-08	TIMATED ROOTS (1X+ 15Y+) O.5379 1.000 0.7797E-06 3.1517 1.000 0.7797E-06 3.01264 0.9427E-01 0.1696E-05 0.1268 0.1288 0.1751E-04 0.34965 0.3494E-01 0.6981E-05 0.3494E-01 0.6981E-05	TIMATED ROOTS (1X+ 15Y+) O 5370 O 5370 O 600 O 7797E-06 O 7797E-06 O 1264 O 9427E-01 O 2068 O 1268 O 1288 O 2189 O 2494E-01 O 6981E-05 O 2494E-01 O 6981E-05 O 7797E-06 O 7797E-06 O 7797E-06 O 7797E-06 O 7797E-06 O 7797E-06 O 7797E-08 O 7797E-08	TIMATED ROOTS (1X+ 15Y+) TIMATED ROOTS (1X+ 15Y+) THEOLENY 1.000 0.7797E-06 3.0.1264 0.9427E-01 0.1247E-08 1.000 0.1287E-06 0.9427E-01 0.1247E-05 0.948E-01 0.1212E-04 0.9048E-01 0.2592 0.1288 0.2455E-04 0.34995 0.2000E-01 0.7132E-08 1.0000E-01 0.7132E-08 1.0000E-01 0.7132E-08	TIMATED ROOTS (1X+ 15Y+) O 5379 O 5379 O 5379 O 69427E-06 O 7797E-08 O 1264 O 9427E-01 O 1696E-05 O 1268 O 1288 O 1288 O 2495E-04 O 3494E-01 O 6981E-05 O 2495E-09 O 7372 O 2699E-01 O 7372 O 7472	TIMATED ROOTS (1X+ 15Y+) O.5370 O.5427E-01 O.5062 O.5062	TIMATED ROOTS (1X+ 15Y+) TIMATED ROOTS (1X+ 15Y+) DAMPING AMPLITUDE 0.5373 1.000 0.7797E-06 3.01247E-08 1.000 0.1247E-08 1.000 0.1247E-08 0.1264 0.9048E-01 0.126E-05 0.1288 0.2592 0.1288 0.2698E-04 0.3494E-01 0.2000E-01 0.7132E-08 1.005	TIMATED ROOTS (1X+ 15Y+) O.5370 1.000 0.7797E-06 3.135 1.000 0.7797E-06 3.135 1.000 0.7797E-08 1.637 1.000 0.1247E-08 1.637 0.2427E-01 0.1247E-08 1.637 0.2427E-01 0.2427E-08 1.637 0.2427E-01 0.2437E-05 0.2424E-01 0.2457E-04 0.2437E-05 0.2424E-01 0.2457E-04 0.2457E-04 0.2437E-05 0.2443E-01 0.2445E-03	TIMATED ROOTS (1X+ 15V+) 1 FRE(AUENCY DAMPING AMPLITUDE PHASE 3.135



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	9460E	_ •	0.3452		•	1	2.595	0.1772	-0.1002	1. Sec.	3.140	-0.4666F-0F
	AMPLIT! IDE	0.1751E-04	•	0.1166E-04	0.1475E-04	0.9396E-07	0.5126E-08		0.8302E-07			0.1400F-07
CORU	+ 147+; DAMPING	0.2040	0.36435-01	0.2191	0.1512E-01	•	0.2269E-01	0.7127E-02	0.1766E-01	0.5385E-01	0.6211	0.6570E-01
	IMATED ROOTS (1X+	0.7738E-01	9.1075 -	J. 1720	0.2993	0.3712	0.5534	9.689S		9.3808	1.276	1.002
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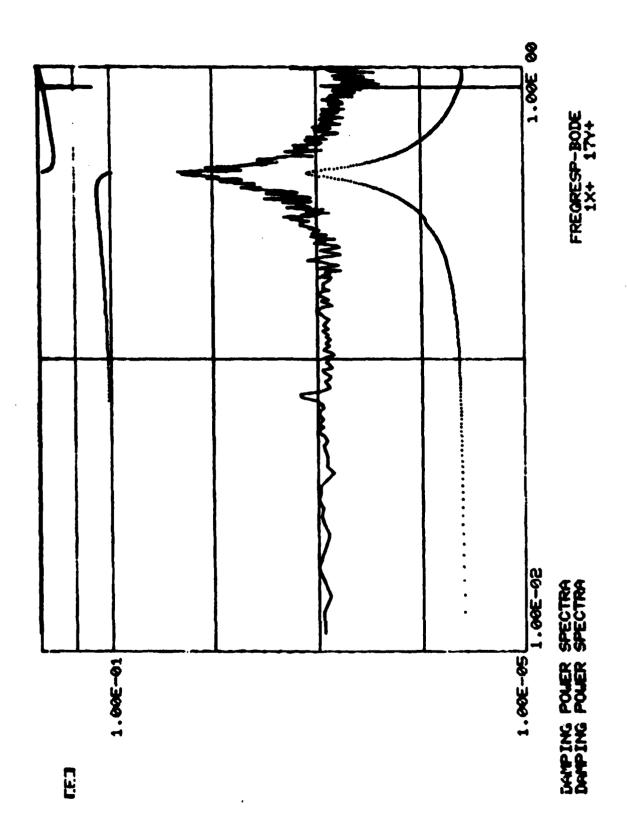


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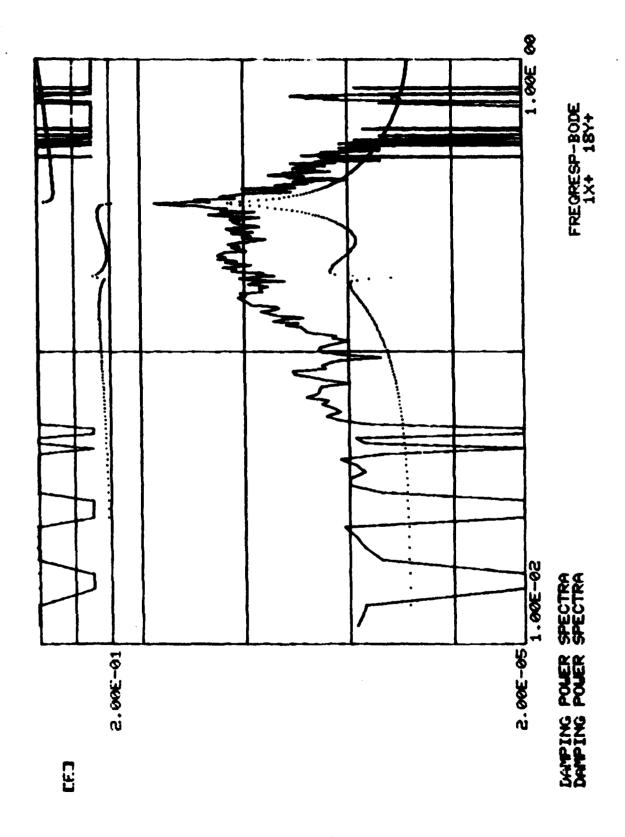
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	PHASE	0.3283E-06	-3.142	2.614	•	0.3513	2.458	-0.1011	0.4788	ව. ප ටි	2.465	2.692	-0.7568E-04
	AMPLITUDE	0.1239E-05	0.3133E-07	0.1578E-11	0.4552E03	0.4853E-07	0.1769E-05	0.1006E-04		0.2087E-09		0.5524E-07	0.3419E-07
(1X+17Y+)	DAMPING	1.000	1.000	1.000	•	•	0.1516	0.2468E-01		0.5708E-01	0.1515E-01	0.6476E-01	0.1693E-02
1X+			11										
ROOTS	FREGUENCY	9.4470	Ø.1121E-01	A.2001	0.1032	0.29%6	6.4194	0.4336	9.5374	0.6721	9.8568	0.9227	1.000
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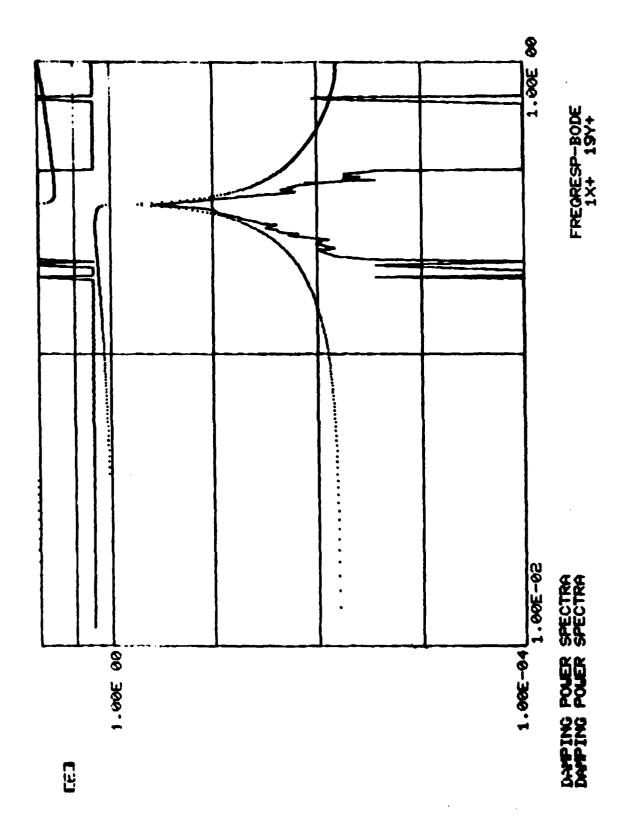


	PHASE 2.353 -3.026 0.3709 -0.1281 1.137 -0.2413	0.3753E-01 -1.087 -2.190
	AMPLITUDE 0.5118E-07 0.2604E-05 0.1588E-04 0.3807E-08 0.1982E-05 0.7473E-05	0.1463E-06 0.2545E-09 0.2645E-08
CORT	4 0000000 2011111110	0.4247E-02 0.4677E-01 0.2827E-01
	D ROOTS (1X+ REQUENCY 0.1117 0.1812 0.1907 0.3620 0.3660 0.5080	. 7431). 7681). 8164
	ESTIMATED PRODUCT FREE SE S	



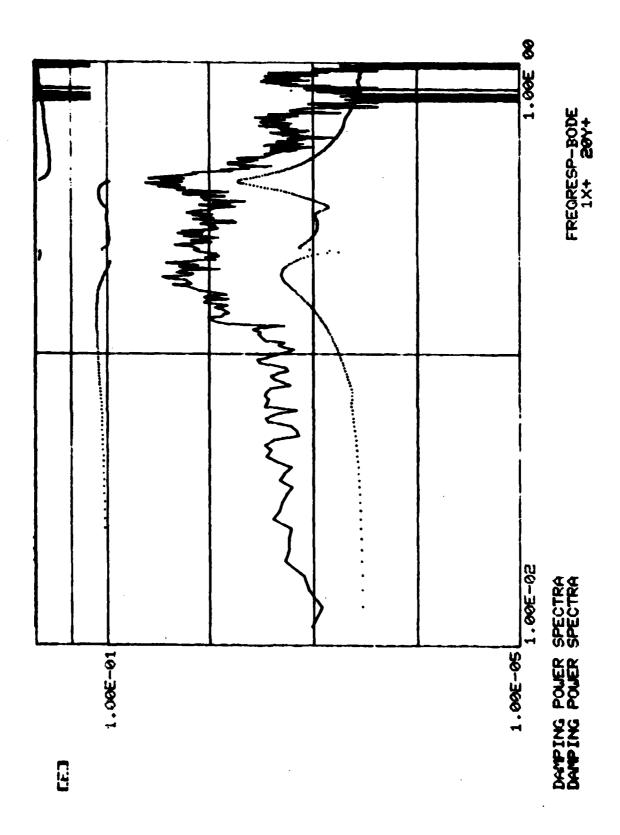
F-18-B

	£	-3.103 0.8744	-2.623	1.829	-0.1196	2.941	-3.123	2.279	-0.1983	2.599	-2.949
	AMPLITUDE	0.9115E08 0.8691F07	0.1181E-04	0.2094E-03	0.1647E-02	0.5032E-08	0.1059E-05	0.3517E-06	0.1407E-05	316	0.4123E-10
CORT	197+) DAMPING	1.000 0.8537F-01	2618	ø.1243	0.1255E-01	0.2151	0.8262E-01	0.1263E-01	0.3942E-02	0.6189E-02	0.6466E-01
	ITED ROOTS (1X+ FREQUENCY	0.5327E-01 8.2183	Ø.0400	9.3966	Ø.3262	0.3624	0.4290	0.7451	0.7527	0.7964	1.002
	ESTIMATED POOT FR	ڻ بھ	i (in	ţ	ហ	ů,	۲۰-	00	O)	10	11

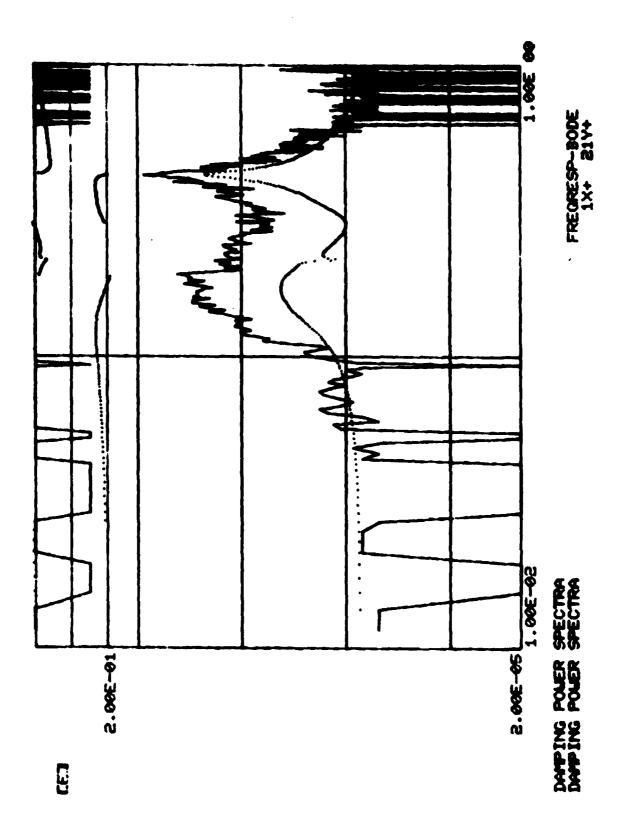


F-19-B

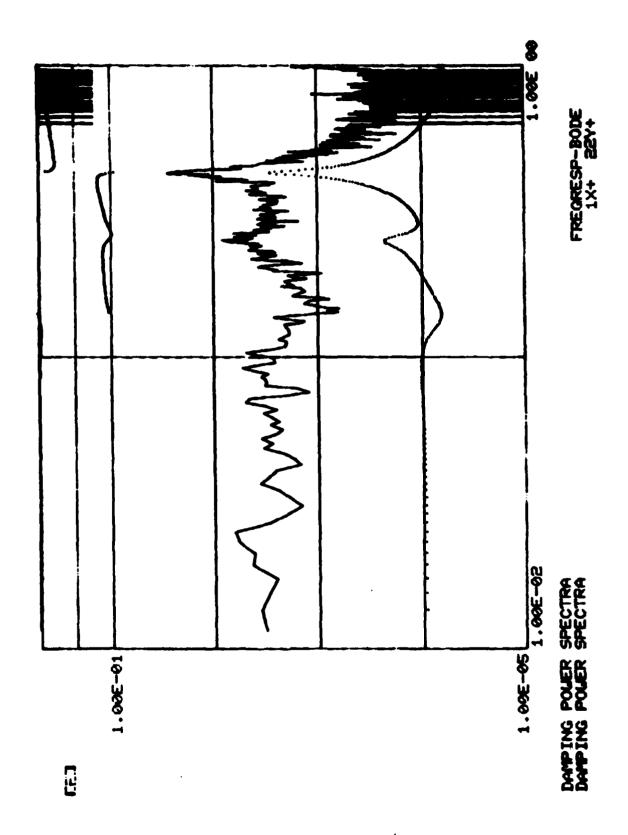
	PHASE	-1.484	0.2602	1.936	-1.334	-0.1400	173	-0.2040	-0.5883	-0.4651E-01		
	AMPLITUDE	0.1511E-06	⊘.3294E−04	9.2860E-05	•	0.4802E-04	0.1466E-06	•	0.2938E-09	0.4188E-06	7	
30×+)	DAMPING	0.8137E-01	0.1354	0.1751E-01	0.4606E-01	0.3399E-01	0.7364E-01	0.5630E-01	0.5732E-01	0.2257E-01	9.9573E-02	
ITED ROOTS (1x+	FREGUENCY	0.7152E-01	0.1893	ø.2278	0.3114	લ. ૩૭ ૦৪	0.4136	0.6378	0.7221	0.865 2	0.9101	
ESTIMATED	<u>ان</u> ان:م	₹'	ณ	(7	4	ហ	ဖ	۲	œ	O)	10	



	PHASE	2.100	-0.1956		2.018	-0.1016	-0.1437	-2.030	-2.394	9.7982	-0.5952E-03	-0.7184E-00
	AMPLITUDE	0.2478E-04	0.7979E-04	9.3261E-05	0.1136E-04	0.1202E-03	35400	0.7492E-06	0.2490E-07	0.1192E-06	0.6427E-11	0.1125E-10
1X+ 01Y+)		0.2049	0.1796	0.1727E-01	0.1418	0.1742E-01	0.1372E-01	0.1091	0.8718E-03	0.3461E-02	0.1610	0.5865
J	•	414	80£	145	3325	. 4206	331	883	220	3238	.013	SS
ESTIMATED ROOTS	POOT FREQUENC	 9.1	2 0.1805	3 0.2145	4 0.3	5 0.4	0	7. 0.6		6	+	-
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1.636 1.5869 1.5869 1.3891 1.5869 1.3891 1.636	0.2997E-05 2.758
AMPLITUDE 0.8635E-10 0.1047E-05 0.1166E-05 0.2328E-05 0.1095E-04 0.6327E-07 0.2855E-12 0.1520E-07	0.1839E-11
1X+ 22V+) DNMPING 0.8826 0.2459 0.4639E-01 0.4253 0.2938E-01 0.4230	9196E
TIMATED ROOTS (7. FREQUENCY 8.1093 9.1253 9.2526 9.290 9.5123 9.5123 9.5842	1.004
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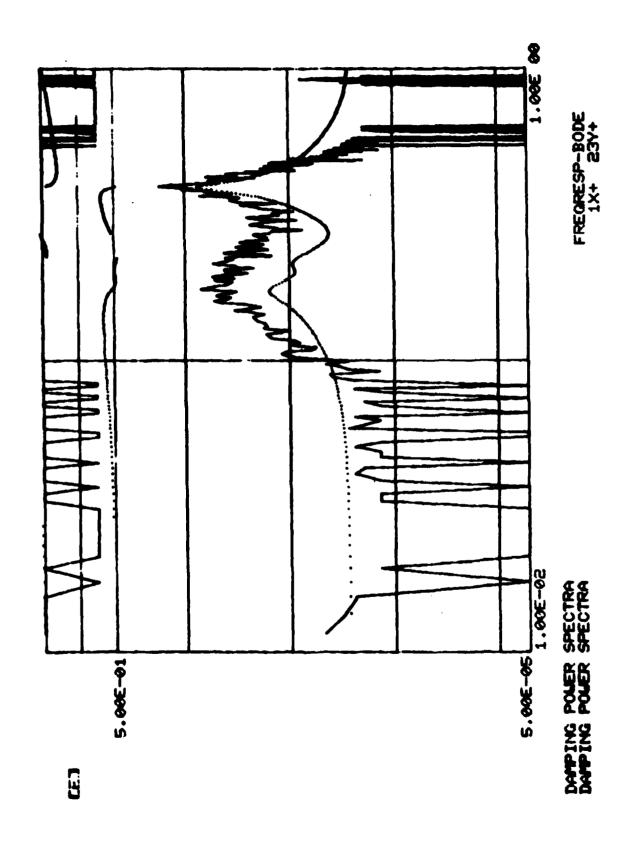


F-22-B

BLOUGH

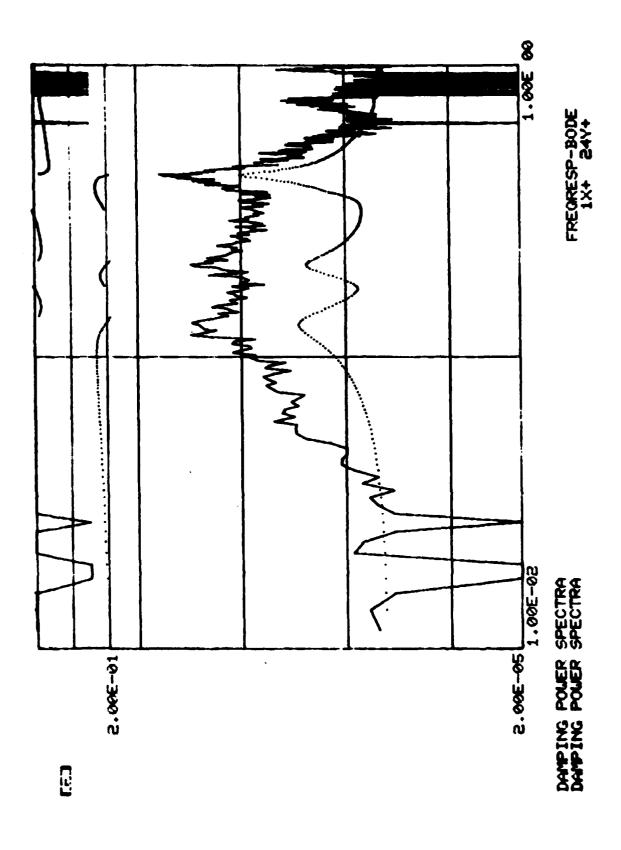
PHRSE	2.345 0.77435-01	0.2465E-01	-1.893	0.8326E-01	-2.159	-0.3166	-2.143	1.605	-0.1865
AMPLITUDE	0.9238E-05 0.1227E-03	7.378E	0.1863€-0 5	0.5114E-03	0.6964E-04	0.4137E-08	.8653.	. •	0.3168E-06
	6.8971E-01	0.9195E-01	9.6879E-01	0.2325E-01	0.1070	0.5747E-01	0.1390E-01	0.2204E-01	0.3424E-02

MATED ROOTS FREGUENCY	0.1753	9.2172	9596	0. 35CS	6.4655	5.00.0	8.504C	8.8048	9.5210
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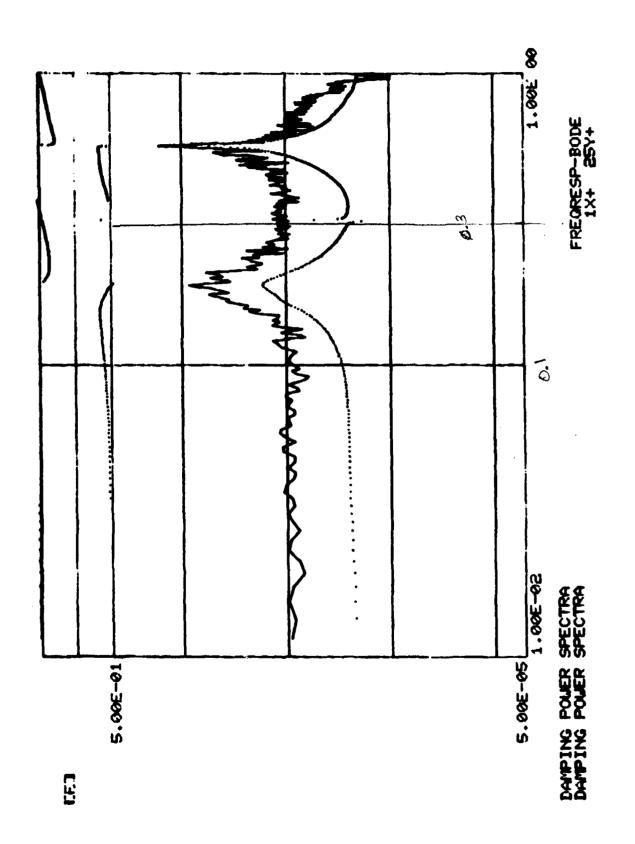
F-23-B

	PHASE -0.6582 0.8417E-01 0.3804 -3.053 -0.1955 0.3896 -1.630 -1.576
	AMPLITUDE 0.1263E-06 0.2375E-04 0.5326E-05 0.5710E-04 0.8044E-05 0.7127E-07 0.7206E-06
HEOLOTE	1X+ 24V+) DAMPING 3.2030 0.1012 0.7346E-01 0.1842E-01 0.3497E-01 0.3497E-01 0.4760E-01
	FREGUENCY 0.1247 0.1247 0.1305 0.3575 0.4470 0.5632 0.7767 0.9696
	R (2) (G (2) 4 (N (2) C (2) 2) 2] を (



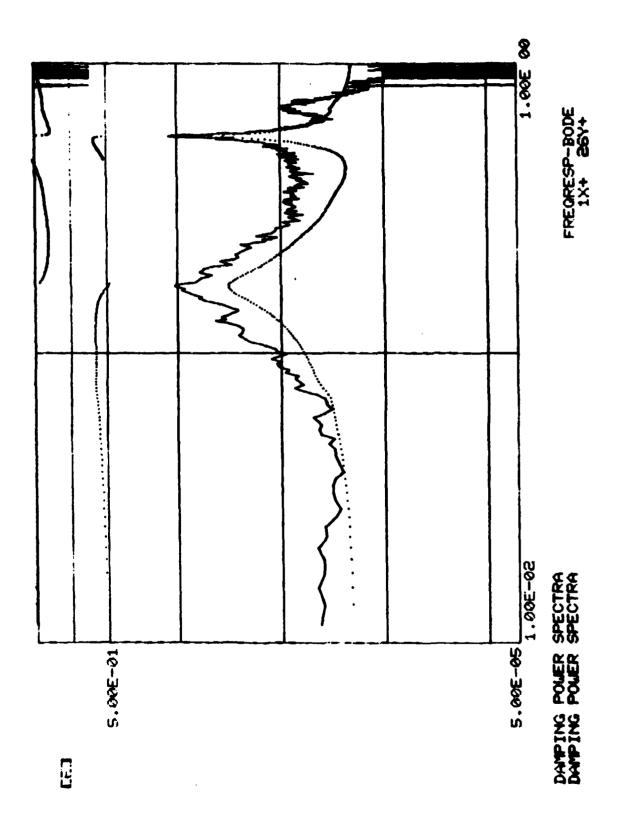
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PHASE	-0.6415E-05	-0.2733E-02	1.771	-0.1154	-0.4971E-02	-0.8606	
AMPLITUDE 0.230EE-84	0.5671E-04 0.2496F-04	0.1324E-03	0.6232E-08	0.2379E03	0.5104E-05	0.3374E-05	0.4739F-96
1X+ 25Y+) DAMPING	1.000	0.6891E-01	0.1291 0.6958F-01	0.4828E-02	0.5182E-01	. 4858E	0.1538E-01
D ROOTS (1) REQUENCY 0.3133E-01	0.7840E-01	0.1394	0.5443	5659	7142	.8373	9536
MATED R FREG	90		6.00	6	Ġ	Ġ	Ġ



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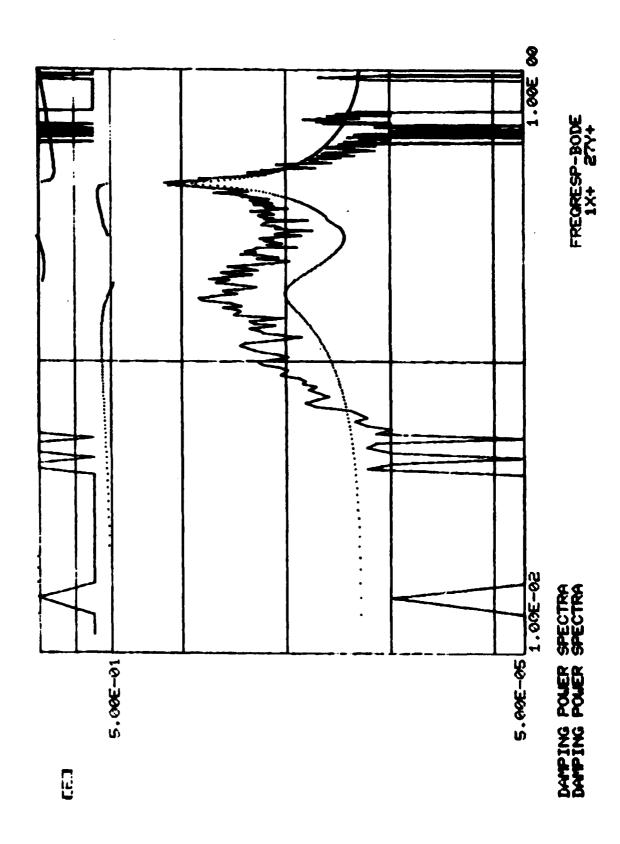
PHASE	8.860 9.00	0.63845-01	586	-2.787	-2.172	-0.2730E-01	-0.2744	-0.1079	7
AMPLITUDE	0.2949E-05	0.3654E-03	-3565E-	.8216E-	1080E-	1745E	.2782E-	.4031E-	0.1480E-06
99	ອ.1 ອ.ນ ລູດນ ໝູ້ວິດນ	•	0.2019	Ξ,	•	ישמטייי	.1700E-	0.3203E-01	0.1884E-01
MATED ROOTS (1X+ FREQUENCY	8.1435	0.1703	2.0887. 0.0887.	0.00 0.00 0.00	7000 C	•	00000	0.0000 00000	Ø. 588
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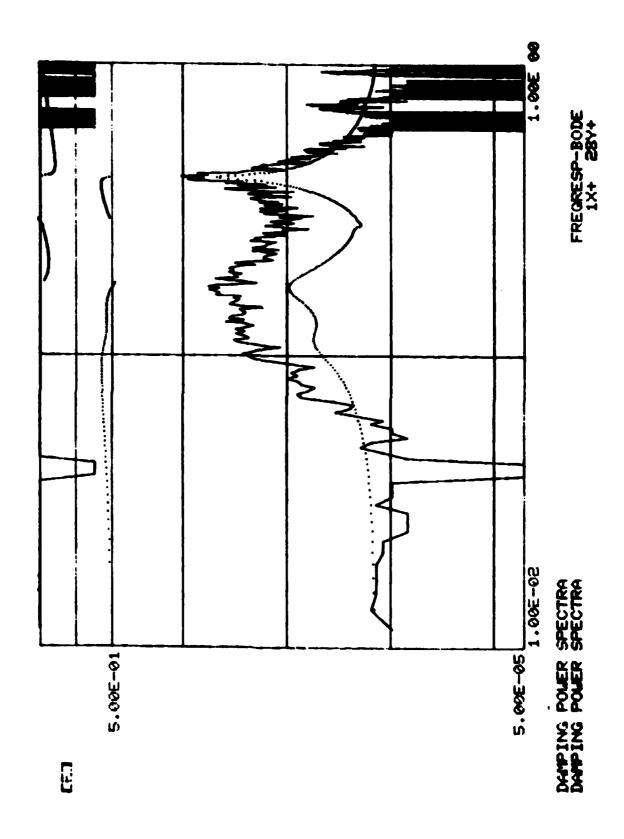
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	PHASE	3.140	-0.4981E-02	-0.2127	0.8456E-01	1.189	-0.4453E-01	χu	2.836	์เน	· LU	0.562GF-02
	AMPLITUDE	0.5384E-04	0.6927E-07	0.1331E-06	0.1613E-03	0.3115E-05	0.3519E-03	0.1192E-04	0.2570E-05	0.2113E-05	0.5040E-10	0.2343E-06
+ 274+)	DAMPING	1.000	1.000	0.3885	0.1469	0.3589E-01	0.1432E-01	0.1618	0.8577E-01	0.3569E-01	0.1387	0.3286E-02
MATED ROOTS (1X+	FREGUENCY	6.2886	_	ତ .1 ୬ ର	•	0.3୭୧૩	•	0.4732	•	•	0.7284	•
ESTIMA		~ ·	ល	m	4-	LO	Q	1-	9 1)	o O	10	11



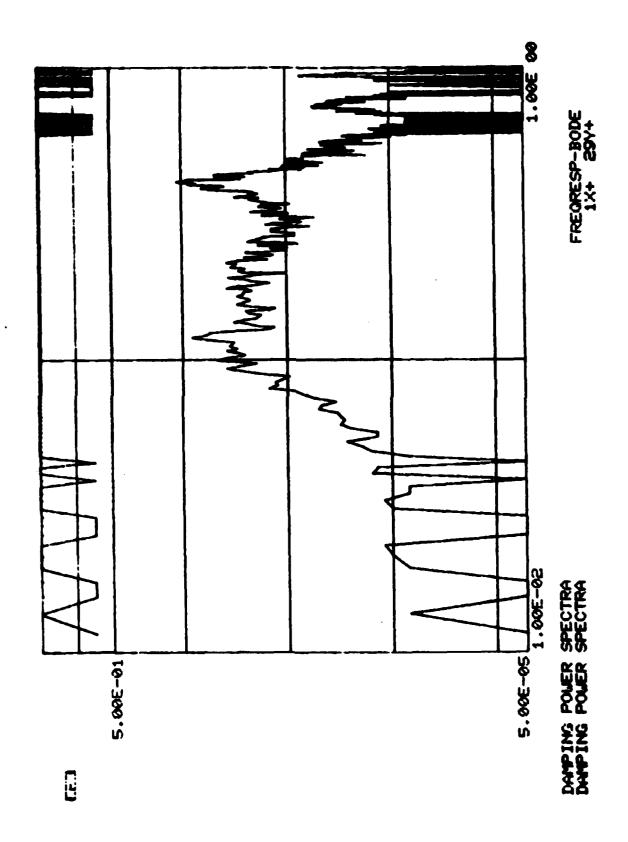
F-27-B

	PHASE	-0.4574F-03	0.7363	0001.0 000000	-2 000 C-		- 6.5500 6.75000	-0.4238 -0.4238	•	ָ ֓֞֝֞֝֞֝֞֝֝֞֝֞֝֝֞֝֞֝֞֝֝֞֝֝֞֝֝֡֓֞֝֝֡	. (0.1000	3.141
	AMPLITUDE	0.3816F-05	0.3406F-04		15045	1 U	0.1623F103		0.4136F-05	0000	10 - 0 - 0 - 0 - 0 - 0 - 0 - 0 - 0 - 0 -	- 27771	0.8715E-08
+ 287+)	DHIMHO	1.000	0.1571	0.1109	0.2330F-01	0.51.00F-01	0.1282F-01	6453E	0.4777E-01	0.7068F-01	D. 1006F-02		0.1585E-01
D ROOTS (1X+	CAPIC	9.7227E-01	0.1120	0.1734	v.2791	0.4015	0.4078	0.5518	0.7307	6. 7339	0.9412		1.000
ESTIMATED	ũ.							C-					77

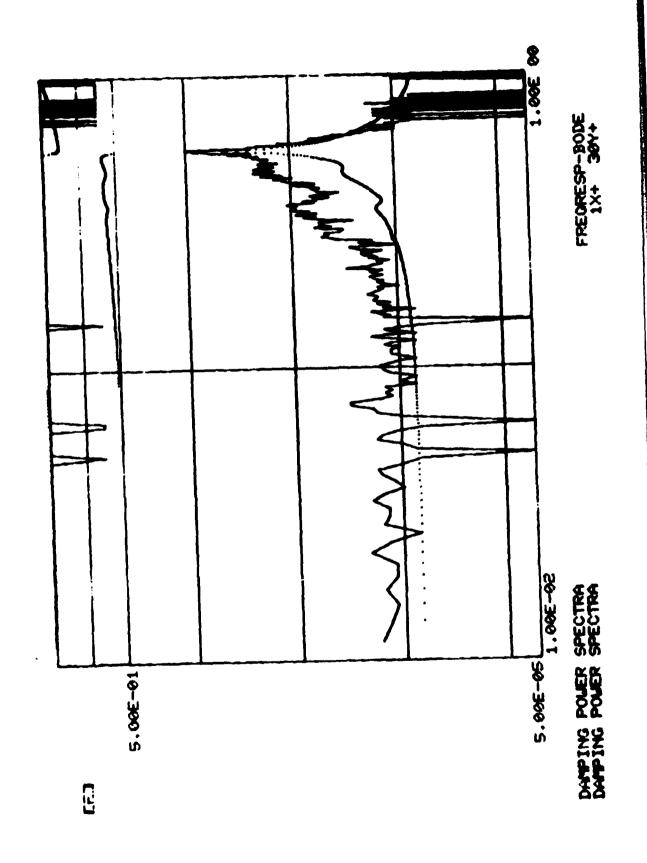


F-28-B

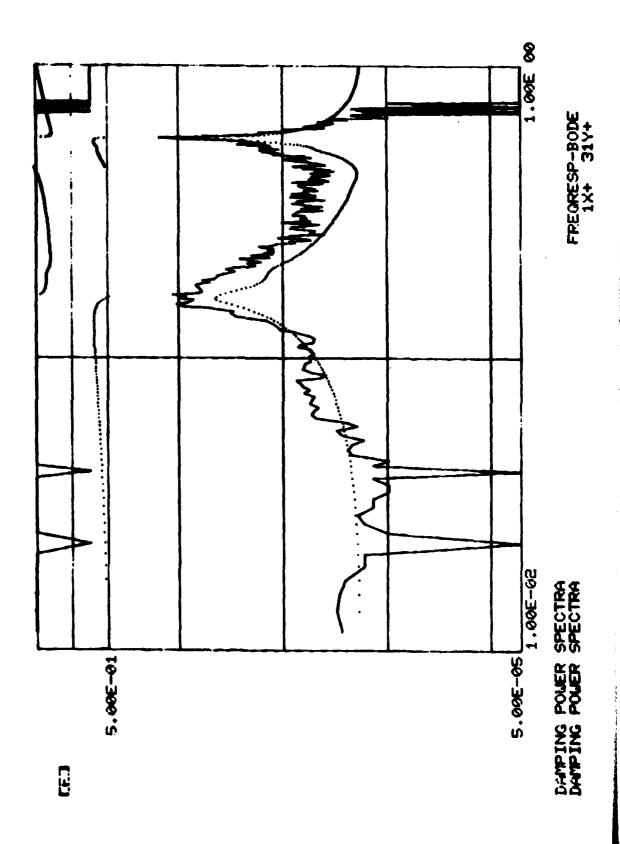
PHASE -0.3127E-01 0.1577E-07	0.3864 -0.2560 2.492	
AMPLITUDE 0.3145E-08 0.1344E 07	0.5124E-64 0.5124E-04 0.1003E-05 0.2423E-03	0.1022E-04 0.6716E-07 0.1404E-05 0.1070E-06 0.5188E-06
H. 297+) DAMPING 1.000 1.000	0.7412E-02 0.7412E-02 0.2275E-01	0.3302E-02 0.2241E-02 0.2962E-01 0.2835E-01 0.4527E-02
MATED ROOTS (1X+ FREGUENCY P.6444E-01 0.8995		0.4297 0.5803 0.7416 6.8324 0.9428
⊢ (-	4. N. O.	œ a a -1



2.177722	-0.8462 -0.8462 0.7090E-04 -1.739
AMPLITUDE 0.3356E-06 0.2825E-09 0.1583E-06 0.3286E-06 0.4527E-05 0.2724E-04 0.3455E-07	0.5708E-08 0.5984E-07 0.5570E-11
}	38.85
Wese as a sec	0.8120 1.001 1.004
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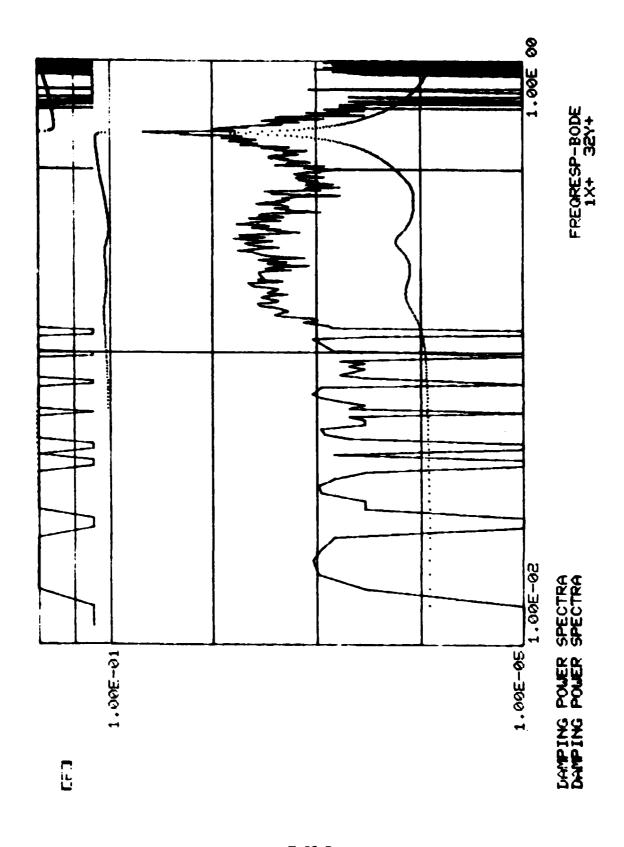


	PHASE	2.083 1.083	-6.7732	0.9315	1.51	-0.1919	2.827	Si Si	0.7178
	AMPLITUDE A 19095 OF	0.2363E-03	0.4587E-04	9.1203E-96		175151	.9816E	X	9.180₹-08
1X+ 31Y+)	DAMPING 0.1219	0.4601E-01	9.7168E-01	1 4 8 8 7 4 4 4 E	0.23406-01	1556E	1241	58E	0.E33EE-01
J	>								
ATED ROOTS	9.1223	9.1602	8.1981 8.9307	0.4022	0.5214	0.5654	9.6810	0.0350	•
ESTIMATED	 } L	ณเ	") †	. n.	Ø	4	x o	9	



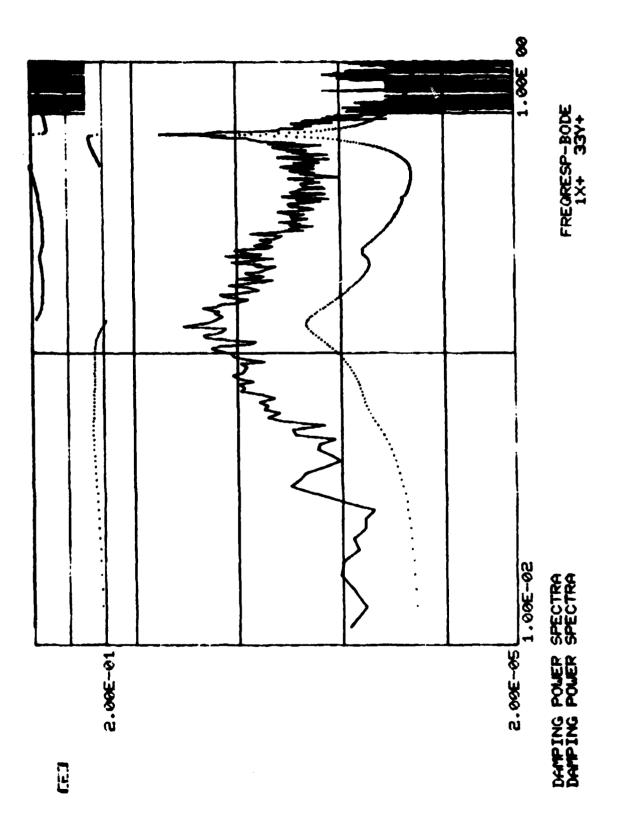
F-31-B

PHASE	0.2292E-05 -3.142	WI	ii 4	-2.655 -0.6959	י אי	-0.9352 0.000	0.7029
PLITUI	0.04040E-05	9310E-	1758E-	0.6377E-06 0.1807E-07	1790E-	Ň,	769E-
1X+ 32Y+) DAMPING		0.1733 0.3447F-01	1519	0.1428 0.5615E-01	6254E-	0.5173E-02	1889
MATED ROOTS (FREWENCY 0.1488	6.1958	ช. 1546 ศ. ส398	ø.2832 ø.2832	0.5030 0.6030	90,	0.7965	0.9253
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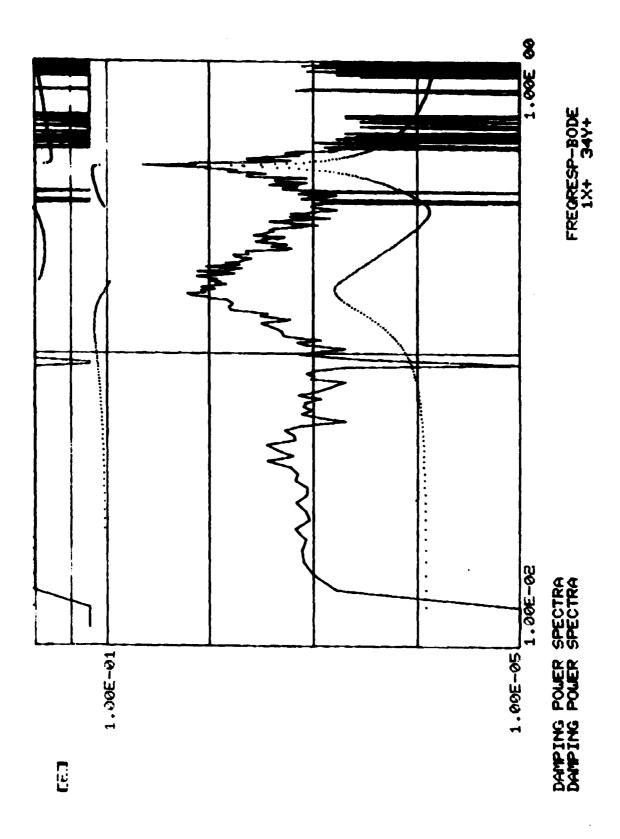


F-32-B

PHASE 1.489	4 0.3651E-01 -0.2597 -0.9551	-0.3385E-01 -1.340 1.693 0.8140E-01 -0.8202
PLITUDE .1336E-09	0.2274E-04 0.2828E-05 0.3784E-07 0.2430F-07	1905E-04 7688E-08 7851E-09 3051E-07
က်င	0.1224 0.73495-01 0.83305-02 0.31175-01	0.4955E-02 0.5866E-01 0.3759E-01 0.4498E-02 0.6692E-01
IMATED ROOTS (1X+ T FREQUENCY 0.6421E-01	6.1455 6.3439 6.4413	6.5540 6.5910 6.7746 8.8987 6.9389
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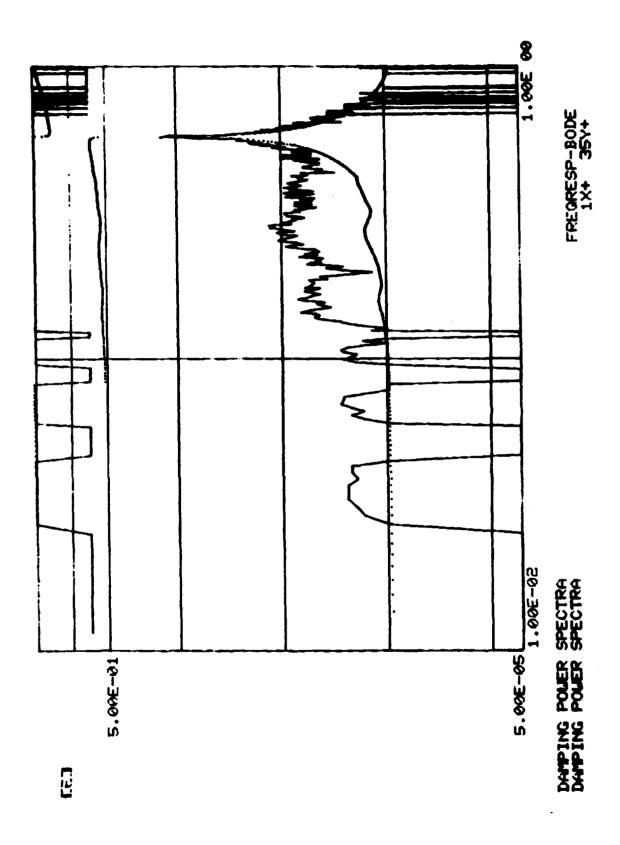


	PHASE	3.140	-1.958	0.4553	-1.976	ප. 362	-0.363 2E-01	-2.747	-0.3478	0.9337E-01	1.441	3.139
	AMPLITUDE	0.1011E-06	0.5849E-05	0.1058E-04	0.6647E-07	0.8730E-06	0.1080E-04	0.1245E-11	•	7	•	0.9949E-10
(+ \A\\)	DAMPING	1.000	0.3937	0.1307	0.8120E-01	٠	0.5237E-02	0.2046	0.3867E-02	0.3890E-02	0.600SE-01	0.4252E-01
Ш	FREGUENCY	0.5915E-03	ଜ.1605	0.1633	ø.2213	O.3685	Ø.4395	0.4859	o.6522	0.7986	0.9108	1.001
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F-34-B

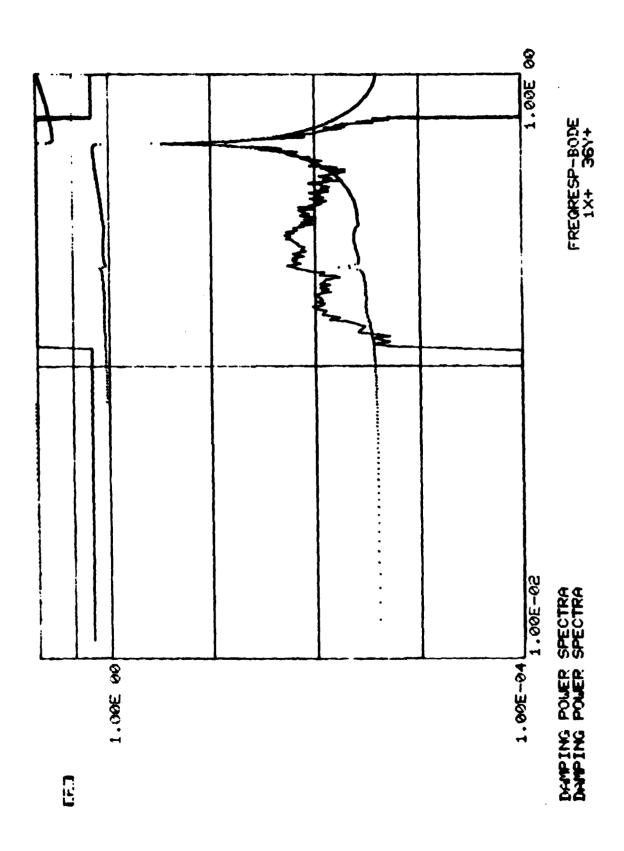
	PHASE	-0.5563E-05	3.142	0.1897	0.4699	2.582	-1.401	1.846	-0.1612E-01	-2.295	2.320	0.1345E-03	Ο,
	AMPLITUDE	0.7171E-05	0.4216E-06	0.1804E-05	0.1542E-04	0.3661E-05	0.1558E-05	0.8193E-06	0.2121E-03	0.1957E-05	0.6774E-07	0.3000E-07	0.1729E-10
《十天以四二十天》		1.690	3000:1	3.1032	0.1545	0.8548E-01	0.3591E-01	0.3690E-01	0.4053E-02	0.1893	0.1214E-01	0.4894E-02	0.7022E-01
MATED ROOTS (1X+	FREQUENCY	0.1770	0.2586E-01	0.1587	0.2746	Ø.3335	0.4170	6.5714	0.5760	•	0.7568	1.000	1.002
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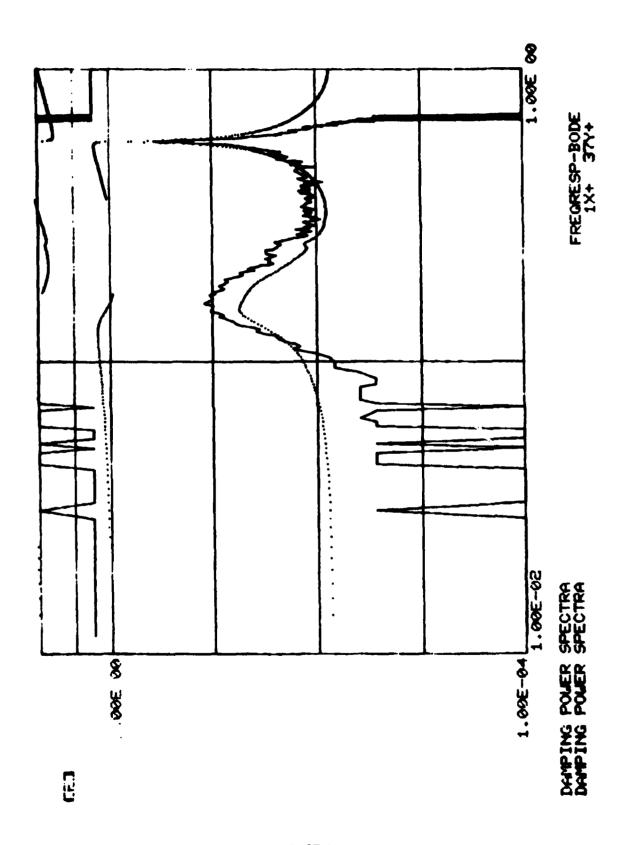
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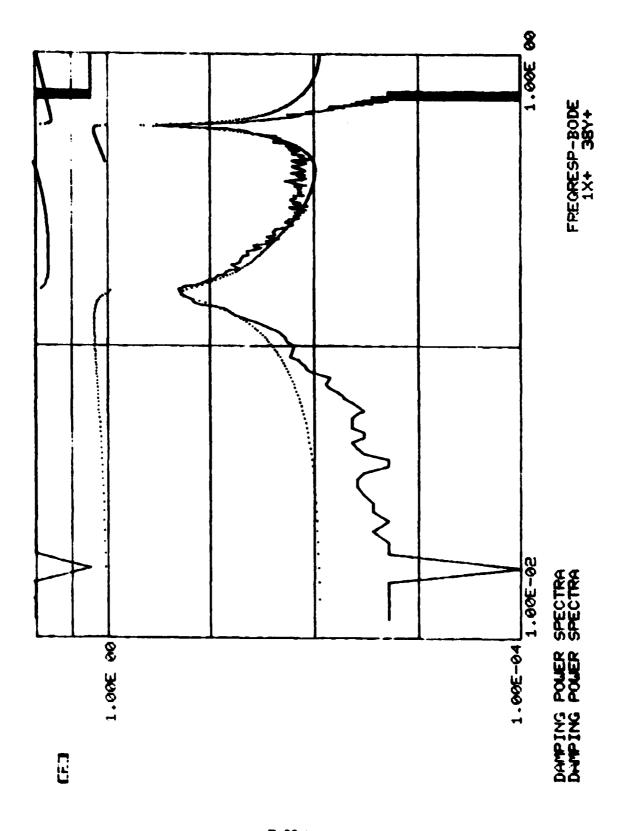
	PHASE	8968	0.6333	139	· N	-2.763	-1.211	118	0	474	778
	AMPLITUDE	. 4329E	0.3026E-05	3730E	1184E	2532	0.1077E-05	0.5942E-03	3063E	0.1138E-05	0.1388E-08
+ 367+)		0.1887	0.7493E-02	17	0.2247E-01		0.1545E-01	0.3627E-02			0.7668E-03
1X+											
TED ROOTS (FREGUENCY	9.154S	0.2187	0.8835	0.3048	0.4615	9.5382	0.5798	Ø.6982	0.7131	Ø.9204
ESTIM		-1	נח	ניח	4	វេរ	Œ	٢-	زی	o O	01



	PHASE	3.140	0.9253	-0.8685	-6.3252	0.9460	2.868	-0.2109E-01	2.801	-3.051	1.413	-3.073
	AMPLITUDE	0.1225E-05	0.4472E-03	0.4723E-03		0.3861E-04	1623E-	0.1231E-02	0.3670E-05	0.5389E-05	0.2165E-08	0.4777E-09
3774)	DAMPING	1.000	1073	0.1523	0.2470E-01	0.3729	0.7230E-01	0.4329E-02	0.3237E-01	0.8341E-01	0.5606E-02	0.3064E-02
. 1X+		01										
STIMATED ROOTS (FREQUENCY	0.3433E-01	0.1473	0.1810	9.2526 9.2526	Ø.3313	0.4253	0.5672	Ø.5695	0.6632	0.9187	1.000
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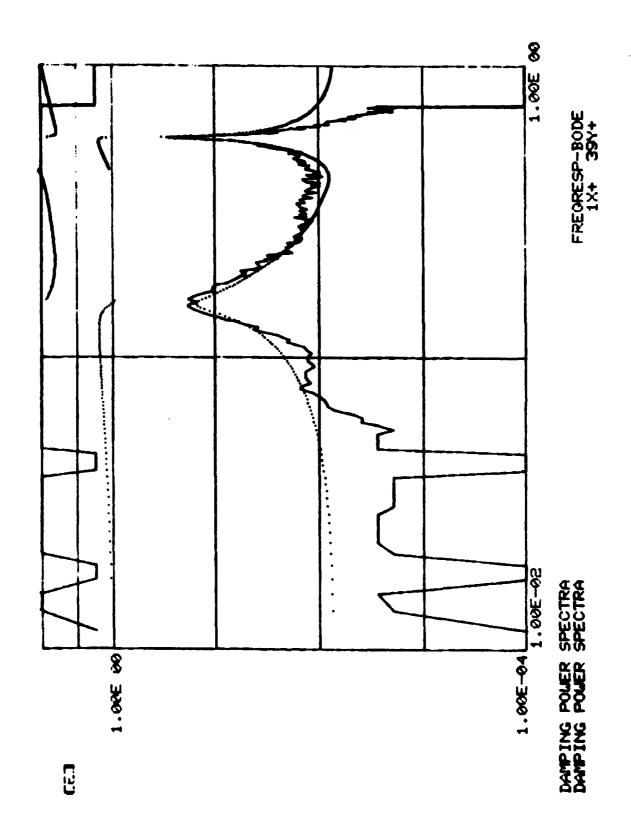


	PHASE	-0.1383F-03	1.755	0.1402	· ru	-1.090	-1.340	α α	2.41	U	4	• (
	AMPLITUDE	0.1007E-03	0.3154E-06		•	7093E-	0.6584E-08	1045E-	0.2251E-05	0.2452E-07	0.4723E-06	.5302E-
1X+ 38V+3	DAMPING	1.000	0.0445	0.5208E-01	0.1955	Ø.1123	0.1011	0.5139E-02	0.7877E-01	0.2014E-02	Ø.1293	0.4673
Ş.	FREGUENCY	©.176±	0.1584	0.1515	A-2372	9.3895	ø.5062	0.5671	O.6512	0.7385	יָנו	1.131
ESTIME	٦. ٢. ا	+ 1	เล	เก	7	ល	G	[-]	ຫ	on.	<u>ئ</u>	Ŧ

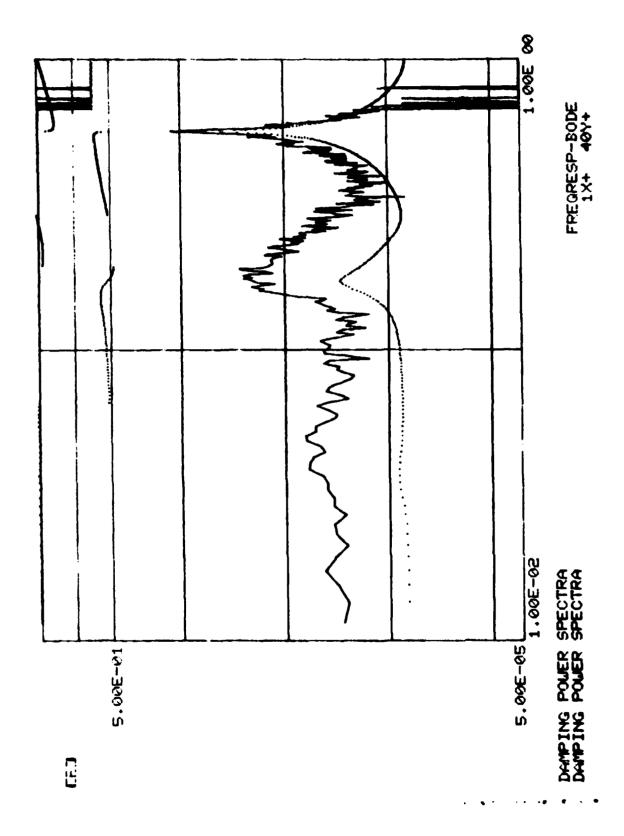


F-38-B

	PHASE	0.8336	0.3047	-1.468	0.2529E-01	-1.840	1.828	-0.3674E-01	2.858	-e.348	3.137	0.9955E-03
	AMPLITUDE	0.3947E-06	0.1013E-02	0.2860E-03	4	9.1671E-06	0.1391E-04	0.8025E-03	0.4347E-06	0.1814E-09	0.3647E-08	0.1271E-05
4 39∀+)	DANGMEN	0.80 <i>8</i> 7	0.6183E-01	0.1757	0.1369	0.6416E-01	0.1376	0.5784E-02	0.6076E-01	0.1745	0.3901E-02	0.2473
ESTIMATED ROOTS (1X+	FPEQUENCY	ਲ• 126 2	ਐ.1522	ტ.1829	e.3367	0.4854	0.5598	0.5666	0.7471	6.8903	1.000	1.032
ESTIMA	けんりつ	•	្រ	ា	7	ហ	Q	2	တ	יני	10	11



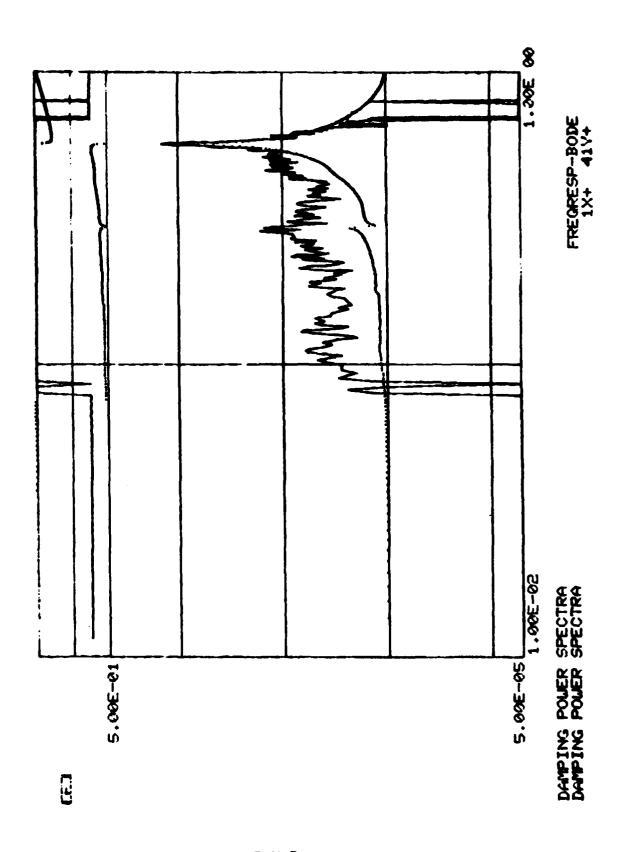
	PHASE	0.17.0	2 . F.3.		10000		٠	-0.4884E-02	-1.902	100	יים מיים מיים מיים	0.1E10	0.1468E-03	-2.141
	AMPLITUDE	0.7807E-06	0.1893F-04		る。いいといい。			0.1.380E-03	0.1268E-05	0.8121E-06	0.1040F-08	00 1000	٦.	0.1169E-07
407+3	DAMPING	C.2411	0.7059E-01	0.0399	0.7376E-01	0.452GF-01	0001007	0.10100	0.1274E-01	0.1152	0.2132E-01	4070	0.1010	0.5141E-01
STIMATED ROOTS (1X+	かいままで	6.3580E-01	0.1712	0.2153	P. 2811	0.5112	9. TABBE	0000	8.59.08	Ø.6766	0.7993	1.008		1.661
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F-40-B

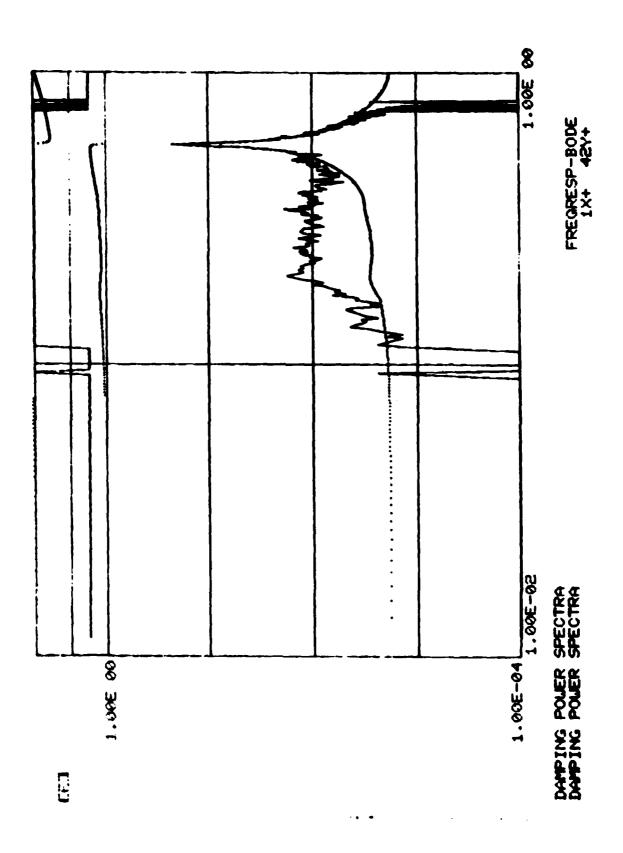
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PHASE 0.3192 1.905 -0.7606 0.5451E-01 0.8621 0.1052 -0.2798E-01 -2.614 -1.864
AMPLITUDE 0.1234E-05 0.1922E-06 0.2057E-05 0.3032E-08 0.3332E-08 0.6439E-06 0.1836E-10
1X+ 41Y+1 DAMPING 0.1823 0.2119E-01 0.9471E-02 0.1533 0.7077E-01 0.3873E-02 0.3873E-02 0.3873E-01 0.9401E-01 0.9401E-01
FRENIENCY 6.1092 9.1763 9.2959 6.3194 6.4573 6.5690 6.5690 6.5690 7.6004 1.0004
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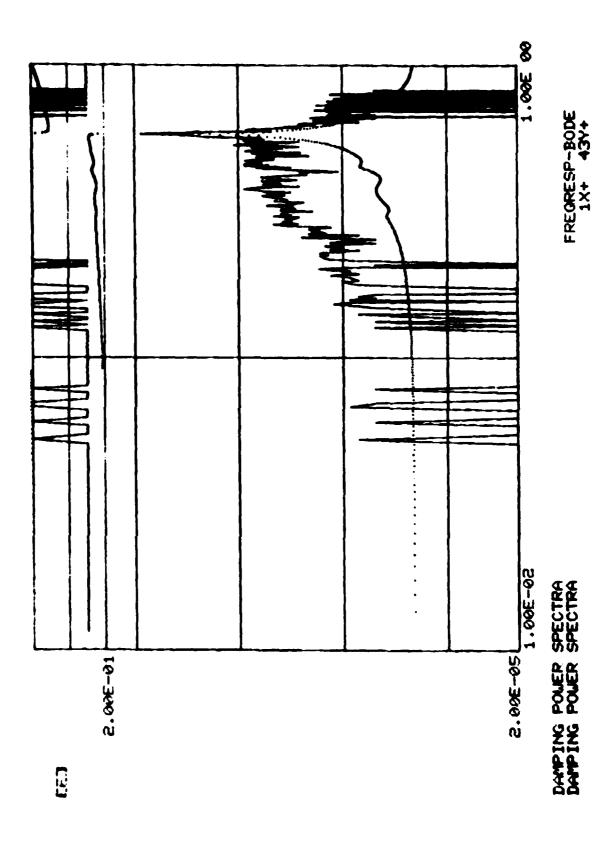
F-41-B

	0.7468F-07	3.02	7	1	-8-1938 BBBBB-8-	S S	5	-0.1012E-01	-2.655	-1.768	3.141
AMP TT IOM	1055E	ΙØ	-	5233E-	2177E-	4657E	3041E	4177E-0	1671E-0	.1294E-0	316
1X+ 42V+)	1.000	•			0.1867		0.4672E-01	.47	0.1323	ú	.812
_	Ø.4352	77	0.1963	ે. ટે8ટે6	0.3511	v. 4484	0.5483	Ø.5672	0.7451	0.7530	1.000
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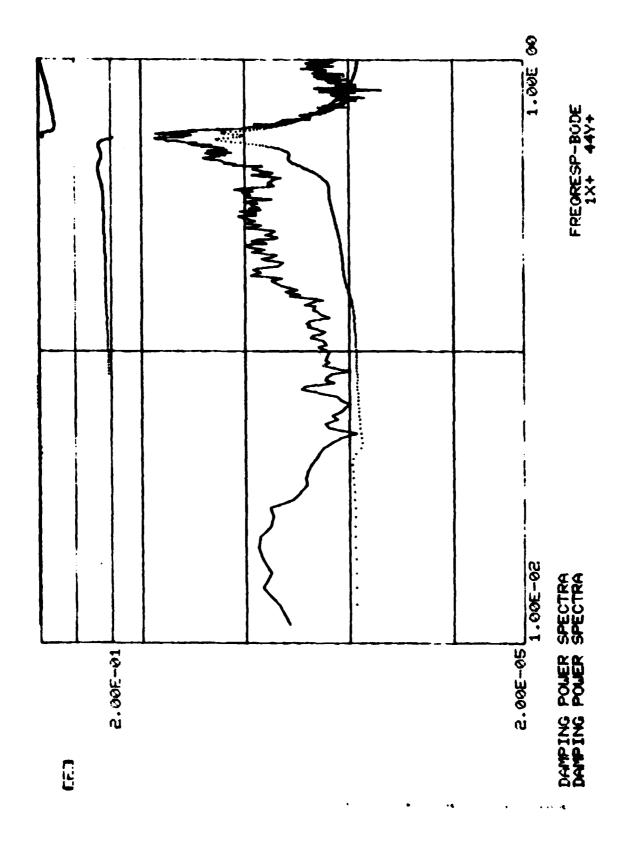
F-42-B

	0		-1.533	-2. G46		0.000	0.1315	\$50°+		0.1440	-0.4930E-01	-0.3373	ָ ֓֞֞֞֞֞֞֞֞֞֞֞֞֞֞֞֞֞֞֞֞֞֞֞֞֞֞֞֞֞֞	Ô	-2.752
	DATITE TAME	2 11 OUE	め・13/85-62	0.121SE-07	0.5246F-0C	10 1000	0.10/0E-03	0.0480E-05	0.4840F-07		4530E	0.5122E-06	0.1416F-00		0. 2489E-06
437+)	DAMPING	0.7745F-01) (- (1040L	0.4195E-01	9000F		0.3819E-01	0.4701E-01	מטיישכסטכ ש	10000	-	0.4954E-01	70.00	•
8	FPEQUENCY	© . 8738E−01	0.0400		9. 31.CS	o.3867	9.448E		v.5186	0.5816	يا	. ו	9. (831	0,70%;	,
FOTIMAT		ç. '	٢.,	; r	• ن	7	U	: 41	0 1	-	00	C	n (S	

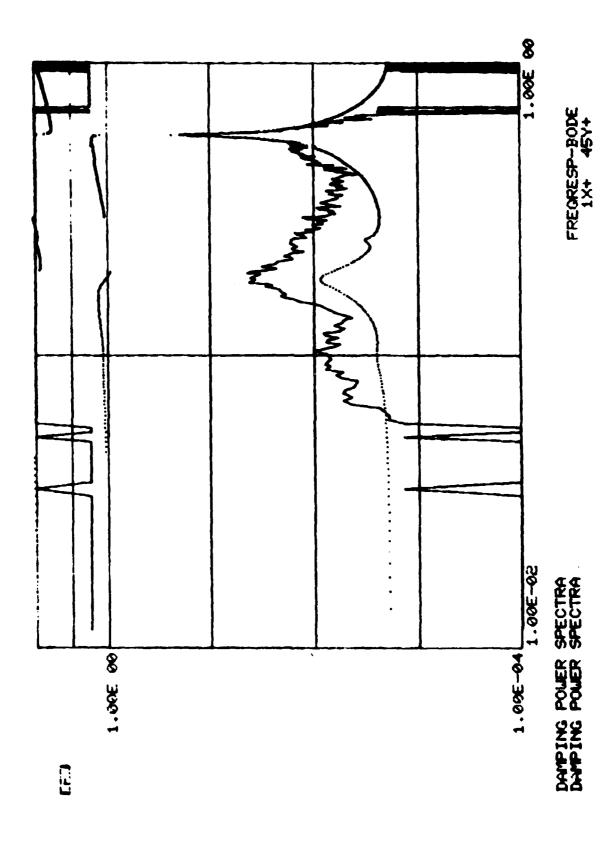


F-43-B

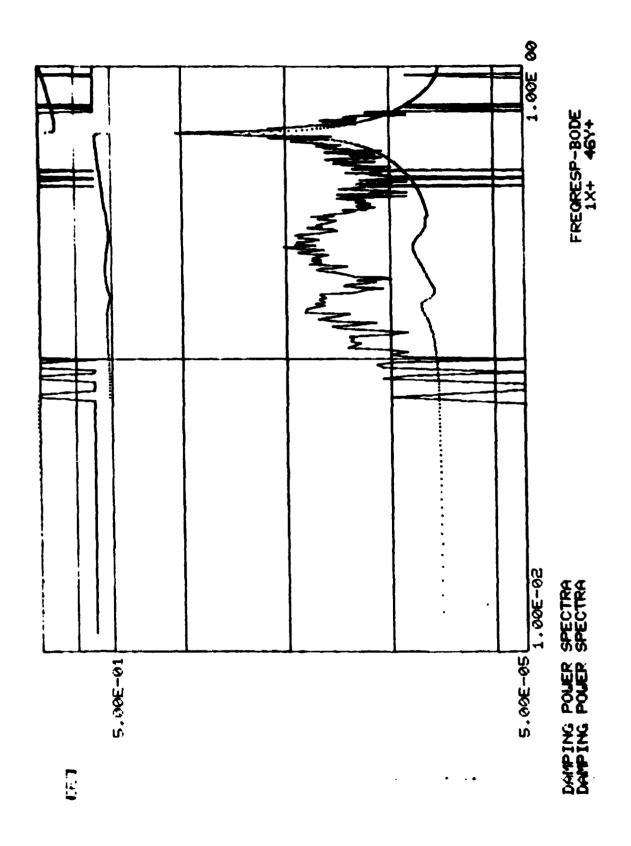
	PHASE	-1.547	1.644	-0.8891	-0.8943	6.5573	9.1625	-0.4434	-0.2649	-3.093	-0.3725F-05	0
	AMPLITUDE	0.5489E-06	0.3099E-05	0.1979E-06	0.1750E-04	0.3028E-04	0.9968E-04	0.6319E-04	0.2182E-07	0.4575E-07	0.3000E-05	0.1565E-09
4474	DAMPING	0.8152E-01	0.184∂	0.6662E-01	0.1489	0.5646E-01	0.1584E-01	0.1248E-01	0.1922E-02	0.1425E-01	0.1454	0.7593E-01
. 1X+		-01										
STIMATED ROOTS	FPEQUENCY	©. 453∂E−	Ø.1637	G.2982	ი. 3665	9.4558	ø.5320	0.56P7	બ. 7835	0.9780	1.011	1.003
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PHPSE	0.2567E-04	-0.2260	0.2185	0.1168	1.468	-2.007	-0.2281E-01	-1.582	-2.698	1.082	-0.3360E-02
AMPLITUDE	0.4375E-05	0.4429E-05	0.6977E-04	0.3751E-05	0.5455E-05	2275	0.3996E-03	9.6614E-06	0.8308E-07	0.6535E-07	0.1787E-07
45Y+) DAMPING	1.000	0.1632	0.7481E-01	0.3031E-01	0.5377E-01	0.2931E-02	0.3952E-02	0.3603E-01	0.3112E-01	0.2097E-01	0.7289E-02
X											
ESTIMATED ROOTS (4. 7953E-01	•	0.1827		0.4545	6.5210	9.5682	0.6410	0.7203	0.9471	1.000
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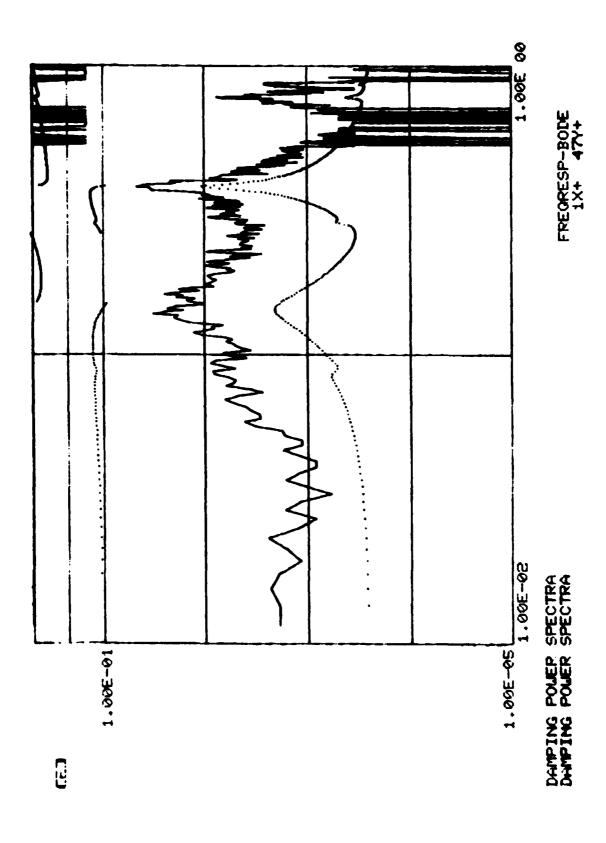


	PHASE	0.00	ממני פיי	J Ç	0.94730E-01	_	0.388	7	, K		j	יממטים.	0.1610
	AMPLITUDE	0.1894E05	9.1330F-0E	こうひん ロー	14.7.00	TT TCE	1	0.5455E-07	0.7939E-84	-8671F-	֓֞֜֜֜֜֜֜֜֜֜֜֓֓֓֓֓֜֜֜֜֓֓֓֓֓֓֓֓֓֓֡֓֜֜֜֓֓֓֡֓֜֜֡֓֜֓֡֓֡֓֜֓֡֓֡֓֡֓֡֓֜֜֡֡֓֜֡֓֜		0.1550E-08
1X+ 46Y+)	SNIGHTO	9.3638	0.6666E-01	0.1243	0.198SF-01) L	֡֝֝֝֝֝֝֝֝֝֡֝֝֝֡֓֓֓֓֓֓֓֓֓֓֓֓֡֓֓֡֡֝֡֓֓֓֓֡֓֡֓֡֡֡֡֓֡֡֝֡֡֓֡֓֡֡֡֡֡֓֡֓֡֡֡֡֡֡	ហ	0.3365E-02	6.1200	0.1390F-02	֓֞֜֜֜֜֜֜֜֜֜֜֜֜֜֜֜֜֜֜֜֜֓֓֓֓֓֓֓֓֓֓֓֓֓֓֓֓	0.5613E-06
POOTS (ს (1 ლ	7 '	7	•	Ø.3044	6.4308	. L	ນ (ກ (v.6607			
ESTIN PORT	• •	ſ	u f	ej i	1	ហ	U	າເ		ומ	וכו	40	,



F-46-B

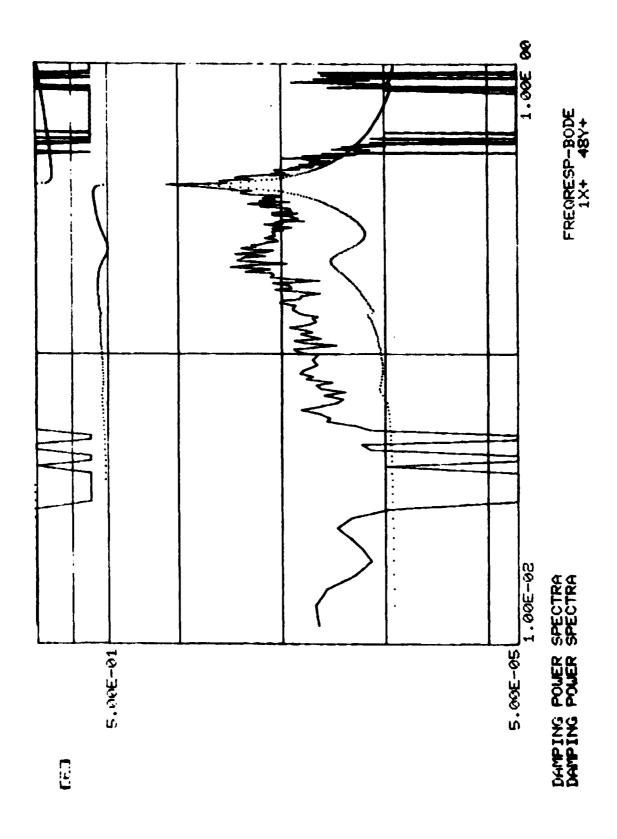
PHASE -0.8084 0.1554 0.8170 1.409 -2.676 -2.539 2.781 -0.7217E-01
AMPLITUDE 0.5376E-06 0.1626E-10 0.4000E-06 0.3936E-04 0.9353E-06 0.4405E-07 0.9678E-06
477/+) DAMPING 0.5350E-01 0.1106 0.7748 0.1549E-01 0.1300E-01 0.2777 0.5633E-01 0.5633E-01
MATED ROOTS (1X+FPEDUENCY 9.8731E-01 9.1439 0.4159 0.2859 0.3823 0.5877 0.6860 0.7785 0.8656
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F-47-B

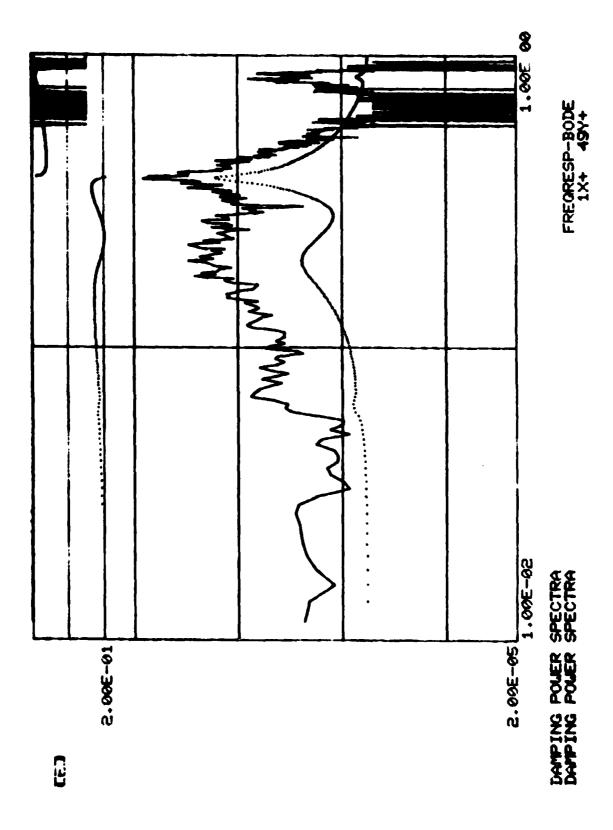
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PHASE 0.3767 -0.7963 0.1374 -0.2193E-01 2.433 -1.870 0.5502	-0.4058
117UD 1186E 1486E 1486E 1486 1486 1486 2816	13.3678E-06
0.9482E-01 0.7039E-01 0.1631E-01 0.9656E-01 0.9585E-01 0.9422E-01 0.9422E-01 0.1311E-02 0.1081E-01	30000
MATED ROOTS (1X+ FREQUENCY 0.7486E-01 0.7486E-01 0.3349 0.3326 0.4939 0.8239 0.8660	
mer Tronnamar-aud E	



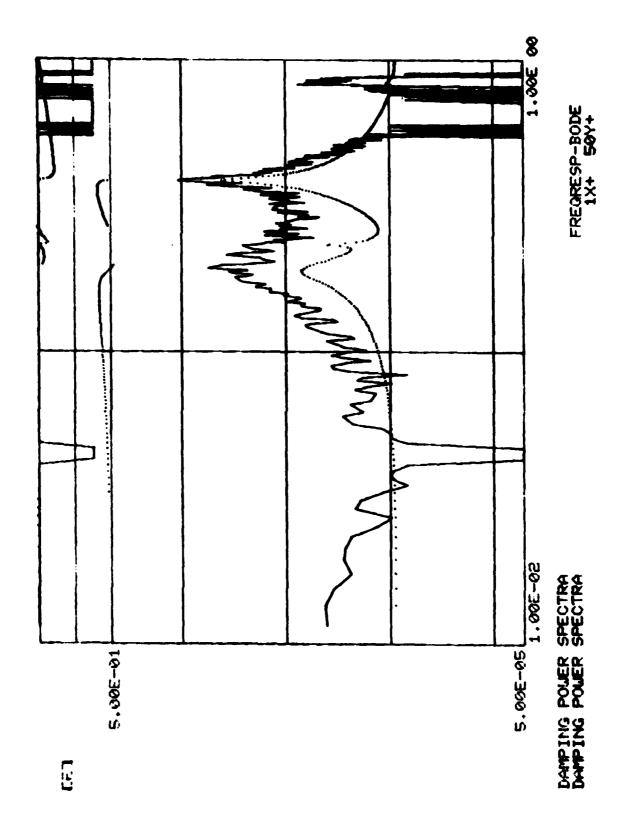
BLOUGH

	PHASE	Ø.8395	0.4115	-1.829	-2.487	-0.1580E-01	-1.107	0.3023	-1.962	-0.7943E-01	-0.3983E-04	-1.614
	AMPLITUDE	e.4959E-06	0.4948E-04	0.5004E-04	0.3870E-06	0.9163E-04	0.3840E-05	0.1640E-12	0.1393E-06	0.1523E-05	0.8555E-06	0.3036E-11
*+ 402+)		0.8414E-01	0.1851	0.5503	0.7938E-01	0.2020E-01	0.6462E-01	0.2621	0.1717E-01	0.1705E-01	0.1520	0.1161
TED ROOTS (1X+	REQUENCY.	0.6318E-01	6.200 3	0.2815	0.3001	0.3802	0.4417	7 0.6757	P.8382	0.8476	1.012	1.007
			'n	œ	4	£)	ဖ	t-	တ	O	10	11



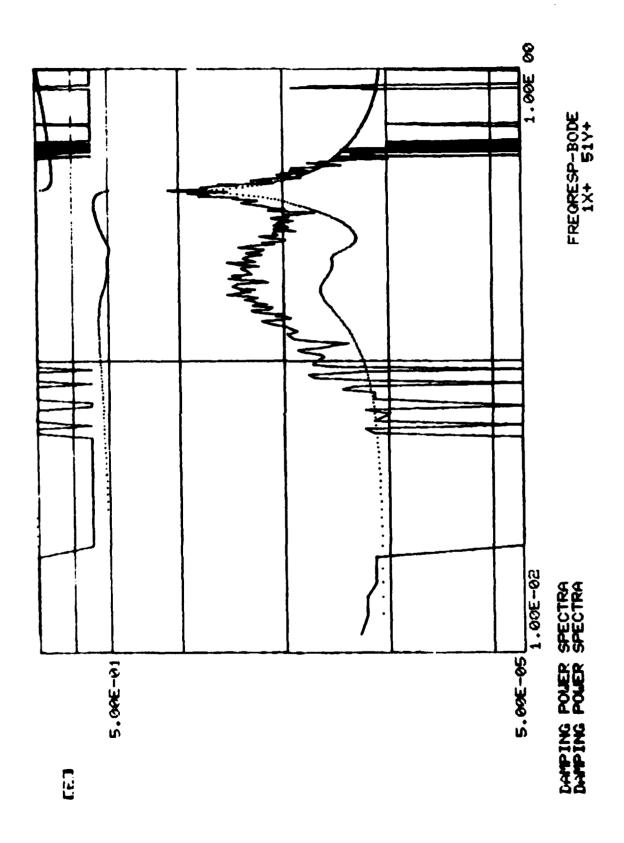
F-49-B

	PHASE	-3.110	0.1116E-03	0.1634	-0.4235	-0.5653	-0.3809E-01	-2.693	-1.787	-0.3120	0.2495	P078 0-
	AMPLITUDE	0.6172E-09	0.4197E-06	0.5721E-04	0.3931E-05	0.1794E-09	0.1531E-03	9.3024E-07	0.1207E-05	0.5075E-08	0.9023E-06	0.2841F-06
・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・	DAMPING	1.000	1.000	0.6598E-01	0.9130E-02	ø.3266	0.1284E-01	0.5342E-01	0.1020	0.1838E-01	0.1134E-01	0.1024E-01
	POST FREQUENCY	@.5566E-01	3.1799E-01	9·1899	0.2334	0.3954	0.3866	0.4960	Ø.5048	0.7721	0.8324	0.8673
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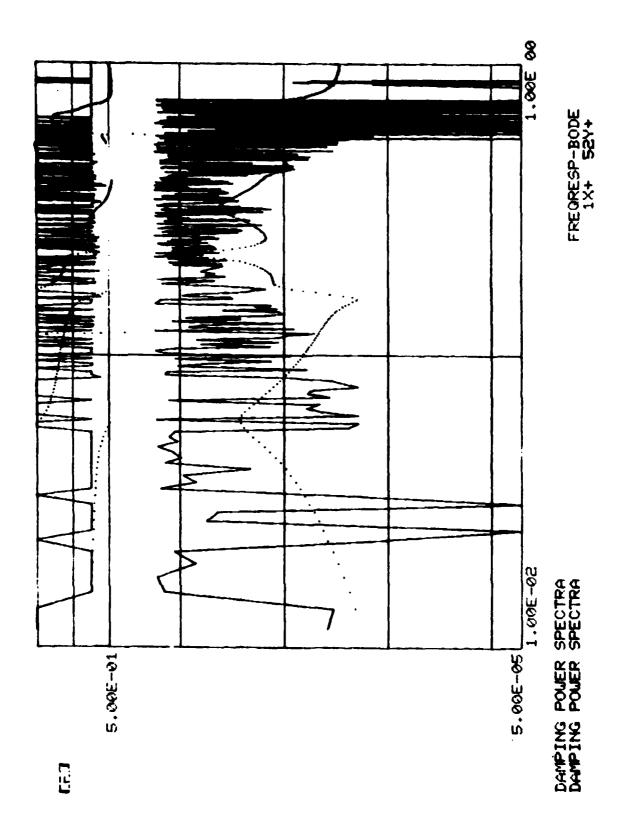
F-50-B

	PHASE	-0.1437F-04	100	400K - 0-	3600	2000 2000 2000 2000	0 2344		1.83.6	0.9956	0.1861E-01	-0.2704F-03	3.141	מינים מינים
	AMPLITUDE	0.57345-05	0.61215-04	0.1373E-04	0.2866F-04	0.0400F103	0.1652F-07	0 200 to 100 to	0 0040F100	0.15548F-0-	0.4 /0XE-05	0.1489E-06	0.4604F-06	0.0010F-12
517+)	DAILG	1.000	0.1629	0.6929E-01	0.1409	0.1708E-01	0.1237	0.3762F-01	0.4584F-01	0 138351.00	0.1200E-0E	0.5312E-01	0.1413	0.8744E-01
ESTIMATED ROOTS (1X+	ACNIE O BOLL	0.9326E-01	0.1769	ଜ.୧3୭ର	O.3440	Ø. 3828	Ø.3964	0.4444	0.6216	0.8667	.00	1.000	1.010	1.004
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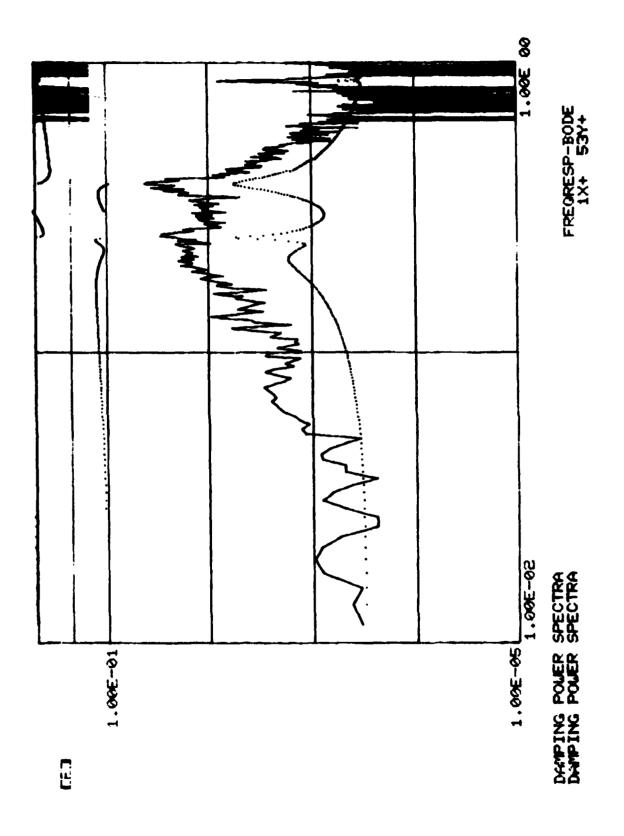
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PHASE	-0.1165	-0.7743E-01	2.570	1.067	-2.519	-1.678	-0.6666	-2.346	0.9621	0.9221
AMPLITUDE		0.9702E-04	0.2201E-03		.6107E	.2142E	. 2889E	.4818E	0.3702E-03	0.5664E-06
+ 527+) DAMPING	Ø.1493	5164 E	1026E	7787E	3834E	6034 E	2111E	1665E	0.2159E-01	1790E
X										
MATED ROOTS (0.6023E-01		P. 2211	0.3187	0.4273	0.5454	0.5697	Ø.6737	0.7206	0.8531
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	PHASE	-3.142	0.1279	0.1032	0.3926	-0.1505		2.794	0.3943	0.9894	•	-0.8260E-05
	AMPLITUDE	ଡ.ଅଟଡମଣ-ଡଟ	0.4399E-08	0.2362E-04	0.9168E-05	0.4645E-04	0.9111E-06	0.2016E-06	0.1643E-07	•	0.4683E-06	0.6514E-07
1X+ 034+)	DNIGHTO	1.000		11	0.9824E-02	0.3035E-01	0.1362E-01	0.1021E-01	0.8148E-02	0.3484E-01	0.3175E-02	0.1010E-01
R00TS (NEW CONTRACT	ତ.1280	A.1333	ø.2159	6.2496	0.3317	0.4237	0.4639	0.5938	0.7843	0.8660	1.000
ESTIMATED		••	រដ	(*)	4	វេរ	(<u>ū</u>	t-	Ø	(O)	10	11



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	PHRSE -1.344 -1.891 0.6008 -2.886 -0.1571 1.143 0.5421 -0.1218 -0.5700E-01	- 4 4 4 4
	AMPLITUDE 0.3535E-06 0.3535E-06 0.1061E-05 0.1022E-04 0.1524E-04 0.1579E-07 0.1579E-11 0.2789E-06	
***************************************	+ 547+) DHMPING 0.2476 0.5762E-02 0.1317 0.6539E-01 0.2480E-01 0.3374E-02 0.1689 0.4452E-01	
	FED ROOTS (1X+ FREGUENCY 9.9230E-01 9.1930 0.3337 0.3337 0.3337 0.4645 0.6288 0.6708 0.8677 1.001	
	ក្រុក្សា ស្រុក ស ស ស្រុក ស្រុក ស្រុក ស្រុក ស្រុក ស្រុក ស្រុក ស្រុក ស្រុក ស ស្រុ ស្រុក ស្រុក ស្រុក ស្រុក ស្រុក ស្រុក ស ស្រុក ស្រុក ស្រុក ស ស ស្រុក ស្រុក ស្រុក ស្រុក ស្រុក ស្រុក ស ស ស ស ស ស ស ស ស ស ស ស ស ស ស ស ស ស ស	

